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## Fast regression of the tritium breeding ratio in fusion reactors

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E-mail: [petr.maneck.19@ucl.ac.uk](mailto:petr.maneck.19@ucl.ac.uk) and [graham.vangoffrier.19@ucl.ac.uk](mailto:graham.vangoffrier.19@ucl.ac.uk)**Keywords:** nuclear fusion, surrogate model, tritium breeding, regression, fast approximation, adaptive sampling**Abstract**

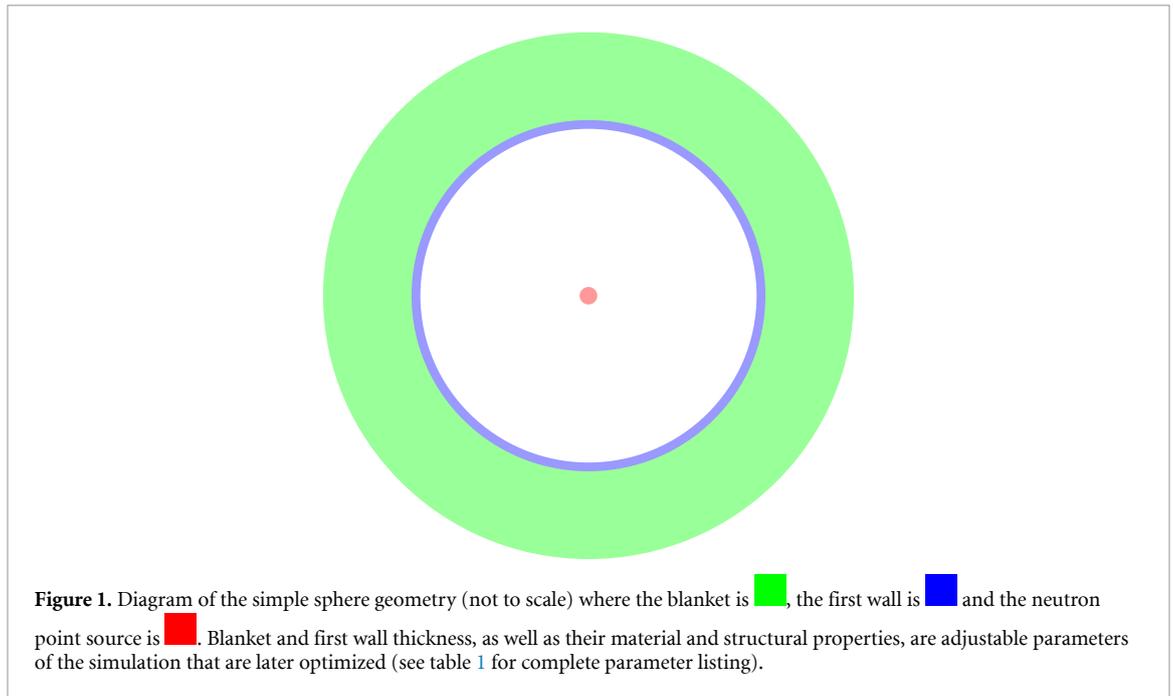
The tritium breeding ratio (TBR) is an essential quantity for the design of modern and next-generation D-T fueled nuclear fusion reactors. Representing the ratio between tritium fuel generated in breeding blankets and fuel consumed during reactor runtime, the TBR depends on reactor geometry and material properties in a complex manner. In this work, we explored the training of surrogate models to produce a cheap but high-quality approximation for a Monte Carlo (MC) TBR model in use at the UK Atomic Energy Authority. We investigated possibilities for dimensional reduction of its feature space, reviewed 9 families of surrogate models for potential applicability, and performed hyperparameter optimization. Here we present the performance and scaling properties of these models, the fastest of which, an artificial neural network, demonstrated  $R^2 = 0.985$  and a mean prediction time of  $0.898 \mu\text{s}$ , representing a relative speedup of  $8 \times 10^6$  with respect to the expensive MC model. We further present a novel adaptive sampling algorithm, Quality-Adaptive Surrogate Sampling, capable of interfacing with any of the individually studied surrogates. Our preliminary testing on a toy TBR theory has demonstrated the efficacy of this algorithm for accelerating the surrogate modelling process.

**1. Introduction**

Surrogate models were developed to resolve computational limitations in the analysis of massive datasets by replacing a resource-expensive procedure with a much cheaper approximation [1]. They are especially useful in applications where numerous evaluations of an expensive procedure are required over the same or similar domains, e.g. in the parameter optimization of a theoretical model. The term ‘metamodel’ proves especially meaningful in this case, when the surrogate model approximates a computational process which is itself a model for a (perhaps unknown) physical process [2]. There exists a spectrum between ‘physical’ surrogates which are constructed with some contextual knowledge in hand, and ‘empirical’ surrogates which are derived purely from samples of the underlying expensive model.

In this work, we develop a family of empirical surrogate models for the tritium breeding ratio (TBR) in an inertial confinement fusion (ICF) reactor. The expensive model that our surrogate model approximates is a Monte Carlo (MC) neutronics simulation, Paramak [3], which returns a prediction of the TBR for a given configuration of a spherical ICF reactor. Although more expensive 3D parametric models exist, we chose the Paramak simulation for its preferable speed in dataset generation in order to most fully demonstrate our methods. We quantify the success of several of our best-performing surrogate models by studying their accuracy and prediction time. We further propose an adaptive sampling algorithm (QASS) suitable for reducing the quantity of expensive samples needed to train our surrogate models.

Paramak facilitates simulation via an OpenMC neutronics workflow that is enclosed in a portable Docker container, which conveniently exposes an HTTP API using the Python 3 `f1ask` package. Within this setup,



we employ a Muir energy distribution [4]<sup>4</sup> around 14.06 MeV to approximate a deuterium-tritium (D-T) plasma neutron source. As illustrated in figure 1, the simulated reactor geometry was made adjustable in order to study its influence on the TBR. Nuclear data for simulation were extracted from the following sources, in order of preference: FENDL 3.1d [5]; JEFF 3.3 [6]; and ENDF/B-VII.1 [7]. To maintain a model-agnostic approach, variance reduction (VR) techniques were not used to accelerate the MC neutronics simulation [8]. It should be noted that depending on application, VR may constitute a viable alternative to the presented work.

