1 Nonlinear wave resonance due to oscillations of twin cylinders in a

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12 Abstract

A higher order finite element method with 8-node element is adopted to analyse the 13 nonlinear wave resonance generated by oscillations of twin cylinders in a uniform current. 14 The velocity potential in the fluid domain at each time step is obtained based on the finite 15 element method through an iteration procedure. Numerical results are provided for twin 16 rectangular cylinders undergoing specified oscillations in a uniform current at resonant 17 frequencies. The effects of current on the wave and hydrodynamic force at the resonant 18 frequencies are studied in detail and it is found that the resonance happens at all first-order 19 resonant frequencies for both symmetric and antisymmetric motions of the cylinders. In 20 particular, in addition to the first-order resonant frequency, the maximum wave elevation and 21 horizontal force at resonance always regularly increase or decrease as the increase of the 22 absolute value of Froude number or the spacing between two cylinders within the range of 23 larger spacings. A similar trend can be also observed in the oscillational frequency of 24 cylinders at resonance. Some results are also compared with those by linear solution and its 25 superposition with the second-order, their difference at different Froude numbers are also 26 discussed. 27

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30 1. INTRODUCTION

31 Wave resonance is an interesting phenomenon in the field of hydrodynamics and it has important application in ocean engineering. The resonance happens when the wave frequency 32 33 is equal to or even near the natural frequency of an ocean structure such as oil platforms. 34 Correspondingly, large wave elevation and hydrodynamic forces are expected at resonance. A traditional approach to study wave resonance is through the perturbation method and quite a 35 36 lot of works can be found in literature. For examples, Second-order resonances of sloshing 37 waves in two-dimensional (2-D) and three dimensional (3-D) containers were analytically 38 studied by Wu [1] and Zhang et al. [2], respectively. The linear and second-order resonances 39 at nearly trapped modes were investigated by Maniar and Newman [3], Evans and Porter [4], 40 Chen and Lee [5], Malenica et al. [6], Wang and Wu [7] and Kagemoto et al. [8]. Furthermore, 41 recent attempts on two structures of side-by-side configuration can be found in Sun et al. [9], 42 Watai et al. [10] and Zhao et al. [11].

43 Another approach to analyse wave-structure interaction is through the velocity potential 44 theory with fully nonlinear boundary conditions. Wang and Wu [12] did research on wave 45 resonance induced by two 2-D cylinders through the finite element method and it was found 46 that wave elevations and hydrodynamic forces trend to be infinity when the perturbation 47 method is applied, which is not in line with the actual situation. Inspired by this, the similar 48 problem was further considered by Wang et al. [13] through the fully nonlinear numerical 49 model. They found that both the wave elevation and hydrodynamic forces on the structures 50 are much smaller than those obtained through the second-order theory. The amplitude of wave 51 and force finally reach a constant value rather than become infinity when the time is 52 sufficiently long. Later, Wang et al. [14] extended the work to the situation of multiple 2-D 53 cylinders in vertical motions, while Li and Zhang [15] employed the boundary element method 54 to study a similar problem that wave resonance generated by two 2-D barges in vertical 55 motions. In addition to 2-D structures, typical study on wave resonance generated by 3-D 56 floating bodies can be found in Sen [16] by a mixed Eulerian–Lagrangian panel method. The 57 works mentioned above are all about wave resonance induced by the motion of floating 58 structures. Besides, the resonance phenomena can be also observed in the problem of wave 59 diffraction. For example, Bai et al. [17] simulated multiple cylinders diffracted by waves at 60 nearly trapped frequencies. Ning et al. [18] and Feng and Bai [19] considered diffracted wave resonated by 2-D and 3-D multiple bodies in narrow gap respectively. In real engineering, the 61 62 effects of viscosity may also be important to the wave resonance phenomenon. The main 63 shortcoming of the viscous model is that it requires many computer resources. Wang et al. [20] 64 studied wave resonance between two elongated parallel boxes with a narrow gap through experiment and viscous flow theory. Zhao et al. [21] also did experimental work on wave 65 66 resonance within a narrow gap. Lu and Chen [22] added a dissipation coefficient to free 67 surface boundary condition based on the potential theory and good results were achieved when compared with the experimental data. However, how to choose the dissipation 68 coefficient depends on the experiment result and the numerical solution based on the viscous 69 70 flow theory. Other typical works with considering vicious effects can be found in Lu et al. [23], 71 Chua et al. [24] and Jiang et al. [25].

