

# Dismounted Soldier Positioning in GNSS-Denied Environments Using Magnetic Fields

Peter J. Thompson<sup>1†</sup>, Paul D. Groves<sup>1</sup>, Rob J. Handley<sup>2</sup>, Owen J. Griffiths<sup>2</sup>, David R. Selviah<sup>1</sup>

- 1 University College London (UCL), United Kingdom
- 2 Defence Science and Technology Laboratory (Dstl), United Kingdom





#### Introduction

Situational awareness provided by robust and resilient positioning systems is mission-critical for many military applications and emergency services. Global Navigation Satellite Systems (GNSS) receivers are ubiquitous. However, GNSS signals can be denied, degraded or otherwise unavailable in many operational environments, necessitating one or more additional positioning navigation and timing (PNT) technologies to be available to the user. No single PNT technology, including GNSS, is sufficient in all operational environments<sup>[1]</sup>. Therefore, a multisensor integrated system using a system of subsystems is required<sup>[2]</sup>.

This PhD project focuses on dismounted soldier positioning based on subsystems derived from inertial and magnetic

Figure 1: Wooden Rig

measurement units (IMMU). Inertial navigation is well-researched for pedestrians; however, map matching derived positioning using magnetometers is under-researched, particularly the effect of different environments on performance. This magnetic-derived subsystem does not require new sensors but complements the commonly used IMMU system.

## **Building Type and Height of Sensor**

This project has investigated how the characteristics of magnetic fields, that could be used for magnetic map matching, vary across different types of buildings. Some of these environments differ significantly from the university buildings typically used by other researchers. These characteristics of magnetic flux density (MFD) measurements have been analysed across various environment types, where specific characteristics for each environment are identified.

This includes five indoor environments as defined by ISO/IEC 18305<sup>[3]</sup> and one outdoor location:

- Single-family House
- Concrete Office Building
- Warehouse/Factory



- Subterranean Structure
- Rural Outdoors





Figure 4: Contextual Building Models (a) and 360° Photos (b)

## MFD Source: AC Electrical Cable<sup>[4]</sup>

Unpredictable temporal variations in MFD could severely disrupt magnetic map matching. A significant source of these is electrical power cables; research on how underfloor cabling affect magnetometer measurements has been conducted. The variables examined include the magnetometer type, the alternating current (AC) electrical power transmitted through the cable, the cable type, and the distance from the cable.

This spatial database of measured MFD will become open access, providing contextual data for each environment, including 3D models and 360° photos.

Analysis of this database proves that MFD measurement characteristics vary by environment type. In the future, the knowledge of these characteristics can be used to tailor MFD positioning algorithms per environmental type, benefiting from these unique characteristics.



Figure 2: MFD (B<sub>v</sub><sup>b</sup>) in the Warehouse and the Office Environment

Depending on the environment, the measured MFD varies with height above ground, making the height of



Figure 5: Time Series on MFD with a Range of AC Power with an Unshielded Cable

A significant amount of building electrical power is alternating current (AC). Due to this, the AC-sourced magnetic fields can be separated using frequency-domain filtering, which requires high-bandwidth magnetometers. This filtering can improve the performance of a magnetic-derived positioning subsystem, improving the overall multisensor integrated positioning system. Therefore, it is recommended that dismounted soldiers use magnetometers with bandwidth high enough to isolate AC sources of MFD.

the sensor on the user critical. In some indoor environments, footlevel sensors show larger MFD variation across a horizontal grid than sensors placed higher on the body. Thus, it is recommended that the height placement of IMMUs on dismounted soldiers be tailored to the type of indoor environment.



Ground (m) in each Environment Type (µT)

#### References

- 1. Government Office for Science (UK). UK Blackett Review (GNSS) Update. 2018. Available from: https://www.gov.uk/government/publications/satellite-derived-time-and-position-blackett-review
- 2. Groves PD. Principles of GNSS, Inertial, and Multisensor Integrated Navigation Systems. 2nd ed. Boston, MA, USA; London, UK: Artech House; 2013. (GNSS technology and applications series).
- 3. ISO (2016) ISO/IEC 18305:2016. Geneva, Switzerland. Available at: https://www.iso.org/standard/62090.html.
- Thompson, Peter J; Groves, Paul D; Griffiths, Owen J; Handley, Robin J; Selviah, David R; (2024) Improving Magnetic Flux Density Fingerprint Map Matching by Mitigating AC-Induced Variability. In: European Navigation Conference 2024 (ENC2024). MDPI: Noordwijk, Netherlands.

<sup>+</sup> peter.thompson.20@ucl.ac.uk; profiles.ucl.ac.uk/81898-peter-thompson www.linkedin.com/in/peterthompsonmrics This research, conducted at University College London (UCL), is funded by the Engineering & Physical Sciences Research Council (EPSRC) and the Defence Science and Technology Laboratory (Dstl) as part of the ICASE scheme.





Engineering and Physical Sciences Research Council