For the remainder of section 1, we will define the TBR and further motivate our research. In section 2 we will present our methodologies for the comparison testing of a wide variety of surrogate modelling techniques, as well as defining an add-on adaptive sampling procedure QASS. After delivering the results of these approaches in section 3, we will give our final conclusions and recommendations in section 4.

### 1.1. Problem description

Nuclear fusion technology relies on the production and containment of an extremely hot and dense plasma containing enriched Hydrogen isotopes. The current frontier generation of fusion reactors, such as the Joint European Torus and the under-construction ITER, make use of both tritium and deuterium fuel. While at least one deuterium atom occurs for every 5000 molecules of naturally-sourced water, and may be easily distilled, tritium is extremely rare in nature. Tritium may be produced indirectly through irradiation of heavy water (D<sub>2</sub>O) during nuclear fission, but only at very low rates which could never sustain industrial-scale fusion power.

Modern D-T reactors rely on tritium breeding blankets, specialized layers of material which partially line the reactor and produce tritium upon neutron bombardment, e.g. by:



The TBR is defined as the ratio of tritium produced per source neutron, whose description in Paramak is facilitated by two classes of parameters (exhaustively listed in table 1). While the geometry of a given reactor is described by continuous parameters, material selections are specified by discrete categorical parameters. For all parameters, we have attempted to cover the full theoretical range of values even where those values are practically infeasible with current technology (e.g. packing fractions close to 1). Simulating broadly around

<sup>4</sup> A bug in the Muir distribution involving erroneous normal sampling was recently uncovered (see <https://github.com/openmc-dev/openmc/pull/1670>), but is disregarded in the present methods-focused work.

**Table 1.** Input parameters supplied to Paramak and surrogates in alphabetical order. Groups of fractions marked †‡ are independently required to sum to 1.

	Parameter name (abbreviation)	Domain
Blanket	Breeder fraction†	[0, 1]
	Breeder <sup>6</sup> Li enrichment fraction	[0, 1]
	Breeder material (BBM)	{Li <sub>2</sub> TiO <sub>3</sub> , Li <sub>4</sub> SiO <sub>4</sub> }
	Breeder packing fraction	[0, 1]
	Coolant fraction†	[0, 1]
	Coolant material (BCM)	{D <sub>2</sub> O, H <sub>2</sub> O, He}
	Multiplier fraction†	[0, 1]
	Multiplier material (BMM)	{Be, Be <sub>12</sub> Ti}
	Multiplier packing fraction	[0, 1]
	Structural fraction†	[0, 1]
	Structural material (BSM)	{SiC, eurofer}
	Thickness	[0, 500]cm
	First wall	Armour fraction‡
Coolant fraction‡		[0, 1]
Coolant material (FCM)		{D <sub>2</sub> O, H <sub>2</sub> O, He}
Structural fraction‡		[0, 1]
Structural material (FSM)		{SiC, eurofer}
Thickness		[0, 20]cm

typical values of parameters also improves the accuracy of the model nearer to typical values, and further aids in demonstrating the robustness of constructed models.

In our work, we set out to produce a fast TBR surrogate model, which takes the same input parameters as the MC model used in Paramak and approximates its output with the greatest achievable regression performance, while also minimizing the required quantity of expensive-model samples needed for training. This represents a significant step forward in computational fusion-reactor design, as speed-ups achieved in TBR evaluation can lead to a speed-up in numerical optimization of reactor parameters, although such optimization is beyond the scope of the present work.

## 2. Methodology

Labeling the expensive Paramak model  $f(x)$ , a surrogate model is a function  $\hat{f}(x)$  such that  $f(x)$  and  $\hat{f}(x)$  minimize a selected dissimilarity metric. In order to be considered *viable*,  $\hat{f}(x)$  is required to achieve an expected evaluation time lower than that of  $f(x)$ . In this work, we consider two methods of producing viable surrogates: (a) a conventional decoupled approach, which evaluates  $f(x)$  on a set of uniformly-random samples and trains surrogates in a supervised scheme, and (b) an adaptive approach, which attempts to compensate for localized regression performance insufficiencies by interleaving multiple epochs of sampling and training. Several high-accuracy and deployment-ready surrogate models are developed using the decoupled approach, and their performance characterized numerically, while the adaptive approach is studied exclusively as a proof-of-concept.

We selected several state-of-the-art regression algorithms to perform surrogate training on sampled point sets. Listed in table 2, these implementations define nine surrogate families which are detailed in section 3. We note that each presented algorithm defines hyperparameters that may influence its performance. Their problem-specific optimal values are searched within the scope of this work, in particular in Experiments 1 & 2 that are outlined in section 2.1.

To compare the quality of the produced surrogates, we define a variety of metrics listed in table 3. For regression performance analysis, we include a selection of absolute metrics (MAE,  $S$ ) to assess the models' approximation capability and to set practical bounds on the expected uncertainty of their predictions. In addition, we also track relative measures ( $R^2$ ,  $R_{adj}^2$ ) that are better-suited for comparison between this work and others, as they are invariant with respect to the selected domain and image space. For analysis of computational complexity, surrogates are assessed in terms of wall time (captured by the Python 3 `time` package). This is motivated by common practical use-cases of our work, where surrogate models are trained as replacements for Paramak. All times reported (training, test, evaluation) are normalized by the corresponding dataset size, i.e. correspond to 'time to process a single datapoint.'

Even though some surrogates support acceleration by means of parallelization, we used non-parallelized implementations. The only exception to this is the ANN family, which requires a considerable amount of processing power for training on conventional CPU architectures. Lastly, to prevent undesirable bias by

**Table 2.** Considered surrogate model families, their selected abbreviations and implementations.  $\mathcal{H}$  denotes the set of hyperparameters, family-dependent priors that control the learning process, and are tuned separately. Families with fewer hyperparameter represent a smaller surrogate domain to explore.