72 The aforementioned studies don't involve the current effect. It is well known that the 73 wave frequency and amplitude will be affected by the presence of current. The effect is more 74 obvious when the current speed is larger. Correspondingly, the waves and loads on ocean structures will be some or even significantly different from those without current, which will 75 76 have important influence on the design of the ocean structures. Extensive works on wave-current-body interactions may be found in [26-31]. However, to the best of our 77 78 knowledge, very little work is done for wave resonance with considering current effect. 79 Fredriksen et al. [32] studied piston type resonance in a moonpool of two rectangular cylinders 80 in vertical motions with a small gap at a low forward speed. In their work, both the 81 experimental tests and numerical simulations are made to investigate resonant behaviour. 82 Recently, Huang and Wang [33] studied two rectangular cylinders undergoing vertical and 83 horizontal motions at resonant frequencies based on the second-order theory in the time 84 domain. They found that the maximum wave elevation and hydrodynamic force generally 85 decrease as the increases of Froude number and the nonlinearities become weaker. In addition, 86 the resonant frequencies in both vertical and horizontal motions generally and slowly increase 87 as the spacing between cylinders increases. Yang and Wang [34] also investigated the 88 second-order wave diffraction by four vertical cylinders at near-trapping frequencies and

89 found that the current effect on the wave and force is very clear, especially for the 90 second-order components.

91 In this paper, we consider the problem of wave resonance by vertical and horizontal 92 motions of two rectangular cylinders in a steady current. Compared with the investigation 93 through the perturbation procedure in Huang and Wang [33], a fully nonlinear potential flow 94 model is employed and more detailed analyses in physics are made for the current effect. 95 Although the fully nonlinear potential theory usually overpredicts results about wave and 96 hydrodynamic force when compared with the experiment data or the simulation based on the 97 viscous flow theory. However, it can still provide meaningful results in describing the behaviour 98 of wave and hydrodynamic force to show the relation between the wave or force peak and the 99 current speed, the oscillational frequency, the oscillational amplitude and the gap between 100 structures. The influence of current on the magnitude of the oscillational frequency at 101 resonance, as well as on the value and nonlinearities of wave & hydrodynamic force are 102 further discussed. Besides, a comparison is made for the similarities and differences between 103 parts of the present nonlinear results and the second-order solutions. The present study may 104 provide useful results about wave-current loads on multi-hulled ships and two approaching 105 offshore structures in wave-current environment.

The paper is organized as follows. The mathematical model of the problem is presented in Section 2. The finite element method applied to discretize the governing equation is introduced in Section. 3. The numerical results are given in Section 4. In particular, the wave resonances induced by vertical oscillations are discussed in Section 4.1, while those by horizontal oscillations are analysed in Section 4.2.

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113 2. MATHMATICAL FORMULATION

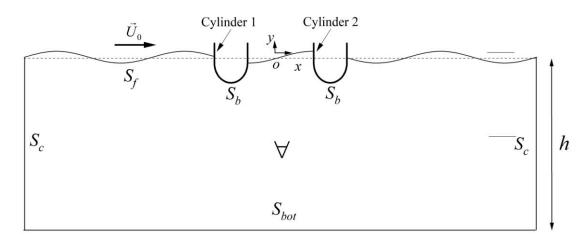




Fig. 1. Coordinate system.

Wave radiation by twin cylinders in forced motions is considered here. A right-handed 116 117 Cartesian coordinate system o-xy is defined in Fig. 1, in which x is on the still water level and 118 y points upward and is perpendicular to the x-axis. The surface of each cylinder is denoted as 119 S_{b} , on which the unit normal vector of any point is $\vec{n} = (n_x, n_y)$ and it directs inward to the 120 cylinder. Both cylinders are located at $(x_{c,k}, 0)$ (k=1, 2), respectively, when they are at rest in 121 the calm water. The left and right cylinders are called as cylinders 1 and 2 respectively. The 122 water bottom S_{bot} is a plane at y=-h. As convenience for simulations, the fluid domain is 123 truncated at an artificial boundary S_c , which is usually three- or four-times linear wavelength 124 distance from the nearest cylinder. We denote t as time and η as wave elevation on free surface S_f . In the fluid domain \forall , the fluid is perfect, and its motion is irrotational. A 125 126 velocity potential ϕ which satisfies the Laplace equation is introduced to describe the fluid 127 motion

128
$$\nabla^2 \phi = 0 \qquad \text{in } \forall \,. \tag{1}$$

For flow problems with a uniform current with speed U_0 along the *x*-axis, the total velocity potential in the fluid domain is expressed as

131
$$\Phi = U_0 x + \phi, \qquad (2)$$

132 where Φ is also governed by the Laplace equation. The boundary conditions should be 133 imposed on all boundaries for solving the boundary value problem to obtain the potential. The

potential ϕ is used in the simulation and its kinematic and dynamic conditions on the free

135 surface S_f can be written as

$$\frac{Dx}{Dt} = U_0 + \frac{\partial \phi}{\partial x} \\
\frac{Dy}{Dt} = \frac{\partial \phi}{\partial y}$$
(3a, b)

(4)

(6)

137

 $\frac{D\phi}{Dt} = -g\eta + \frac{1}{2} |\nabla\phi|^2,$ respectively, where g denotes the gravity acceleration and $\frac{D}{Dt} = \frac{\partial}{\partial t} + \nabla \phi \cdot \nabla$ is the material 138

139 derivative.

