Multiple-view diffuse optical tomography system based on time-domain compressive measurements

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Compressive sensing is a powerful tool to efficiently acquire and reconstruct an image even in Diffuse Optical Tomography (DOT) applications. In this work a time-resolved DOT system based on structured light illumination, compressive detection and multiple views acquisition has been proposed and experimentally validated on a biological tissue-mimicking phantom. The experimental scheme is based on two Digital Micromirror Devices (DMD) for illumination and detection modulation, in combination with a time-resolved single element detector. We fully validated the method and demonstrated both imaging and tomographic capability of the system, providing a state of the art reconstruction quality. © 2017 Optical Society of America

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In the last decade the possibility to quantitatively reconstruct absorbing, scattering and fluorescent inclusions within in vivo organisms has attracted a great interest for diagnostic purposes (e.g. tumor detection)[1], functional studies (e.g. brain oximetry)[2] and molecular imaging on small animals (e.g. pharmacological research)[3]. The general measurement scheme consists of illuminating the sample and detecting the diffused light exiting from it. Then, by solving the inverse problem, based on a model of photon propagation through the biological tissue, the optical parameters in each point of the sample can be quantitatively reconstructed. It is usually referred to these modalities as Diffuse Optical Tomography (DOT) and Fluorescence Molecular Tomography (FMT) when the absorption/scattering or fluorescence properties are reconstructed, respectively. DOT/FMT performance is mainly characterized by its capability to resolve the position and shape of inhomogeneities inside the tissue, and, consequently, improving the quantification capability of their optical parameters. Previous studies have demonstrated the importance of a dense source/detector [4] and multiple views measurement scheme [5, 6] in order to increase the tomographic spatial resolution. Moreover, further data, such as spectral and temporal information, are crucial [7, 8]. Temporal information provides three main advantages: i) better disentanglement of absorption/scattering properties; ii) temporal encoding of photons depth; iii) fluorescence lifetime quantification in the case of FMT. Spectral information (i.e. different excitation/detection wavelength) allows one to discriminate among tissue chromophores. Hence, DOT/FMT turns out to be a highly multidimensional problem with the drawback to generate a huge data set. This represents a practical limitation of these techniques because of the extremely long acquisition and computational times, which are not typically compatible with clinical and pre-clinical needs. Hence, a reduction of the acquired data set by preserving the spatial resolution, or more generally the data set information content, is highly desirable.

Following this concept, different studies have recently exploited the fact that a highly scattering medium (such as biological tissue) behaves as a low pass filter in the spatial domain. Hence, few illumination patterns, instead of the more typical raster scanning approach, can be adopted without losing significant spatial information [8–10]. This in turn leads to a reduction of the data set dimension and, consequently, of the acquisition and computational time. Recent studies have exploited such approach both in imaging and tomographic schemes and detection is generally carried out by a parallel detector such as CCD, CMOS or gated cameras [11]. Moreover, the use of a wide field approach (such as the case of structured illumination) allows one to illuminate the sample with high power without exceeding safety limits. This improves the signal-to-noise ratio.

Recently a patterned detection [12], following the single-pixel camera scheme [13], has been proposed for FMT applications, as well as for PhotoAcoustics [14]. Basically, the image of the diffused light exiting the sample is spatially modulated and subsequently focused on a single element detector. This operation is equivalent to projecting the image on an element of a base set, such as Fourier, Wavelets, or Hadamard patterns. By repeated acquisitions for different base elements it is possible to recover the same image as would be measured in a conventional pixel...
basis. Due to the fact that a highly scattering medium acts as a low-pass filter in the spatial frequency domain, just few frequencies are needed. This approach has the great advantage of exploiting the superior characteristics of a single detector (e.g. higher temporal resolution and larger spectral bandwidth) and lower cost with respect to a parallel device. Moreover, comparing with raster scanning, a further advantage is the acquisition speed given by a wide field detection analogous to structured illumination approach. Finally, it is worth mentioning that both structured illumination and detection open the possibility to get images and reconstructions with increasing spatial details by increasing the number of measurements.

Whereas the patterned detection approach has been successfully demonstrated for fluorescence optical tomography in a single view [12], a fully tomographic modality requires multiple views to reduce the ill-posedness in depth resolution, which leads to a more challenging experimental arrangement. In this work we propose a multiple-view time-domain compressed sensing DOT system exploiting Hadamard patterns both in the illumination and collection plane, and applicable to non-planar geometries. The system has been experimentally validated on tissue phantoms with absorbing inclusions, demonstrating both imaging and tomographic capabilities.