Surrogate family	Abbr.	Impl.	$ \mathcal{H} $
Support vector machines [9]	SVM	SciKit [10]	3
Gradient boosted trees [11–13]	GBT	SciKit	11
Extremely randomized trees [14]	ERT	SciKit	7
AdaBoosted decision trees <sup>a</sup> [15]	ABT	SciKit	3
Gaussian process regression [16]	GPR	SciKit	2
$k$ nearest neighbours	KNN	SciKit	3
Artificial neural networks	ANN	Keras [17]	2
Inverse distance weighing [18]	IDW	SMT [19]	1
Radial basis functions	RBF	SMT	3

<sup>a</sup> Note that ABTs can be viewed as a subclass of GBTs.

**Table 3.** Metrics recorded in experiments. In formulations, we work with a training set of size  $N_0$  and a test set of size  $N$ , values  $y^{(i)} = f(x^{(i)})$  and  $\hat{y}^{(i)} = \hat{f}(x^{(i)})$  denote images of the  $i$ th testing sample in Paramak and the surrogate respectively. The mean  $\bar{y} = N^{-1} \sum_{i=1}^N y^{(i)}$  and  $P$  is the number of input features.

Regression performance metrics	Notation	Mathematical formulation
Mean absolute error	MAE	$N^{-1} \sum_{i=1}^N  y^{(i)} - \hat{y}^{(i)} $
Standard deviation of error	S	$\text{StdDev}_{i=1}^N \left\{  y^{(i)} - \hat{y}^{(i)}  \right\}$
Coefficient of determination	$R^2$	$1 - \sum_{i=1}^N (y^{(i)} - \hat{y}^{(i)})^2 \left[ \sum_{i=1}^N (y^{(i)} - \bar{y})^2 \right]^{-1}$
Adjusted $R^2$	$R_{\text{adj}}^2$	$1 - (1 - R^2)(N - 1)(N - P - 1)^{-1}$
Computational complexity metrics		
Mean training time	$\bar{t}_{\text{trn.}}$	(wall training time of $\hat{f}(x)$ ) $N_0^{-1}$
Mean prediction time	$\bar{t}_{\text{pred.}}$	(wall prediction time of $\hat{f}(x)$ ) $N^{-1}$
Relative speedup	$\omega$	(wall evaluation <sup>a</sup> time of $f(x)$ ) $(N \bar{t}_{\text{pred.}})^{-1}$

<sup>a</sup> This corresponds to evaluation of Paramak on all points of the test set. In surrogates, the equivalent time period is referred to as the “prediction time.”

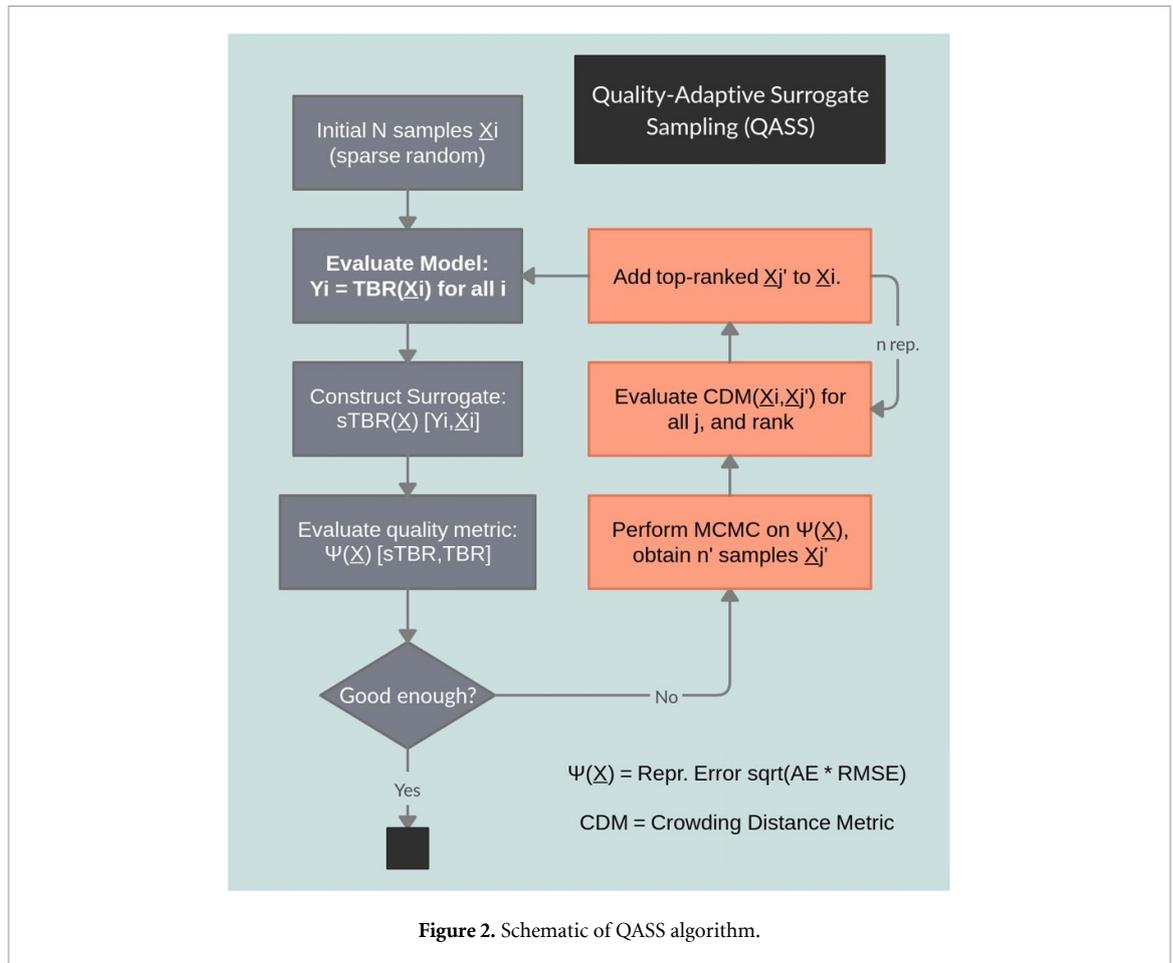
training set selection, all reported metrics are obtained via five-fold cross-validation. In this setting, a sample set is uniformly divided into five disjoint folds, each of which is used as a test set for models trained on the remaining four. Having repeated the same experiment for each division, the overall value of individual metrics is reported in terms of their mean and standard deviation over all folds.