140 To satisfy the radiation condition, an artificial damping zone is placed near the truncated 141 boundary S_c to absorb the incoming wave and minimize the reflection. This is achieved 142 through adding a damping term in Eqs. (3) and (4), or

$$\frac{Dx}{Dt} = U_0 + \frac{\partial\phi}{\partial x}
\frac{Dy}{Dt} = \frac{\partial\phi}{\partial y} - v(x)y ,$$
(5a, b)

where v(x) denotes the artificially viscous coefficient and its expression in detail may be 145 146 found in Wang et al. [13].

147

The impermeable condition on the cylinder surface can be expressed as 148

 $\frac{\mathrm{D}\phi}{\mathrm{D}t} = -g\eta + \frac{1}{2}\nabla\phi\nabla\phi - \nu(x)\phi,$

149
$$\frac{\partial \phi}{\partial n} = -U_0 n_x + \vec{n} \cdot (\vec{v} + \vec{\Omega} \times \vec{r}) \qquad \text{on } S_b, \qquad (7)$$

where \vec{v} is the translational velocity of cylinder 1 or 2 at $x = x_{c,k}$ (k = 1,2) and y = 0, 150

 $\vec{\Omega}$ is the angular velocity around the axis z_k which passes through $(x_{c,k}, 0)$ and is 151 perpendicular to the *xoy* plane. $\vec{r} = (x - x_{c,k}, y)$ is the location vector. 152

153 On the bottom of the water, the velocity potential ϕ satisfies

154
$$\frac{\partial \phi}{\partial n} = 0$$
 on S_{bot} . (8)

The initial conditions including the position of the free surface and the potential on it are given as

$$\begin{array}{l} y(t=0) = 0\\ \phi(x, y; t=0) = 0 \end{array} \right\}.$$
 (9a, b)

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157

The velocity potential in the fluid domain is obtained through solving Eqs. (1), (5) ~ (9). The
pressure on the cylinder surface is calculated by using the Bernoulli equation

161
$$p = -\rho \left(\frac{\partial \phi}{\partial t} + U_0 \frac{\partial \phi}{\partial x} + \frac{1}{2} \left| \nabla \phi \right|^2 + gy \right), \qquad (10)$$

162 where ρ denotes the fluid density. The hydrodynamic force and moment acting on the 163 cylinder can be obtained by a direct integration of the pressure over the instantaneous wetted 164 cylinder surface

165
$$\vec{F}_j = \int_{S_b} p \vec{n}_j ds.$$
(11)

In above equation, $\vec{n}_j = (n_1, n_2, n_3) = (n_x, n_y, n_z, r_x n_y - r_y n_x)$ is the normal vector of any point on the surface of cylinder, where (r_x, r_y) is the location vector. In Eq. (11), a problem is how to calculate the integral of $\partial \phi / \partial t$ or ϕ_t over the wetted body surface. Here, we choose to follow the procedure proposed in Wu [35] and Wu and Eatock Taylor [36]. Through introducing a term related to the uniform current in Eq. (2), this approach is now extended to forward speed problems or problems with current effects. In particular, the term ϕ_t satisfies the Laplace equation in the fluid domain as

$$\nabla^2 \phi_t = 0. \tag{12}$$

174 On the free surface, ϕ_t is obtained through

175
$$\phi_t = -gy - \frac{1}{2}\nabla\phi\nabla\phi - U_0\frac{\partial\phi}{\partial x} \quad . \tag{13}$$

176 On the stationary boundary, ϕ_t satisfies

177
$$\frac{\partial \phi_t}{\partial n} = 0, \qquad (14)$$

and on the nonstationary boundary, it is

179
$$\frac{\partial \phi_{i}}{\partial n} = (\dot{\vec{v}} + \dot{\vec{\Omega}} \times \vec{r}) \cdot \vec{n} - \vec{v} \cdot \frac{\partial \nabla \phi}{\partial n} + \vec{\Omega} \cdot \frac{\partial}{\partial n} \{ \vec{r} \times [(\vec{v} - \vec{U}_{0}) - \nabla \phi] \},$$
(15)

where the dot over \vec{v} and $\vec{\Omega}$ means the derivative with respect to time. Thus, the time 180 181 derivative ϕ_t can be obtained through solving Eqs. (12) ~ (15).

