



Low-Reynolds-number flow past a cylinder with uniform blowing or sucking

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We analyse the low-Reynolds-number flow generated by a cylinder (of radius a) in a stream (of velocity U_∞) which has a uniform through-surface blowing component (of velocity U_b). The flow is characterized in terms of the Reynolds number Re ($=2aU_\infty/\nu$, where ν is the kinematic viscosity of the fluid) and the dimensionless blow velocity Λ ($=U_b/U_\infty$). We seek the leading-order symmetric solution of the vorticity field which satisfies the near- and far-field boundary conditions. The drag coefficient is then determined from the vorticity field. For the no-blow case Lamb's (*Phil. Mag.*, vol. 21, 1911, pp. 112–121) expression is retrieved for $Re \rightarrow 0$. For the strong-sucking case, the asymptotic limit, $C_D \sim -2\pi\Lambda$, is confirmed. For blowing, the limit of validity is $\beta < 1$ or $\Lambda < 4/Re$, after which the flow is unsymmetrical about $\theta = \pi/2$. The analytical results are compared with full numerical solutions for the drag coefficient C_D and the fraction of drag due to viscous stresses. The predictions show good agreement for $Re = 0.1$ and $\Lambda = -5, 0, 5$.

Key words: low-Reynolds-number flows, Stokesian dynamics

1. Introduction

The modification of the flow past a body due to a uniform blowing or sucking component is of fundamental importance in many areas of engineering. A through-surface flux is introduced to cool turbine blades or modify the force acting on lifting surfaces or can be generated by a phase change (e.g. evaporation).

Dukowicz (1982) derived a closed-form expression for the drag force acting on a blowing/sucking sphere at low Reynolds numbers which retrieves Stokes' (1851) solution for $\Lambda = 0$. For strongly sucking flows, the flow is irrotational in the far field and the drag force reduces to what is expected by a global momentum analysis. At a Reynolds number of $Re = 1$, the difference between the full numerical results and Dukowicz's solution is approximately 10% in the drag coefficient for blowing flows (Cliffe & Lever 1985).

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For the case of a cylinder, the complexity of the analysis is increased by the requirement of a far-field or Oseen correction (see the discussion by Stokes (1851)). The study of the force on a cylinder at low Re has been developed over the last 100 years, and it is worth pointing out some of the historical elements, as they provide a guide to the different ways in which we could treat the problem in this paper. Later editions of Lamb's book 'Hydrodynamics' include a discussion of the flow past a cylinder at low Re (Lamb 1932, p. 614, 1911). The technique Lamb employed attracted criticism in the 1960s because it was not a rigorous asymptotic analysis. The construction technique that Lamb employed is reasonably accurate, giving predictions for the drag coefficient up to $Re = 1$ that are within 5% of the full solution. Lamb's (1911) technique follows that of Oseen, introducing a correction (advective) term to account for the far-field flow, but it is simpler as it makes use of a transformational split that is not extendable to the problem in this paper. While a matched asymptotic solution is mathematically rigorous and can account for the full inertia term, the series expansion method by Dennis & Shimshoni (1965) is just as powerful and accurate, though far less elegant mathematically.

The purpose of this paper is to examine the low-Reynolds-number flow past a cylinder which has a through-surface component and to develop an understanding of the influence of Re and Λ on the drag force. The leading-order solution is calculated using a construction technique, which has the advantage of being simple. The fidelity of this approach is tested with comparisons against full numerical solutions. The mathematical model is described in §2. Approximate solutions are developed in the limit of $\Lambda = 0$ and strongly sucking flows and described in §3. A comparison between predictions and numerical solutions is shown in §4.

2. Mathematical model

We consider a cylinder of radius a fixed at the origin and set in a uniform flow. To account for the far field at low Reynolds numbers, the Oseen approximation is applied which uses a linear approximation for the inertia term so that $\mathbf{u} \cdot \nabla \mathbf{u} \approx U_\infty \partial \mathbf{u} / \partial x$. We are interested in examining the flow past a cylinder with a through-surface flow so that the radial blow component is included, and therefore seek to determine the leading-order solution to

$$\rho \left(U_\infty \frac{\partial \mathbf{u}}{\partial x} + \frac{U_b a}{r} \frac{\partial \mathbf{u}}{\partial r} \right) = -\nabla p + \mu \nabla^2 \mathbf{u}, \quad (2.1)$$

where μ is the dynamic viscosity, ρ is the density, U_b is the blow velocity and U_∞ is the far-field velocity. The boundary conditions imposed on the flow are

$$(u_r, u_\theta) = (U_b, 0) \quad (2.2)$$

at the surface of the cylinder (at $r = a$) and

$$(u_r, u_\theta) \rightarrow (U_\infty \cos \theta, -U_\infty \sin \theta) \quad (2.3)$$

in the far field (as $r \rightarrow \infty$).