## 2.1. Decoupled approach

Experiments related to the decoupled approach are organized in four parts, further described in this section. In summary, we aim to optimize the hyperparameters of each surrogate family separately, and later compare the best results between families.

The objective of Experiment 1 is to simplify the regression task for surrogates prone to suboptimal performance in discrete spaces. To this end, training points are filtered to a single selected discrete feature assignment, and surrogates are trained only on the remaining continuous features. This is repeated several times to explore variances in behavior, particularly in four distinct assignments that are obtained by setting blanket and first wall coolant materials to one of:  $\{\text{H}_2\text{O}, \text{He}\}$ . Experiment 2 conventionally measures surrogate performance on the full feature space without any parameter restrictions. In both experiments, hyperparameter tuning is facilitated by Bayesian optimization [20], where we select the hyperparameter configuration that produces the model that maximizes  $R^2$ . The process is terminated after 1000 iterations or 2 days, whichever condition is satisfied first. The results of Experiments 1 & 2 are depicted in figures 3 and 4 respectively, and described in section 3.1.1.

In Experiment 3, the twenty best-performing hyperparameter configurations for each model family are used to train surrogates on sets of various sizes to investigate their scaling properties. In particular, we track the metrics from table 3 as functions of training set size (1, 2, 5, 10, 12, 15 and 20 thousands of samples) individually for each family. This allows their comparison based on observed trends, and estimation of optimal training set sizes. The results of this experiment are shown in figure 5 and discussed in section 3.1.2.



Finally, Experiment 4 aims to produce surrogates suitable for practical use by retraining selected well-scaling instances on large training sets. The results of this process are displayed in figure 6 and in table 5, and summarized in section 3.1.3.

## 2.2. Adaptive approach

Adaptive sampling techniques appear frequently in the literature and have been specialized for surrogate modelling, where precision is implicitly limited by the quantity of training samples which are available from the expensive model. Garud's [21] 'Smart Sampling Algorithm' achieved notable success by incorporating surrogate quality and crowding distance scoring to identify optimal new samples, but was only tested on a single-parameter domain. We theorized that a nondeterministic sample generation approach, built around Markov Chain Monte Carlo methods (MCMC), would fare better for high-dimensional models by more thoroughly exploring all local optima in the feature space. MCMC produces each sample point according to a jump step drawn from a shared proposal distribution. These sample points will converge to a desired posterior distribution, so long as the acceptance probability meets certain statistical criteria (see [22] for a review).

Many researchers have embedded surrogate methods into MCMC strategies for parameter optimization [23, 24], in particular the ASMO-PODE algorithm [25] which makes use of MCMC-based adaptive sampling. Our approach draws inspiration from ASMO-PODE, but instead uses MCMC to generate samples which increase surrogate precision throughout the entire parameter space.

We designed the quality-adaptive surrogate sampling algorithm (QASS, figure 2) to iteratively increment the training/test set with sample points which maximize surrogate error and minimize a crowding distance metric (CDM) [26] in feature space. Error maximization is desirable for these sample points because it identifies regions of parameter space where the surrogate most needs to be improved. On each iteration following an initial training of the surrogate on  $N$  uniformly random samples, the surrogate was trained and absolute error calculated. MCMC was then performed to sample the error function generated by performing nearest-neighbor interpolation on these test error points. The resultant samples were culled by 50%

according to the CDM, and then the  $n$  highest-error candidates were selected for reintegration with the training/test set, beginning another training epoch. Validation was also performed during each iteration on independent, uniformly-random sample sets.

### 3. Results

#### 3.1. Decoupled approach

##### 3.1.1. Hyperparameter tuning

The results displayed in figure 3 indicate that in the first, simplified case GBTs clearly appear to be the most accurate as well as the fastest surrogate family in terms of mean prediction time. Following that, we note that ERTs, SVMs and ANNs also achieved satisfactory results with respect to both examined metrics. In addition, prediction times of GBTs and SVMs show relatively lower variance than those of ERTs and ANNs. Even though the remainder of tested surrogate families do not exhibit prohibitive complexity, their regression performance fall below the average.

Comparing these results with those of the second, unrestricted experiment (shown in figure 4), we observe that many surrogate families consistently underperform. The least affected models appear to be GBTs, ANNs and ERTs, which are known to be capable of capturing relationships involving mixed feature types that were deliberately withheld in the first experiment. With only negligible differences, the first two of these families appear to be tied for the best performance as well as the shortest prediction time. We observe that ERTs and RBFs also demonstrated satisfactory results, clearly outperforming the remaining surrogates in terms of regression performance, and in some cases also prediction time.

Following both hyperparameter tuning experiments, we conclude that while domain restrictions employed in the first case have proven effective in improving the regression performance of some methods, their performance fluctuates considerably depending on the selected slices. For instance, the variance in SVM performance in slice 1 is much lower than in slices 2–3, and both KNNs and ABTs perform much better in slices 1–2 than in slice 3. Furthermore, in all instances the best results are achieved by families of surrogates that do not benefit from this restriction (GBTs, ANNs, ERTs).

##### 3.1.2. Scaling benchmark

The results shown in figure 5 suggest that in terms of regression performance the most accurate families from the previous experiments consistently maintain their relative advantage over others, even as more training points are introduced. While such families achieve nearly comparable performance on the largest dataset, in the opposite case tree-based ensemble approaches clearly outperform ANNs. For instance, GBTs achieve  $MAE = 0.107$ , nearly half of the  $MAE = 0.186$  achieved by ANNs, representing a clear benefit given vastly disparate training and prediction times. This trend continues for set sizes up to 6000.