182

3. FINITE ELEMENT DISCRITAZATION AND NUMERICAL PROCEDURES 183

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In the present simulations, we employed a finite element method with 8-node quadrilateral 184 185 isoparametric element (see Fig. 2) to calculate the velocity potential at each time step. The shape functions defined in a local coordinate system $\vec{\xi} = (\xi, \zeta)$ corresponding to element e 186 187 with eight nodes may be expressed as

$$N_{i}^{(e)}(\xi,\zeta) = \frac{1}{4}(1+\xi_{i}\xi)(1+\zeta_{i}\zeta)(\xi_{i}\xi+\zeta_{i}\zeta-1) \quad (i=1,2,3,4)$$

$$N_{i}^{(e)}(\xi,\zeta) = \frac{1}{2}(1-\xi^{2})(1+\zeta_{i}\zeta) \qquad (i=5,7)$$

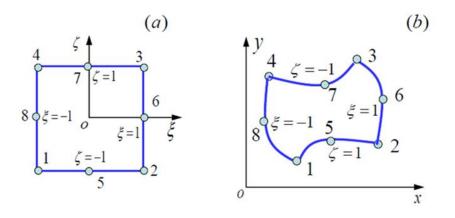
$$N_{i}^{(e)}(\xi,\zeta) = \frac{1}{2}(1-\zeta^{2})(1+\xi_{i}\xi) \qquad (i=6,8)$$

$$(16a, b, c)$$

189 The Evaluation of first and second order derivatives of potential with respect to coordinates such as $\partial \phi / \partial x$, $\partial \phi / \partial y$, $\partial^2 \phi / \partial x^2$, $\partial^2 \phi / \partial x \partial y$ and $\partial^2 \phi / \partial y^2$, which are required in Eqs. 190 191 (5), (6), (10) and (15) can be obtained through differentiating the shape functions or Eq. (16)192 directly. The Detailed finite element discretization and calculation of derivatives can be found 193 in Wang et al. [13]. The element coefficient matrices can be calculated in every quadrilateral 194 element, and they are then assembled into a global coefficient matrix M. Meanwhile, the 195 right-hand side vector \mathbf{F} with considering the normal velocity on the boundary can also be 196 calculated. Thus, a system of linear equations by finite element method can be established as

197
$$\mathbf{M}\boldsymbol{\Phi} = \mathbf{F}, \tag{17}$$

where $\mathbf{\Phi} = [\phi_1, \phi_2, \dots, \phi_n]^T$ is the velocity potential vector containing potentials 198 ϕ_i (*i* = 1,2,...,*n*) and *n* is the total number of nodes in the discretized fluid domain. Eq. (17) 199 can be solved through the conjugate gradient method with a symmetric successive 200 201 overrelaxation (SSOR) preconditioner.



202 203

Fig. 2. 8-node quadrilateral isoparametric element.

On the free surface, nodes (x_i, y_i) (i=1,2,...,n) and their potential ϕ at the next time step 204 205 are calculated through Eqs. (5) ~ (6), which is numerically implemented based on the 206 fourth-order Runge-Kutta method. It should be noticed that the intersection points between 207 the free surface and the cylinder surface should be handled because very small gap exists 208 between them in the simulation and the closest nodes to the cylinder surface should be taken back 209 to stay on the cylinder surface at each time step. Furthermore, the nodes (x_i, y_i) (i=1,2,..,n)210 should be redistributed every several time steps to avoid clustering or stretching, and the 211 redistribution will be performed more frequently due to the existence of the current speed than that without current. In addition, a remeshing method based on the B-spline function [37] is applied 212 213 for smoothing the free surface during the simulation.

214

215 4. NUMERICAL RESULTS

216 We consider twin rectangular cylinders in vertical or horizontal oscillations. Wang et al. 217 [13] made simulations of fully nonlinear wave motions between twin rectangular, 218 wedged-shaped and elliptical cylinders in specified oscillations without current. They found that the resonance is much more serious in the rectangular cylinder than those for the 219 220 wedge-shaped and elliptical cylinders. Thus, we investigate two rectangular cylinders in 221 forced oscillations only in the present paper. Besides, the effect of a uniform current is further 222 considered. The width of each cylinder is 2b and the initial draught is d=b/2 at still water 223 plane. The still water depth h=10d. The spacing between the centre lines of the two cylinders is denoted by l_c . Cylinders 1 and 2 are initially located at $x_{c,1}=-l_c/2$ and $x_{c,2}=l_c/2$, 224

225 respectively.

226

227

The cylinders are subject to following oscillation in vertical or horizontal direction

(18)

$$\delta = A \sin \omega t$$
,

where A is the oscillational amplitude and ω is the oscillational frequency. A modulation function is applied in Eq. (7) [12] to ensure the wave developing gradually and smoothly. The current speed U_0 is nondimensionalized as the Froude number and it is defined as $F_n = U_0 / \sqrt{gb}$. As discussed in Wang and Wu [12] based on the second-order theory, the real resonant frequency is

233
$$\omega_i' = C_i \omega_i \ (i = 1, 2, \cdots) \tag{19}$$

for cases without current, where C_i is a constant and can be obtained by numerical tests. ω_i

is defined as

236
$$\omega_i = \sqrt{\frac{i\pi}{l_c - b}} g, \quad (i = 1, 2, ...),$$
 (20)

and it is the resonant or natural frequency of a sloshing container with $(l_c - b)$ in width and great depth of water. It should be noted that the resonant frequency is equal to the oscillational frequency predicted by Eq. (19) of both cylinders when resonance happens at $F_n=0$. However, they are somewhat different from each other when a current exists. For convenience, the oscillational frequencies corresponding to the real resonant frequencies ω'_i (i = 1, 2, ...) are denoted as ω''_i (i = 1, 2, ...) here when $F_n \neq 0$.