The experimental set-up is schematically sketched in Fig. 1. The sample is illuminated by a pulsed structured light while detection is carried out either by a time-resolved Single Pixel Camera (SPC) or a Continuous Wave (CW) parallel detector. The sample is placed on a rotational stage to allow different view acquisition. By means of an acousto-optic tunable filter, light pulses at 650 nm are spectrally selected from a ps pulsed supercontinuum (rep. rate of 80 MHz) laser source (SuperK Extreme, NKT). Structured illumination is carried out by a Digital Micromirror Device (DMD Discovery kit 1100, Vialux), which spatially modulates the light, and an objective lens (f=50 cm) to create the image over an area of 3x3 cm² of the sample. The diffused light, exiting the sample over an area of about 2x2 cm², is imaged by a lens (f=60 cm) on a second DMD (DMD Discovery 4100, Vialux). A flip mirror allows us to image the DMD plane either on a low noise 16-bit cooled CCD camera (Versarray 512, Princeton Instruments) or a single element detector. The latter consists of a long working-distance objective (10X/0.25) which focuses the light reflected by the second DMD on a 1 mm diameter optical fiber. The light exiting the fiber is finally detected by a photomultiplier (PMT) (HPM-100-50, Becker & Hickl) connected to a Time-Correlated Single Photon Counting (TC-SPC) board that samples the temporal profile of the diffuse light. The system is fully computer controlled by a home-made LabView software enabling an automated acquisition of the whole data set (illumination/detection patterns, sample rotation and acquisition). The sample is a homogeneous cylindrical tissue mimicking phantom (Ø=20 mm, height 50 mm) made of epoxy resin, TiO₂ (as scatterer) and toner (as absorber). By means of a time-resolved spectroscopy system [15] the optical parameters were measured: absorption coefficient (µₐ) about 0.01 mm⁻¹ and reduced scattering coefficient (µ's) about 1 mm⁻¹. Two holes (see Fig. 4), drilled into the sample (Ø=1.6 mm), allowed us to insert either solid or liquid absorbing inclusions. In particular, to better simulate a realistic perturbation, 3 solutions of calibrated ink and Intralipid have been prepared [16], giving µ'ᵢ ~ 1 mm⁻¹ (the same as that of the background) and µₐ of: 0.05/0.05 mm⁻¹ (Exp 1), 0.05/0.1 mm⁻¹ (Exp 2) and 0.05/0.03 mm⁻¹ (Exp 3) for inclusions A and B, respectively.

Initially, images have been acquired by means of the CCD camera on the detection side and of a low-cost camera on the illumination side, to register the illumination/detection area over the sample. Then 360 shadows of the object (every 1°) have been acquired to create the mesh [6]. It is worth emphasizing that precise calibration is critical to achieving an accurate simulation of the forward problem, which in turn is a prerequisite to obtain a high quality tomographic reconstruction.

Measurements have been performed on the phantom while and without the absorbing inclusions. The acquisition procedure is carried out by a complete 360° rotation of the sample with steps of 45° (8 views). For each view 8x8 ordered Walsh-Hadamard (WH) patterns, covering a 1.3x1.3 cm² area on the sample, have been used for both illumination and detection. Each WH pattern consists of two states (-1 to +1). Hence two positive patterns (ranging from 0 to +1), complementary to one another, have been acquired and properly subtracted to obtain the desired WH pattern. Acquisition time for each pattern is 1 s with 800KHz as maximum count-rate to fulfill the single-photon statistics. This last parameter is, indeed, the limiting factor on the overall acquisition time that is about 25 minutes. A full-pixel image can be recovered by applying the fast Walsh-Hadamard transform to the detected data [17].

For the reconstruction of the absorption map in the volume, the following objective function has been constructed:

\[ \Psi(x) = \frac{1}{2} \sum_n \left[ \frac{y_n - f_n(x)}{f_{0n}(x)} \right]^2 + \tau R(x) \]  

(1)

where \( x \) is the absorption coefficient in every mesh element, \( y_n \) is the measurement performed with the SPC, \( f_n \) and \( f_{0n} \) are the forward model, heterogeneous and homogeneous, respectively, \( \tau \) is the hyper-parameter, \( R \) is a regularization functional and \( n \) is the measurement index. The software TOAST, a finite-element based solver [18], has been used to calculate \( f_n(x) \). In order to minimize the objective function in Eq. (1) a damped Gauss-Newton method based on a one dimensional line-search algorithm [19] has been implemented. A Total Variation (TV) regularization functional has been used. In the calculation of both the forward model and the Jacobian, the IRF has been taken into account by convolution in time.