Consistent with our expectations, the shortest training times were achieved by instance-based learning methods (KNN, IDW) that are trained trivially at the expense of increased lookup complexity later during prediction. Furthermore, we observe that the majority of tree-based ensemble algorithms also perform and scale well, unlike RBFs and GPR which appear to behave superlinearly. We note that ANNs, which are the only family to utilize parallelization during training, show an inverse scaling characteristic. We suspect that this effect may be caused by a constant multi-threading overhead that dominates the training process on relatively small sets.

Finally, all tested families with the exception of previously mentioned instance-based models offered desirable prediction times. Analogous to previous experiments, GBTs, ABTs and ANNs appeared to be tied, as they not only exhibited comparable times but also similar scaling slopes. After those, we note a clear hierarchy of ERTs, SVMs, GPR and RBFs, trailed by IDW and KNNs.

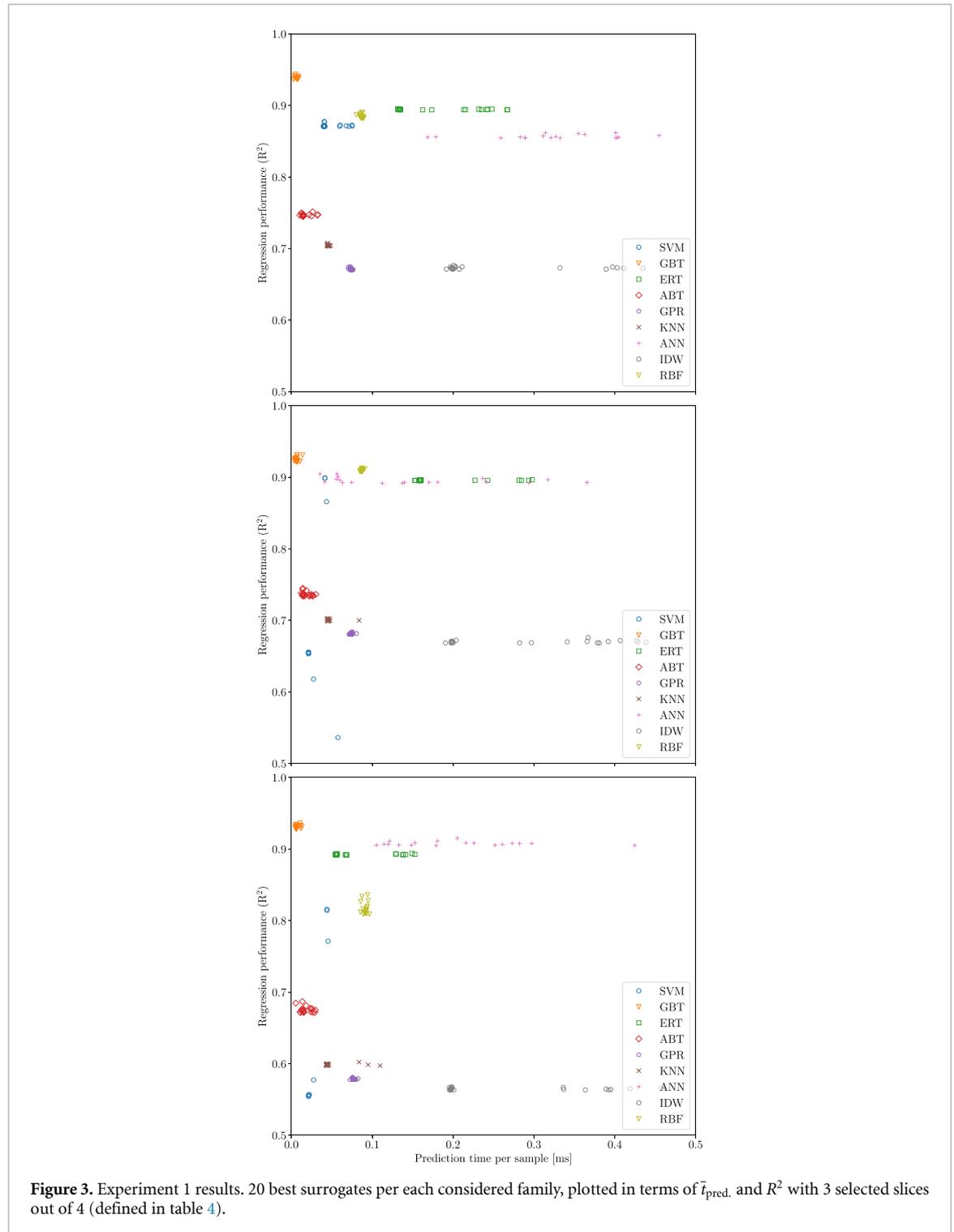
##### 3.1.3. Model comparison

In Experiment 4, we aim to create models that yield: (a) the best regression performance regardless of other features, (b) acceptable performance with the shortest mean prediction time, or (c) acceptable performance with the smallest training set. To this end, we trained 8 surrogates that are presented in figure 6 and table 5. We compared these surrogates with the baseline represented by Paramak per-sample evaluation time  $\bar{t}_{\text{eval.}} = 7.777\,049\,573\,054\,314 \pm 2.810\,359\,210\,393\,0337\text{s}$ , which was measured earlier on a set of 500 000 samples.

Having selected ANNs, GBTs, ERTs, RBFs and SVMs based on the results of Experiments 2 & 3, we utilized the best-performing hyperparameters. In pursuit of goal (a), the best approximator (Model 1, ANN) achieved  $R^2 = 0.998$  and mean prediction time  $\bar{t}_{\text{pred.}} = 1.124\ \mu\text{s}$ . These correspond to a standard

**Table 4.** Slices 1–4 of the domain space (discrete parameter assignments) explored in Experiment 1. Columns correspond to abbreviated parameter names listed in table 1.