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4.1. Wave resonance induced by vertical motions of the cylinder

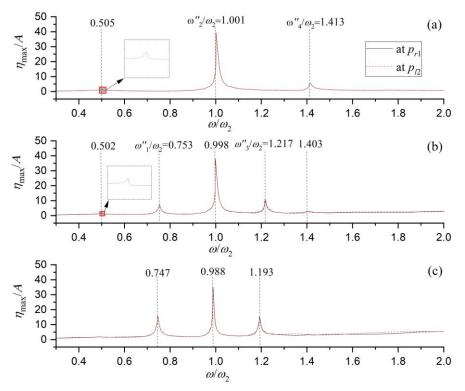
We first make some simulations at A/d=0.0125 for both cylinders in a completely same vertical motions at three Froude numbers $F_n=0$, 0.064 and 0.128. The spacing between two cylinders is chosen as $l_c=8b$. The situation of a current propagating along the negative x-direction or $F_n<0$ is not considered here due to the symmetric properties of the problem. Besides, the waves between two cylinders are generally much larger than those outside the cylinders at resonant frequencies [12, 13]. Thus, we may pay more attention to the regions between two cylinders. For convenient comparison, we may denote the positions of the left 252 and right sides of cylinder 1 by p_{l1} and p_{r1} , while using p_{l2} and p_{r2} for cylinder 2. Fig. 3 gives 253 the nondimensionalized values of maximum wave elevations η_{\max} at p_{rl} & p_{l2} versus the 254 nondimensionalized oscillational frequency ω/ω_2 , where ω_2 is defined in Eq. (20). At $F_n=0$ (see Fig. 3a), the two curves coincide with each other because of symmetry, and their three 255 256 peaks at ω/ω_2 =0.505, 1.001 & 1.413 approximately can be observed. Among them, the maximum wave is at $\omega/\omega_2 = 1.001$, while that at $\omega/\omega_2 = 0.505$ is the smallest and an 257 enlarged view is given to show. As discussed by Wu [1], Wang and Wu [12] and Wang et al. 258 259 [13], for symmetric motions such as vertical oscillations in an identical direction or horizontal 260 oscillations in opposite directions. The first- and second-order resonances happen at the even order resonant frequencies ω_{2i} (i = 1,2,...) and half of the even order resonant 261 frequencies $\omega_{2i}/2(i=1,2,...)$, respectively. By contrast, when the system undergoes 262 asymmetric motions such as the horizontal oscillations toward an identical direction, the 263 first-order resonance happens at ω_{2i-1} (i = 1, 2, ...), while the second-order resonance is at 264 $\omega_{2i}/2(i=1,2,...)$. For the case without the current or $F_n=0$, only little differences between 265 the fully nonlinear results and second-order solution are observed. In particular, the 266 second-order resonance actually happens at $\omega/\omega_2 = 0.5\omega_2''/\omega_2 \approx 0.505$, which is very close 267 to the prediction value $\omega/\omega_2 = 0.5$, while the first-order resonance happens at 268 $\omega/\omega_2 = \omega_2''/\omega_2 = 1.001$ and $\omega/\omega_2 = \omega_4''/\omega_2 = 1.413$, which is very close to and $\omega_2/\omega_2 = 1.413$ 269 270 and $\omega_4 / \omega_2 = 1.414$ predicted by Eq. (20).

Figs. 3b gives the maximum waves at F_n =0.064. Compared with F_n =0 in Fig. 3a, a distinct difference is that two peaks appear at ω_1''/ω_2 =0.753 and ω_3'/ω_2 =1.217, which are close to the anti-symmetrical resonance frequencies ω_1/ω_2 =0.707 and ω_3/ω_2 =1.225 predicted by Eq. (20). The reason why two peaks appear at ω_1''/ω_2 =0.753 and ω_3''/ω_2 =1.217 is probably that the fluid motion becomes asymmetric due to the presence of the current and