2.1. Defining equations

A **vorticity–stream function** (ω – ψ) method of solution is employed (see Batchelor 1967, appendix 2), where the velocity and vorticity fields are defined by

$$u_r = \frac{\partial \psi}{\partial \theta}, \quad u_\theta = -\frac{1}{r} \frac{\partial \psi}{\partial r}, \quad \omega = -\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial \psi}{\partial r} \right) - \frac{1}{r^2} \frac{\partial^2 \psi}{\partial \theta^2}. \quad (2.4a-c)$$

The boundary conditions (2.2) impose significant constraints on the velocity near the boundary, mainly because $\partial u_\theta / \partial \theta = \partial u_r / \partial \theta = 0$. This means that

$$\omega = \frac{\partial u_\theta}{\partial r} \Big|_{r=a} \quad (2.5)$$

and

$$\frac{\partial u_r}{\partial r} \Big|_{r=a} = -\frac{U_b}{a} \quad (2.6)$$

(where mass conservation was used in (2.6)). From (2.1), the vorticity equation is

$$U_\infty \frac{\partial \omega}{\partial x} + \frac{U_b a}{r} \frac{\partial \omega}{\partial r} = \nu \nabla^2 \omega. \quad (2.7)$$

Our starting point is quite similar to **that of Lamb** (1932) and involves expressing the vorticity field $\tilde{\omega}$ ($= 2a\omega/U_\infty$) as

$$\tilde{\omega} = e^{(Re/4)\tilde{r} \cos \theta} P, \quad (2.8)$$

giving

$$\frac{Re^2}{8} \Lambda \frac{1}{\tilde{r}} \cos \theta P + \frac{Re}{2} \frac{\Lambda}{\tilde{r}} \frac{\partial P}{\partial \tilde{r}} + \left(\frac{Re}{4} \right)^2 P = \tilde{\nabla}^2 P, \quad (2.9)$$

where $Re = 2aU_\infty/\nu$ and $\tilde{r} = r/a$. Following Dukowicz (1982), we seek the **leading-order symmetric solution**, which is of the form

$$P = P_1(\tilde{r}) \sin \theta, \quad (2.10)$$

where P_1 satisfies

$$P_1'' + \frac{P_1'}{\tilde{r}} (1 - 2\beta) - \left(\left(\frac{Re}{4} \right)^2 + \frac{1}{\tilde{r}^2} \right) P_1 = 0, \quad (2.11)$$

where $\beta = Re \Lambda / 4$. This is valid **provided that** $Re^2 |\Lambda| \ll 1$ and for $\beta \rightarrow -\infty$ because the flow is symmetric about $\theta = \pi/2$, but not for $\beta \rightarrow \infty$. The solution that satisfies $P_1 \rightarrow 0$ as $\tilde{r} \rightarrow \infty$ is

$$P_1 = C_1 \tilde{r}^\beta K_{(1+\beta^2)^{1/2}}(Re \tilde{r}/4). \quad (2.12)$$

The stream function, ψ , can be constructed by writing it as the sum of the known blowing and **free-stream components**, together with a component to be determined. As such we write

$$\psi = U_\infty a (\Lambda \theta + \tilde{r} \sin \theta + f_1 \sin \theta). \quad (2.13)$$

94 Substitution of (2.13) into (2.4) gives

$$95 \quad f_1'' + \frac{f_1'}{r} - \frac{f_1}{r^2} = -\frac{1}{\pi} \int_0^\pi \sin \theta \tilde{\omega} \, d\theta = -\frac{1}{2\pi} P_1(\tilde{r}) \int_0^{2\pi} e^{(Re \tilde{r}/4) \cos \theta} \sin^2 \theta \, d\theta. \quad (2.14)$$

96 The boundary conditions for f_1 are

$$97 \quad f_1(1) = -1, \quad f_1'(1) = -1, \quad \lim_{\tilde{r} \rightarrow \infty} f_1(\tilde{r}) = 0. \quad (2.15a-c)$$

98 The right-hand side of (2.14) is defined as $C_1 p_1(\tilde{r})$, where

$$99 \quad p_1(\tilde{r}) = -\tilde{r}^\beta \frac{J_1(iRe \tilde{r}/4)}{iRe \tilde{r}/4} K_{(1+\beta^2)^{1/2}}(Re \tilde{r}/4). \quad (2.16)$$