BBM	BCM	BMM	BSM	FCM	FSM
Li <sub>4</sub> SiO <sub>4</sub>	H <sub>2</sub> O	Be <sub>12</sub> Ti	eurofer	H <sub>2</sub> O	eurofer
Li <sub>4</sub> SiO <sub>4</sub>	He	Be <sub>12</sub> Ti	eurofer	H <sub>2</sub> O	eurofer
Li <sub>4</sub> SiO <sub>4</sub>	H <sub>2</sub> O	Be <sub>12</sub> Ti	eurofer	He	eurofer
Li <sub>4</sub> SiO <sub>4</sub>	He	Be <sub>12</sub> Ti	eurofer	He	eurofer





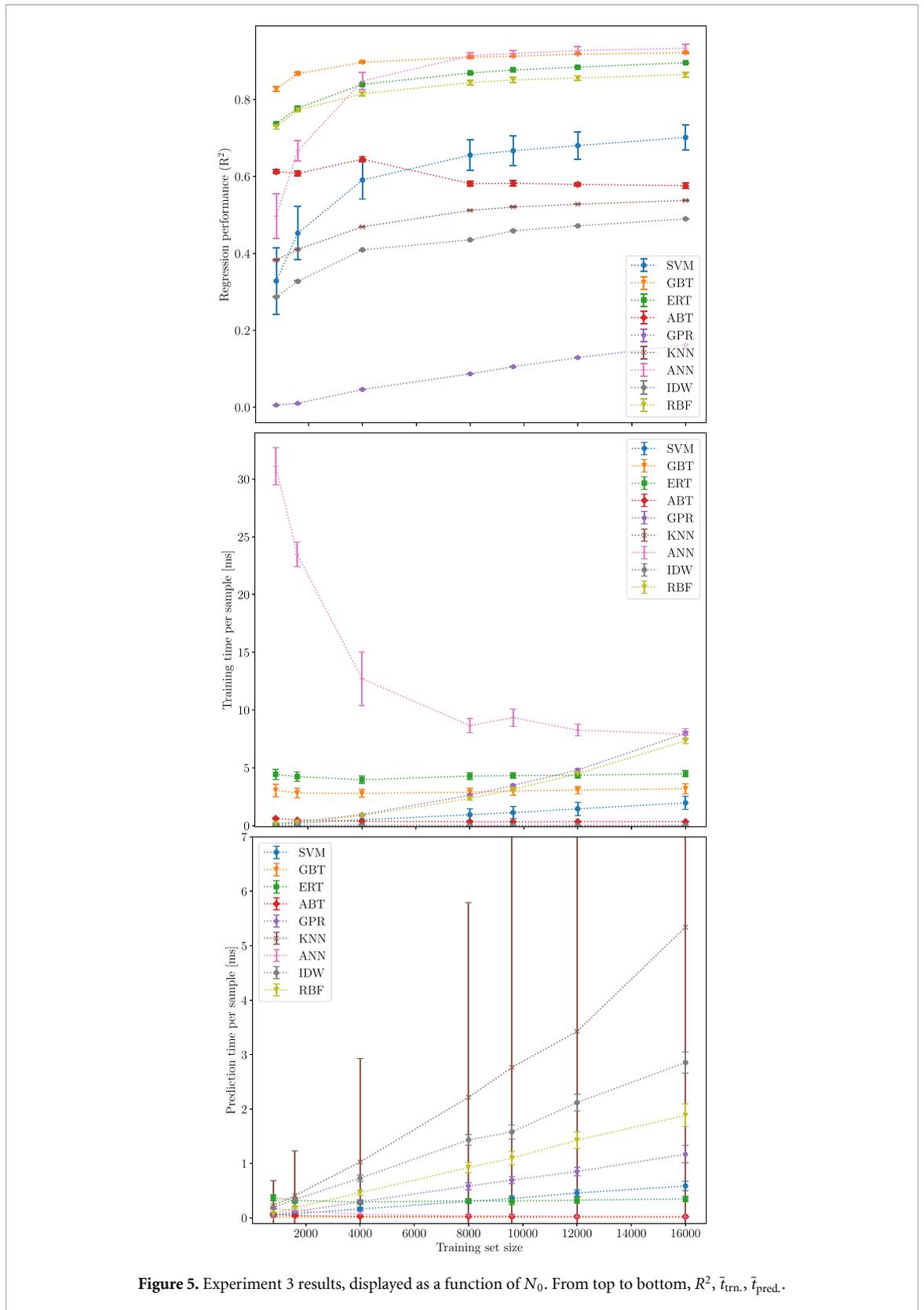
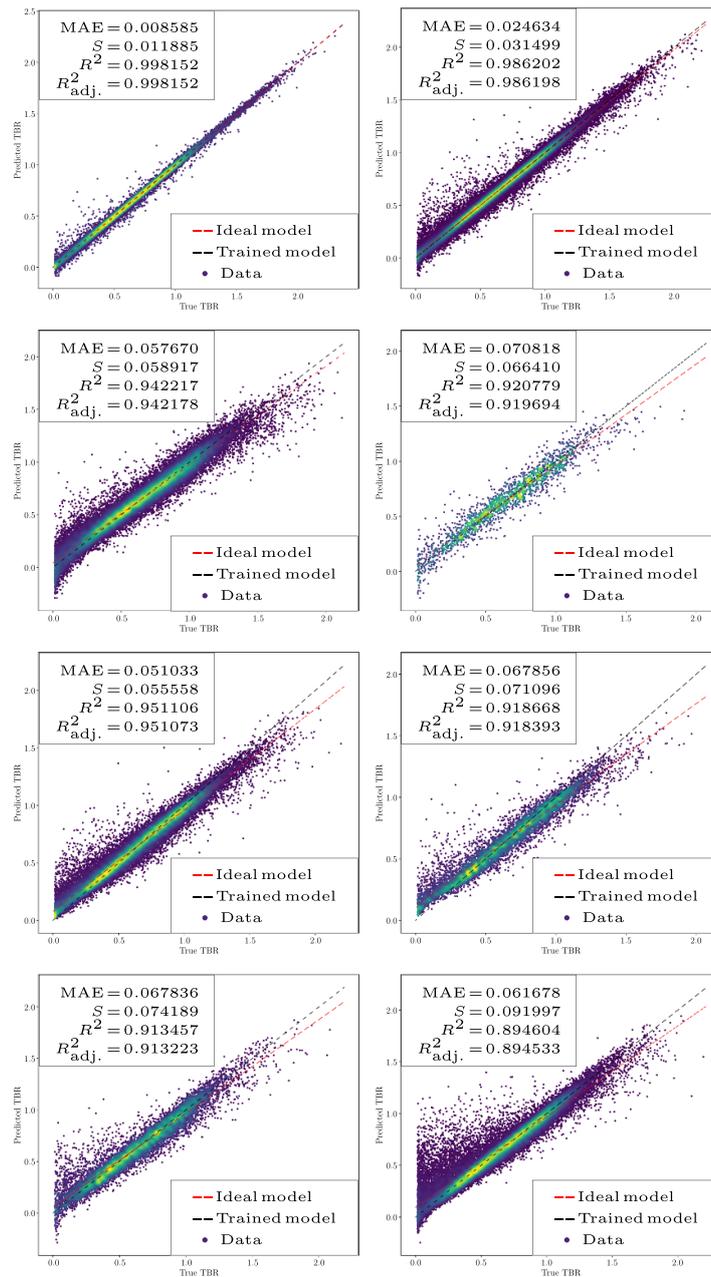