hence the resonances around the odd-order frequencies ω'_{2i-1} (i = 1,2) can be observed. 276 $0.5\omega_2''/\omega_2$ Besides, nondimensionalized oscillational 277 the frequencies and ω_i''/ω_2 (i = 2,4) become slightly smaller and change from 0.505, 1.001 & 1.413 at $F_n=0$ to 278 0.502, 0.998 & 1.403 at $F_n=0.064$, respectively. Another interesting phenomenon can be 279 noticed is that both the peaks at $\omega_2''/\omega_2 = 0.998$ and $\omega_4''/\omega_2 = 1.403$ in Fig. 3b become 280 281 smaller when comparing with the corresponding ones in Fig. 3a, respectively. When the 282 Froude number continue to increase to 0.128 (see Fig. 3c). It can be seen that the peak at around $0.5\omega_2''/\omega_2 = 0.5$ almost disappears, and even that at ω_4''/ω_2 cannot be graphically 283 seen. The oscillational frequencies ω_1''/ω_2 , ω_2''/ω_2 and ω_3''/ω_2 become more smaller and 284 they are 0.747, 0.988 & 1.194, respectively. Furthermore, it can be seen that peak at 285 $\omega_1''/\omega_2 = 0.747$ and $\omega_3'/\omega_2 = 1.193$ clearly become larger than those at $F_n = 0.064$. In summary, 286 all oscillational frequencies $\omega_i''(i=1,2,3,4)$ slightly decrease as the increases of F_n . The 287 peak at ω_i''/ω (i = 2,4) decline and that at ω_i''/ω (i = 1,3) increase as the increase of F_n , 288 respectively. 289

290 Fig. 4 gives a clearer comparison of maximum wave elevation at p_{r1} . The main peaks at ω_2'' are around 39.45, 37.97 and 34.65 at $F_n=0$, 0.064 and 0.128, respectively, which means 291 292 the wave peak at resonance generally decreases as the Froude number increases. Similar declination is also observed at ω_4'' . However, the situation here is a little different. The peak 293 at $F_n=0.128$ is the least obvious but its magnitude is larger than that at $F_n=0.064$. This is 294 because the resonance effect at ω_4'' is not as strong as that at ω_2'' . When a current with 295 296 larger speed exists, the current effect may dominate the wave-current-structure interactions 297 and weaken the resonance. In such a case, the waves at the intersection points between the 298 free surface and the cylinder surface will be mainly evaluated by the current. By contrast, the peaks around ω_1'' and ω_3'' clearly increases as the increases of the Froude number, which 299 indicates the current can reduce the resonant effect at ω_2'' and ω_4'' but enhance that at ω_1'' 300

and ω_3'' . Besides, the phenomenon at $\omega_2''/2$ is similar to that at ω_4'' . Fig. 5 shows the corresponding maximum horizontal forces $F_{x,\text{max}}$ on both cylinders versus the nondimensionalized frequency, which is generally similar to the wave depicted in Fig. 4.



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Fig. 3. Maximum values of waves versus ω/ω_2 ; (a) $F_n=0$; (b) $F_n=0.064$; (c) $F_n=0.128$.

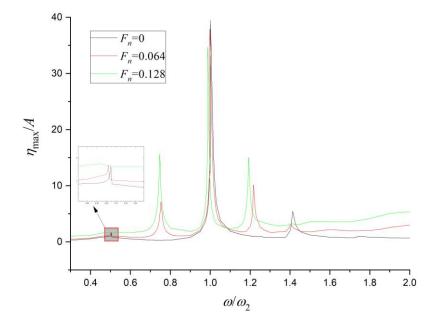
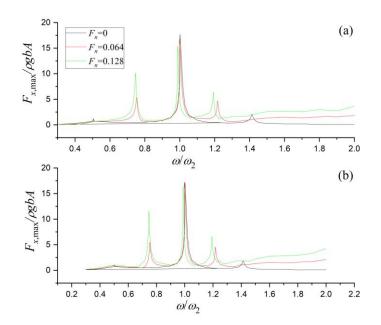




Fig. 4. Maximum values of waves at p_{r1} versus ω/ω_2 .



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Fig. 5. Maximum horizontal forces on (a) cylinder 1 and (b) cylinder 2 versus ω/ω_2 .

311 Fig. 6 shows convergence tests for mesh and time interval. In the figure, η expresses the 312 wave elevation. Wang et al. [13] have tested the cases at $F_n=0$ and hence we give convergence tests at $F_n=0.128$ only. The test of waves at p_{r1} & p_{l2} is at $\omega_2''/\omega_2=0.988$, which is the 313 314 position of the main peak. The control surfaces S_c at both ends are located at distance about 315 four times wavelength away the nearest cylinder. Two meshes and time intervals are used to 316 test the numerical convergence. The details are given in Table 1, where NF1 is the segment 317 number along the free surface on the left of cylinder 1 or the right of cylinder 2, NF2 denotes 318 the segments on the free surface between the two cylinders, ND and NB denote the segments 319 along the vertical and horizontal faces of each cylinder respectively, NH represents the segment on the both control surfaces S_c at the far ends, NE and NN are the total numbers of 320 321 elements and nodes in the whole fluid domain respectively. The results for Case 1 and Case 322 2 are given in Fig. 6. It can be seen that they are in very good agreement over the entire 323 simulations of two hundred cycles. These tests show that Case 1 with 3904 elements & 12201 nodes and $\Delta t = T/250$ can provide convergent results in this case. 324