First measurements have been carried out using black solid rods as inclusions, to demonstrate the imaging capability of the
system and to estimate the number of patterns to be used in the tomographic reconstruction. In particular time-resolved data acquired by SPC have been integrated over time to obtain CW data and compared with the CCD images. An example of the images acquired by the CCD and the ones based on SPC (by spatially modulating the detection) is shown in Fig. 2. We observe a good agreement between the two images which improves by increasing the number of adopted patterns as reported in Fig. 2, where the Root Mean Square Error (RMSE) is reported as a function of the WH pattern order. In particular, we do not observe a significant improvement for WH pattern order higher than 8. Moreover, it is possible to observe that the RMSE plot for the inhomogeneous phantom presents a higher variability among the different views with respect to the homogeneous case. It is worth stressing that the number of required patterns strongly depends on the optical parameters/shape of the sample and position/dimension of the inclusions. In order to explore the imaging capability of the proposed method, the relative contrast, calculated as difference between heterogeneous and homogeneous images divided by the homogeneous one, provided by one solid inclusion, both in the CCD and SPC images, are reported, for 8 different views, in Fig. 3. In particular three cases are reported: i) the sample is illuminated with 16x16 ordered WH patterns while detection side has a uniform square pattern (Fig. 3, first row); ii) the sample is illuminated with a uniform square pattern while detection side is spatially modulated by 16x16 ordered WH patterns (Fig. 3, second row); iii) CCD images by using uniform square illumination pattern are also reported (Fig. 3, third row). Cases ii) and iii) show good agreement, in particular the presence of the absorbing inclusion can be clearly observed when it is located, during sample rotation, closer to the detector (see the vertical blue bar in the image at 0° or 45° for OUT). On the contrary, for the other views, the inclusion cannot be observed because of the scattering. In case i) there is no correspondence between the images acquired by the CCD and SPC. In particular we observe that, by modulating the illumination, we can better observe the inclusion for the views where it is closer to the illumination source (see the vertical blue bar in the image at 180° or 225° for IN). In fact, the SPC approach measures the integral of the signal, then the imaging capability is not influenced by the scattering events followed by photons after impinging on the inclusion as occurs for the CCD [20]. These examples demonstrate the imaging capability of the proposed method and in particular the importance of the choice of the illumination/detection patterns according to the view, the sample (shape and optical parameters) and inclusions, for both imaging and reconstruction.

As a first demonstration of the tomographic capability of the proposed system, three tomographic reconstructions by using an early gate of the time-resolved profile have been carried out. For each view, a single constant illumination pattern was used and the detection was performed with 8x8 WH patterns while the temporal gate has been chosen corresponding to the rising edge of the TR signal, here resulting in a time window of 500 ps length. The homogeneous measurements have been used to scale the inhomogeneous phantom data to match the magnitude of the forward TPSFs. The mesh used for the forward problem has 120000 elements and 1016 temporal point spread functions (TPSF) have been generated (127 WH patterns for 8 views) and sampled in 156 temporal steps of 8 ps length. The computational time for the forward problem is about 10 s on a machine with 10 2.3 GHz Dual Intel Xeon processors, an Nvidia Tesla K-40 GPU and 64 Gb RAM memory. Firstly, the eight TR measurements of the homogeneous phantom with planar illumination have been acquired (127 WH patterns for 8 views) and sampled in 156 temporal steps of 8 ps length. The computational time for the forward problem is about 10 s on a machine with 10 2.3 GHz Dual Intel Xeon processors, an Nvidia Tesla K-40 GPU and 64 Gb RAM memory. Firstly, the eight TR measurements of the homogeneous phantom with planar illumination have been acquired (127 WH patterns for 8 views) and sampled in 156 temporal steps of 8 ps length. The computational time for the forward problem is about 10 s on a machine with 10 2.3 GHz Dual Intel Xeon processors, an Nvidia Tesla K-40 GPU and 64 Gb RAM memory. Firstly, the eight TR measurements of the homogeneous phantom with planar illumination have been acquired (127 WH patterns for 8 views) and sampled in 156 temporal steps of 8 ps length. The computational time for the forward problem is about 10 s on a machine with 10 2.3 GHz Dual Intel Xeon processors, an Nvidia Tesla K-40 GPU and 64 Gb RAM memory. Firstly, the eight TR measurements of the homogeneous phantom with planar illumination have been acquired (127 WH patterns for 8 views) and sampled in 156 temporal steps of 8 ps length. The computational time for the forward problem is about 10 s on a machine with 10 2.3 GHz Dual Intel Xeon processors, an Nvidia Tesla K-40 GPU and 64 Gb RAM memory.

Fig. 4(a-c) shows the tomographic reconstructions of $\mu_4$ at different vertical slices. Due to the limited field-of-view of both illumination and detection, only a part of the cylinder can be reconstructed (about 16 mm centered at about 14 mm from the top). We observe a good reconstruction quality pertaining both the localization and relative contrast of the two inclusions. By fitting the reconstructed inclusions with a 3D gaussian function, we obtained a total contrast of about 0.3 times the truth for all
esigns. Moreover in Fig. 4 (b-d-f) normalized line profiles across the inclusions at the plane \( z=13 \) mm are reported for all the experiments. We observe a worsening of the localization for the inclusion B of Exp 3 probably due to the reduced contrast produced by the low absorbing solution poured in it. Finally, in order to quantify the localization capability of the reconstruction, the center of mass (COM) for each inclusion has been computed on a region twice larger than the inclusions (See Table 1).

In conclusion, a fully tomographic time-resolved DOT system based on the sampling in the spatial frequency domain (both illumination/detection space) and multiple views acquisition has been proposed and validated on tissue-mimicking phantom, demonstrating a state of the art reconstruction quality. Moreover, the imaging capability of the system has been validated in CW by comparing SPC with a standard CCD acquisition, showing the importance of the choice of illumination/detection in CW by comparing SPC with a standard CCD acquisition, demonstrating a state of the art reconstruction quality. More-
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