Figure 5. Experiment 3 results, displayed as a function of  $N_0$ . From top to bottom,  $R^2$ ,  $\bar{t}_{\text{tr}}$ ,  $\bar{t}_{\text{pred}}$ .

not affect QASS performance. Schemes in which the ANN is periodically retrained were also discarded, as the retention of network weights from one iteration to the next was demonstrated to greatly benefit QASS efficiency. Further insight came from direct comparison between QASS and a baseline scheme with uniformly random incremental samples, shown in figure 7.

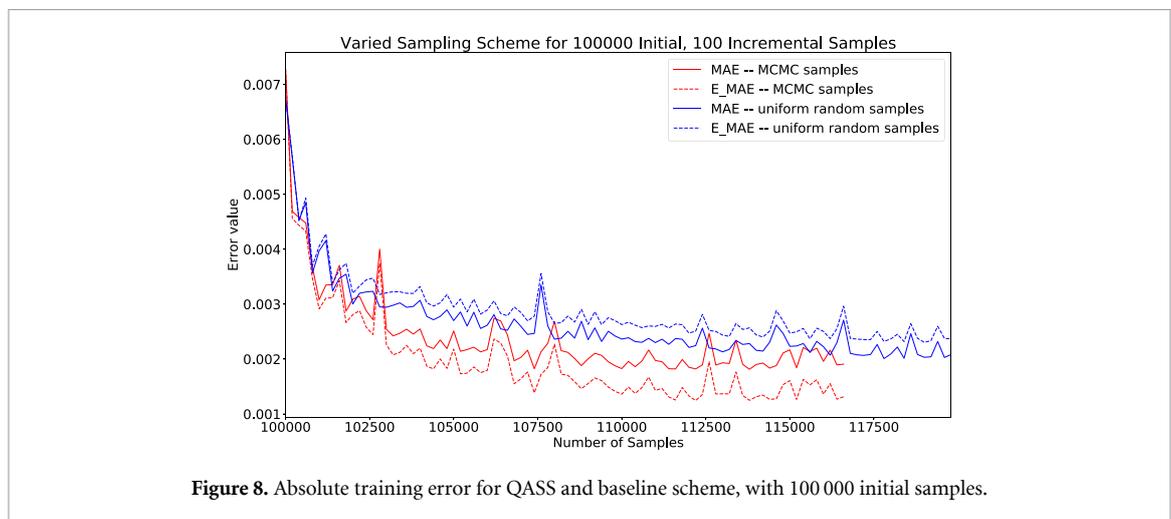
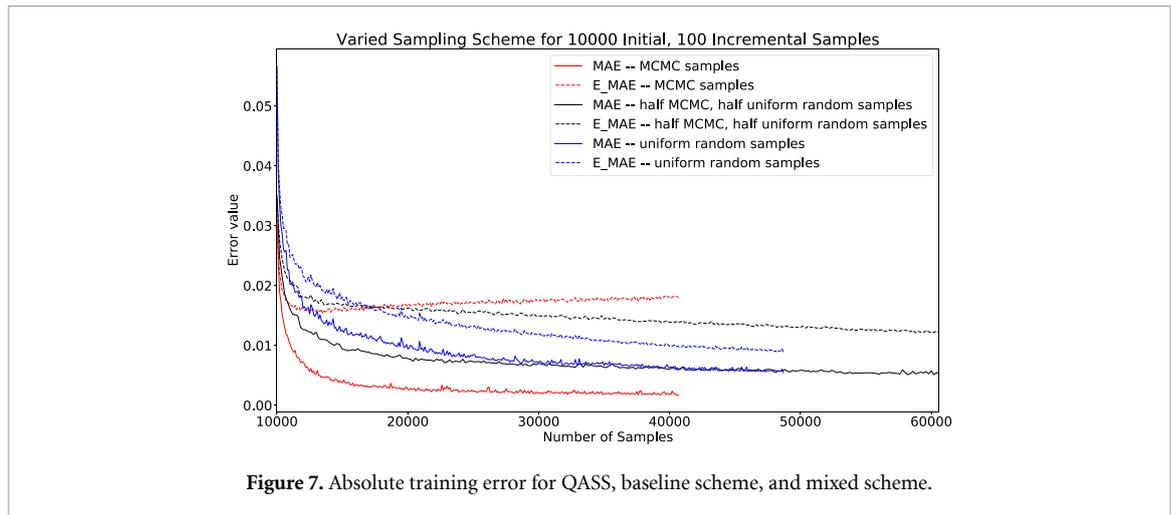


**Figure 6.** Regression performance of Models 1–8 (from left to right, top to bottom) in Experiment 4, viewed as true vs. predicted TBR on a test set of a selected cross-validation fold. Points are colored by density.