Table 1. Parameters of mesh schemes

	NF1	NF2	ND	NB	NH	NE	NN	Δt
Case 1	70	42	9	12	20	3904	12201	T/250
Case 2	100	60	14	18	26	7192	22277	T/500

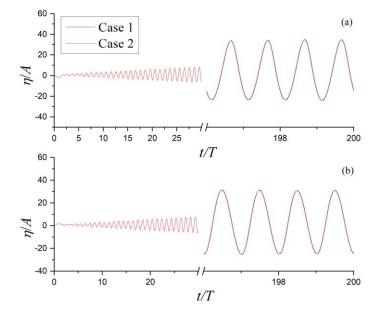


Fig. 6. Comparisons of waves with different meshes and time intervals at F_n =0.128. (a) at p_{r1} ; (b) at p_{l2} .

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Fig. 7 gives wave histories at p_{r1} and p_{l2} at the nondimensionalized oscillational 331 frequencies ω_2''/ω_2 . Similar variation trends can be observed in these three waves at both p_{r1} 332 333 and p_{12} . In particular, the amplitude generally increases as the development of most time and 334 then a gradual decline may appear at the end of simulation time. It has already been shown in 335 Fig. 4 that the maximum wave within the simulation time of two hundred cycles clearly 336 decreases as the increase of F_n at ω_2''/ω_2 . The wave histories in this figure show how the waves develop as the increase of time at the resonant frequencies and the three Froude 337 numbers, and this is distinctly different from the situation of a single cylinder shown in Fig. 8, 338 in which the wave runup rises to a bigger value as the increase of F_n at both the left and right 339 340 sides. Moreover, the wave runup in Fig. 7 are much larger than those in Fig. 8, in which the waves runups at $F_n=0$, 0.064 and 0.128 are about 0.6, 0.88 & 1.83 at the right side and 0.6, 341 342 0.97 & 1.89 at the left side, respectively.

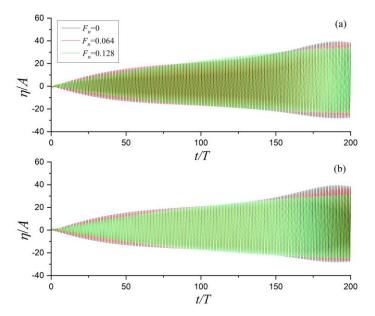
A comparison of wave between the fully nonlinear results and the linear plus second order solutions at $\omega_2''/\omega_2 = 1.001$ and $F_n=0$ is given in Fig. 9. Detailed simulations of wave resonance due to oscillations of two rectangular cylinders in a current based on the second order theory can be found in Huang and Wang [33]. It can be seen from the figure that the 347 nonlinear wave is in good agreement with the linear plus second order solution within the first 348 forty cycles and then they become distinctly discrepant. It should be mentioned that the above 349 three resonant frequencies are a little different from those obtained by Huang and Wang [33] 350 and it is because the former is based on the fully nonlinear model and the latter is on the second order theory. In particular, according to the second order theory [33], the 351 nondimensionalized oscillational frequencies ω_2''/ω_2 at $F_n=0, 0.064 \& 0.128$ are about 1.01, 352 1.005 & 0.99, respectively. In the case of $F_n=0$, the wave histories at p_{r1} are given in Fig. 10 353 with $\omega_2''/\omega_2 = 1.01$ and it is shown that the linear and linear plus second-order waves 354 355 always increase as the time, but the fully nonlinear wave has a clear envelope oscillating at a 356 lower frequency and it maximum peak is much smaller than those of linear and linear plus 357 solution solutions. Thus, the waves exhibit a completely different change at the two frequencies $\omega_2''/\omega_2 = 1.001$ and 1.01, which are calculated based on the fully nonlinear 358 model and the second order theory, respectively. Similarity can be found for the waves at 359 $F_n=0.064$, which is not given here. Further comparison of wave at p_{r1} at resonant frequency 360 $\omega_2''/\omega_2 = 0.988$ and at $F_n=0.128$ is given in Fig. 11. The waves are in good agreement 361 362 between the fully nonlinear result and the linear plus second order solution before t/T=25.

Fig. 12 shows the corresponding hydrodynamic forces on cylinder 1 at $\omega_2''/\omega_2 = 1.001$, 0.998 & 0.988 at $F_n=0$, 0.064 & 0.128, respectively. The variation of the horizontal force F_x with the Froude number is similar to that of the wave. It is also noted that all vertical components F_y at smaller Froude number have more evident double peaks, which corresponds to stronger nonlinear feature.