100 We can solve (2.14) exactly by writing $f_1 = \tilde{r} g_1$, which transforms the ordinary
101 differential equation to

$$102 \quad \frac{d(\tilde{r}^3 g_1')}{d\tilde{r}} = C_1 p_1(\tilde{r}) \tilde{r}^2. \quad (2.17)$$

103 The boundary conditions on g_1 are $g_1(1) = -1$, $g_1'(1) = 0$ and $g_1 \rightarrow 0$ as $\tilde{r} \rightarrow \infty$.
104 Integrating twice, we find two results. The first is that

$$105 \quad f_1 = C_1 \tilde{r} \left(-\frac{1}{2\tilde{r}^2} G(1) - \int_\infty^{\tilde{r}} G(\tilde{r}) \tilde{r}^{-3} \, d\tilde{r} \right), \quad (2.18)$$

106 where

$$107 \quad G(\tilde{r}) = \int_{\tilde{r}}^\infty p_1(\tilde{r}) \tilde{r}^2 \, d\tilde{r}. \quad (2.19)$$

108 The second result (which ensures that the far-field boundary condition is satisfied) is

$$109 \quad C_1 = \frac{2}{\int_1^\infty p_1(\tilde{r}) \, d\tilde{r}}. \quad (2.20)$$

111 The integrand scales as $\tilde{r}^{\beta-2}$ in the far field (using $K_n(z) \sim \exp(-z)/z^{1/2}$ and $J_1(iz) \sim$
112 $\exp(z)/z^{1/2}$) and so the integral converges when $-\infty < \beta < 1$.

113 2.2. Diagnostics

114 The pressure and viscous drag coefficients for characterizing the force on a cylinder
115 are

$$116 \quad C_P = \int_0^{2\pi} \left(\frac{1}{Re} \frac{\partial \tilde{\omega}}{\partial \tilde{r}} - \frac{1}{2} \Lambda \tilde{\omega} \right) \sin \theta \, d\theta, \quad C_v = -\frac{1}{Re} \int_0^{2\pi} \tilde{\omega} \sin \theta \, d\theta, \quad (2.21a,b)$$

117 which is an extension of the relationship given by Dennis & Shimshoni (1965) to
118 include a through-surface flow. On substituting (2.10) into (2.21),

$$119 \quad \left. \begin{aligned} C_P &= -C_1 \frac{\pi}{Re} \left((\beta + (1 + \beta^2)^{1/2}) K_{(1+\beta^2)^{1/2}}(Re/4) + \frac{Re}{4} K_{(1+\beta^2)^{1/2}-1}(Re/4) \right), \\ C_v &= -C_1 \frac{\pi}{Re} K_{(1+\beta^2)^{1/2}}(Re/4). \end{aligned} \right\} \quad (2.22)$$

The ratio of the viscous drag to the total drag coefficient is

$$\frac{C_v}{C_D} = \frac{1}{\beta + (1 + \beta^2)^{1/2} + 1 + \frac{Re K_{(1+\beta^2)^{1/2}-1}(Re/4)}{4 K_{(1+\beta^2)^{1/2}}(Re/4)}}, \quad (2.23)$$

where $C_D = C_p + C_v$. Since Re is small, C_v/C_D is effectively a function of $Re \Lambda$. **It should be noted** that (2.23) does not depend on C_1 .

3. Approximate solutions

We present a **leading-order** solution to (2.14) which will then be used to understand two limits: (a) **the no-blow case** where the result reduces to Lamb's (1911) original solution and (b) strongly sucking flows.

3.1. No-blow case ($\Lambda = 0$)

The purpose here is to retrieve Lamb's solution for the no-blow case. When $\Lambda = 0$, p_1 can be expressed exactly as

$$p_1 = -K_1(Re \tilde{r}/4) \frac{J_1(iRe \tilde{r}/4)}{iRe \tilde{r}/4}. \quad (3.1)$$

Using the substitution $z = Re \tilde{r}/4$, the integral in (2.20) can be written as

$$\int_1^\infty p_1 d\tilde{r} = \frac{4}{Re} \int_{Re/4}^\infty K_1(z) \frac{J_1(iz)}{iz} dz = \frac{4}{Re} \int_{Re/4}^\infty K_1(z) \left(\frac{1}{2} + \sum_{n=1}^\infty \frac{z^{2n}}{2^{2n+1} n!(n+1)!} \right) dz, \quad (3.2)$$

such that

$$\int_1^\infty p_1 d\tilde{r} = \frac{2}{Re} \left(K_0(Re/4) + \sum_{n=1}^\infty \int_{Re/4}^\infty \frac{z^{2n} K_1(z)}{2^{2n} n!(n+1)!} dz \right). \quad (3.3)$$