Such tests revealed that while QASS has unmatched performance on its own adaptively-sampled training set, it is outperformed by the baseline scheme on uniformly-random evaluation sets. We inferred that while QASS excels in learning the most strongly peaked regions of the TBR theory, this comes at the expense of precision in broader, smoother regions where uniformly random sampling suffices. Therefore a mixed scheme was implemented, with half MCMC samples and half uniformly-random samples incremented on each iteration, which is also shown in figure 7. An increase in initial sample size was also observed to improve precision in these smooth regions of the toy theory, as the initial samples were uniformly-random. As shown in figure 8, with 100 000 initial samples it was possible to obtain a  $\sim 40\%$  decrease in error as compared to the baseline scheme, from 0.0025 to 0.0015 mean averaged error. Comparing at the point of termination for QASS, this corresponds to a  $\sim 6\%$  decrease in the number of total samples needed to train a surrogate model while achieving the same error.

**Table 5.** Results of Experiment 4. Here, means and standard deviations are reported over five cross-validation folds,  $|\mathcal{T}|$  denotes cross-validation set size ( $\times 10^3$ ) and  $\omega$  is a relative speedup with respect to  $\bar{t}_{\text{eval.}} = 7.777049573054314 \pm 2.8103592103930337\text{s}$  measured in Paramak over 500000 samples. The best-performing method(s) under each metric are highlighted in bold.

Model	$ \mathcal{T} $	Regression performance					Computational complexity		
		MAE [TBR]	S [TBR]	$R^2$ [rel.]	$R^2_{\text{adj.}}$ [rel.]	$\bar{t}_{\text{trn.}}$ [ms]	$\bar{t}_{\text{pred.}}$ [ms]	$\omega$ [rel.]	
1 (ANN)	500.0	<b>0.008777</b> $\pm$ 0.000269	<b>0.012512</b> $\pm$ 0.000535	<b>0.997995</b> $\pm$ 0.000150	<b>0.997995</b> $\pm$ 0.000150	3.658670 $\pm$ 0.035377	<b>0.001124</b> $\pm$ 0.000062	691.6416 $\times$	
2 (ANN)	500.0	0.025271 $\pm$ 0.000719	0.033191 $\pm$ 0.001331	0.985065 $\pm$ 0.001069	0.985061 $\pm$ 0.001069	2.989270 $\pm$ 0.026018	<b>0.000898</b> $\pm$ 0.000037	<b>865.9251</b> $\times$	
3 (GBT)	200.0	0.058242 $\pm$ 0.000528	0.059233 $\pm$ 0.000337	0.941086 $\pm$ 0.000844	0.941046 $\pm$ 0.000845	2.220903 $\pm$ 0.010040	0.006647 $\pm$ 0.000218	116.9933 $\times$	
4 (GBT)	10.0	0.070804 $\pm$ 0.001843	0.071597 $\pm$ 0.003491	0.913014 $\pm$ 0.006027	0.911823 $\pm$ 0.006110	<b>1.621323</b> $\pm$ 0.007535	0.006125 $\pm$ 0.000291	126.9777 $\times$	
5 (ERT)	200.0	0.051286 $\pm$ 0.000288	0.056296 $\pm$ 0.000486	0.950486 $\pm$ 0.000738	0.950453 $\pm$ 0.000739	2.634038 $\pm$ 0.009780	0.214195 $\pm$ 0.003631	363.08 $\times$	
6 (ERT)	40.0	0.067868 $\pm$ 0.000302	0.071722 $\pm$ 0.000461	0.917489 $\pm$ 0.001005	0.917210 $\pm$ 0.001009	2.368460 $\pm$ 0.005461	0.187990 $\pm$ 0.008412	413.70 $\times$	
7 (RBF)	50.0	0.068405 $\pm$ 0.000813	0.076889 $\pm$ 0.001908	0.909963 $\pm$ 0.003076	0.909719 $\pm$ 0.003084	3.452536 $\pm$ 0.018824	1.512068 $\pm$ 0.016163	514.3 $\times$	
8 (SVM)	200.0	0.062351 $\pm$ 0.000493	0.094484 $\pm$ 0.001577	0.890579 $\pm$ 0.002923	0.890505 $\pm$ 0.002925	33.346811 $\pm$ 0.381933	2.415167 $\pm$ 0.010751	3220 $\times$	



## 4. Conclusion

We employed a broad spectrum of data analysis and machine learning techniques to develop a library of fast and high-quality surrogate models for the expensive Paramak TBR model. After reviewing 9 surrogate model families, examining their behaviour on a constrained and unrestricted feature space, and studying their scaling properties, we retrained the best-performing instances to produce properties desirable for practical use. The fastest surrogate, an artificial neural network trained on 500 000 datapoints, attained an  $R^2 = 0.985$  with mean prediction time of  $0.898 \mu\text{s}$ , representing a relative speedup of  $8 \cdot 10^6$  with respect to Paramak. Furthermore, we demonstrated the possibility of achieving comparable results using only a training set of size 10 000.

We additionally developed a novel adaptive sampling algorithm, QASS, capable of interfacing with any of the surrogate models presented in this work. Preliminary testing on a toy theory, qualitatively comparable to Paramak, demonstrated the effectiveness of QASS and key behavioral trends. With 100 000 initial samples and 100 incremental samples per iteration, QASS achieved a  $\sim 40\%$  decrease in surrogate error compared to a baseline random sampling scheme. Further optimization over the hyperparameter space has strong potential to increase this performance by further reduction of necessary expensive samples, in particular by decreasing the required quantity of initial samples. This will allow for future deployment of QASS on top of any of our most effective identified TBR surrogate models.

## Data availability statement

Relevant source code, model instances and datasets are freely available online as well as a more detailed technical report [27, 28].

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