In the limit of $Re \ll 1$, the lower limit is close to zero and it can be shown, using (A.4), that

$$\sum_{n=1}^\infty \int_0^\infty \frac{z^{2n} K_1(z)}{2^{2n} n!(n+1)!} dz = \frac{1}{2}, \quad (3.4)$$

such that

$$C_1 = \frac{Re}{\frac{1}{2} + K_0(Re/4)}. \quad (3.5)$$

The drag coefficient corresponding to (3.5) is

$$C_D = -\frac{2\pi}{\frac{1}{2} + K_0(Re/4)} \left(K_1(Re/4) + \frac{Re}{8} K_0(Re/4) \right) \cong -\frac{8\pi}{Re(\frac{1}{2} + K_0(Re/4))}, \quad (3.6)$$

where use was made of (A.2). Now, Lamb (1932, p. 616) derived the following expression for vorticity:

$$\omega = C e^{(\tilde{r}Re/4) \cos \theta} \frac{\partial}{\partial y} K_0(Re \tilde{r}/4) = -\frac{C Re}{a} \frac{e^{(\tilde{r}Re/4) \cos \theta}}{4} K_1(Re \tilde{r}/4) \sin \theta, \quad (3.7)$$

146 which is the same expression as that derived here from the vorticity equation. (It
 147 should be noted that there is a typographical error in Lamb’s vorticity expression,
 148 where e^{kz} should read e^{kx} ; the correct analysis is given in Lamb (1911) except for
 149 the typographical error of ‘sphere’ which should be ‘cylinder’ after equation (54).) A
 150 higher-order expansion of the stream function was determined,

$$151 \quad C = \frac{2U_\infty}{\frac{1}{2} + K_0(Re/4)}, \quad (3.8)$$

152 or equivalently

$$153 \quad C_D = -\frac{8\pi}{Re \left(\frac{1}{2} + K_0(Re/4) \right)}. \quad (3.9)$$

154 Therefore, the general expression for the drag coefficient agrees exactly with Lamb’s
 155 expression as $Re \rightarrow 0$ (the difference for $Re = 1$ is less than 1%).

156 3.2. Strongly sucking flow ($-\Lambda \gg 1$)

157 For strongly sucking flows where $|\beta| \gg 1$ and $\beta < 0$, we can write

$$158 \quad \frac{\int_1^\infty p_1 d\tilde{r}}{K_{(1+\beta^2)^{1/2}}(Re/4)} = -\frac{1}{2} \left(\frac{4}{Re} \right)^{\beta+1} \int_{Re/4}^\infty z^\beta \frac{K_{(1+\beta^2)^{1/2}}(z)}{K_{(1+\beta^2)^{1/2}}(Re/4)} dz \cong \frac{1}{2(\beta - (1 + \beta^2)^{1/2} + 1)}, \quad (3.10)$$

159 which can be substituted into (2.22), giving a drag coefficient of

$$160 \quad C_D \approx -\frac{4\pi}{Re} (\beta + (1 + \beta^2)^{1/2} + 1)(\beta - (1 + \beta^2)^{1/2} + 1). \quad (3.11)$$

161 This reduces to

$$162 \quad C_D \approx -2\pi\Lambda. \quad (3.12)$$

163 This approximation is appropriate when $|\beta| \geq 1$ or $\Lambda < -4/Re$ (so that the asymptotic
 164 approximation is valid). Equation (3.12) agrees with a global momentum analysis
 165 when the far-field downstream flow is irrotational, which was derived by Pankhurst
 166 & Thwaites (1953, appendix I) for high- Re flows. This is to be expected because in Q7
 167 both cases, the boundary layer is thin compared with the size of the cylinder.

168 4. Numerical results

169 4.1. Solution technique

170 The solution for $\tilde{\omega}$ contains an unknown, C_1 , which is determined from (2.20). The
 171 numerical solution to the Navier–Stokes equation was solved using a finite-element
 172 method that employs a characteristic-based split (CBS) methodology (see Zienkiewicz,
 173 Taylor & Nithiarasu 2005). The ACESim code has been validated for two-dimensional
 174 flows (e.g. Nicolle & Eames 2011; Klettner & Eames 2012). For low Re , White
 175 (1945) suggests a domain width of $2000a$ for the no-blow case to be unaffected by
 176 boundedness. As the influence of boundedness is increased for strong blowing/sucking,
 177 the domain width was increased to $20000a$ for the two cases of $|\Lambda| = 5$.

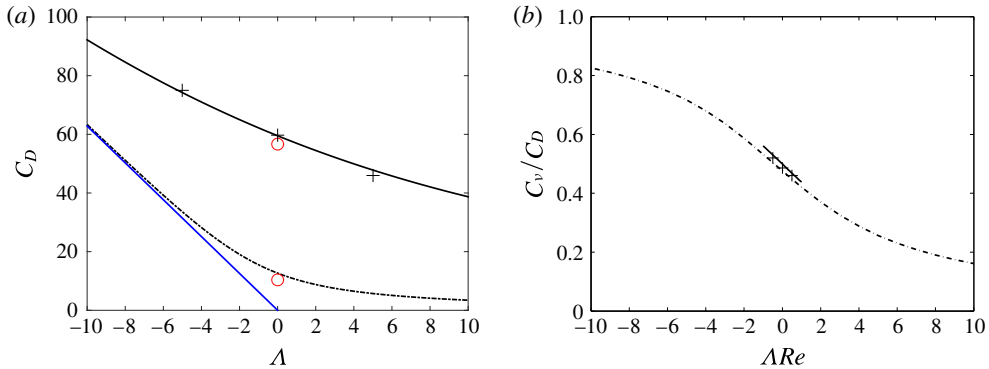


FIGURE 1. A comparison between the theoretical predictions and full numerical calculations of (a) C_D and (b) C_v/C_D as functions of Λ . In (a,b) the dot-dashed and full curves correspond to the predictions (2.22), (2.23) for $Re = 1, 0.1$ respectively and the full numerical simulations for $Re = 0.1$ are represented by crosses. The numerical results of Dennis & Shimshoni (1965) are plotted as red circles for the no-blow case. The blue line is the strongly sucking solution, $C_D = -2\pi\Lambda$, given in Pankhurst & Thwaites (1953, appendix I).

4.2. Results

Figure 1(a) shows the drag coefficient as a function of Λ for $Re = 0.1$. Good agreement is found between the analytical results and full numerical simulations. The asymptotic limit for strongly sucking flows ($C_D \sim -2\pi\Lambda$) is confirmed for $Re = 1$. Figure 1(b) shows the fraction of the total force due to viscous stresses for $Re = 0.1$. For small $|\Lambda|$ ($\ll 1$), the influence of blowing and sucking is symmetric on the drag force. For strongly sucking flows, the drag force increases linearly with $|\Lambda|$ because the viscous stresses near the wall scale as $\mu|\Lambda|U_\infty/a$. For strongly blowing flows, $C_D \rightarrow 0$ because the vorticity is blown off the surface of the cylinder. Therefore, the influence of the through-surface flow is asymmetric on the drag force at large Λ . For $\beta > 0$, the range of validity of the analysis was determined to be $\beta < 1$ or $\Lambda < 4/Re$ using a scaling analysis.

5. Conclusion

We identified the gap of low-Reynolds-number flow past a cylinder with a through-surface flow, and studied this problem using an analytical technique that identifies the leading-order component to the vorticity field. For the case of $\Lambda = 0$ and $Re \rightarrow 0$, we retrieve Lamb's (1911) result for the drag force. For strongly sucking flows, where the flow is irrotational outside the thin boundary layer, the asymptotic result $C_D = -2\pi\Lambda$ is recovered. The agreement between the analytical results and the full numerical solutions is good for $Re = 0.1$.

Appendix A. Useful relationships for K_n

We list the recurrent and asymptotic relationships that are used in this paper.

$$\frac{dK_n}{dz} = -K_{n-1}(z) - \frac{n}{z}K_n(z). \quad (\text{A } 1)$$

201 The expansion for K_1 is

$$202 \quad K_1(z) = \frac{1}{z} + \frac{z}{2} \log\left(\frac{z}{2}\right) + \dots . \quad (\text{A } 2)$$

203 When the argument $n \gg 1$,

$$204 \quad K_n(z) \cong \frac{\Gamma(n)}{2} \left(\frac{z}{2}\right)^{-n} . \quad (\text{A } 3)$$

205 Another useful formula is

$$206 \quad \int_0^\infty z^m K_n(z) dz = 2^{m-1} \Gamma\left(\frac{n+m+1}{2}\right) \Gamma\left(\frac{m+1-n}{2}\right) . \quad (\text{A } 4)$$

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