Fig. 13 shows histories of waves at p_{r1} with A/d=0.0125, 0.025 and 0.05. It can be seen that the difference between the three nondimensionalized waves at each F_n is very clear. Generally, the wave nonlinearity becomes stronger as the amplitude increases at each F_n . However, as pointed out by Wang et al. [13] that the waves in smaller oscillational amplitudes can exhibit clearer resonant behaviour because their nondimensionalized amplitudes are larger. In other words, the wave resonances in larger oscillational amplitudes are weaker.

Fig.14 depicts the wave profiles from t=196T to 200T with a time interval $\Delta t = 0.1T$ at

375 ω_1'' and ω_2'' with the aforementioned three Froude numbers. It is known that no resonance 376 happens at ω_1'' when $F_n=0$ (see Fig. 14a). We then replace ω_1'' with ω_1 obtained by Eq. (20) 377 for comparisons with those at ω_1'' when $F_n=0.064 \& 0.128$. It is seen that the wave between 378 the two cylinders is much larger than those outside the two cylinders except that in Fig. 14a. 379 The wave development with time can be also clearly seen and differences between different 380 F_n can also be observed.



381

382

Fig. 7. Histories of waves at oscillational frequencies ω_2'' ; (a) at p_{r1} ; (b) at p_{l2} .

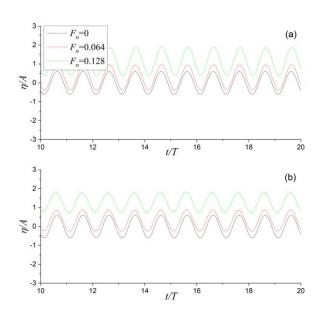


Fig. 8. Histories of waves at (a) the right side and (b) the left side of a single cylinder at ω_2'' .

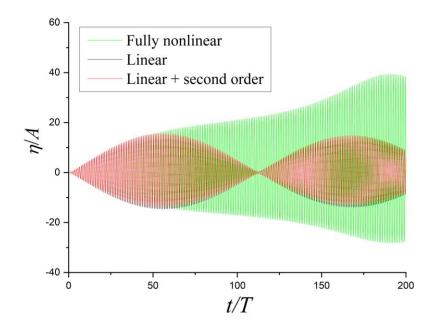






Fig. 9. A comparison of waves with linear and linear plus second order solutions

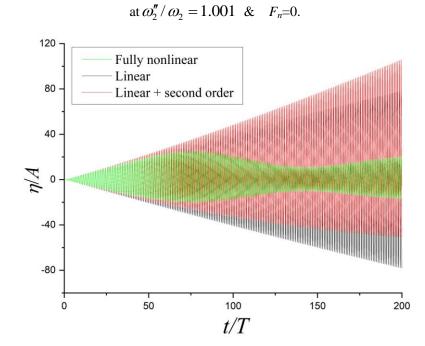


Fig. 10. Comparisons of waves with linear and linear plus second order solutions

at
$$\omega_2'' / \omega_2 = 1.01$$
 & $F_n = 0$.

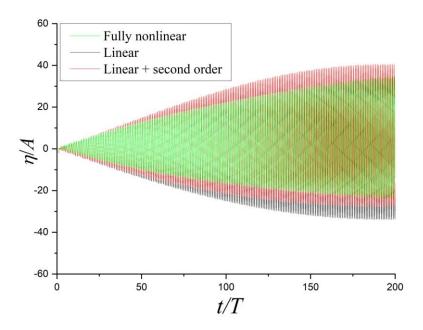


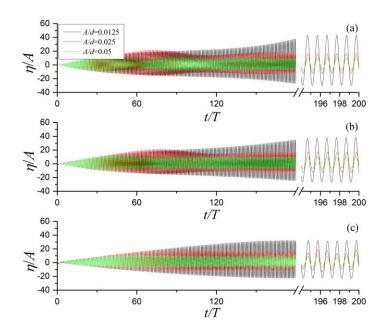


Fig. 11. Comparisons of waves with linear and linear plus second order solutions

at $\omega_2'' / \omega_2 = 0.988$ & $F_n = 0.128$.

 $F_n = 0$ $F_n = 0.064$ (a) $F_n = 0.128$ $F_x/\rho gbA$ u))))) -10 -20 -30 o t/T(b) $F_{y}/\rho gbA$ -10 -20 -30 t/T

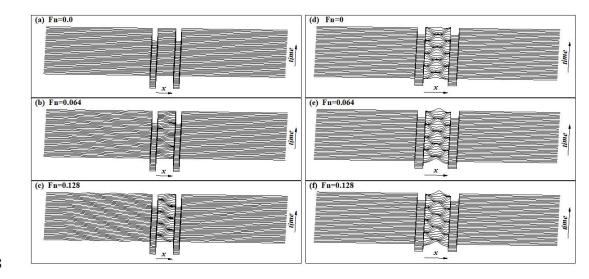
Fig. 12. Histories of forces on cylinder 1 at ω_2'' .





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Fig. 13. Histories of waves at p_{r1} at ω_2'' ; (a) $F_n=0$; (b) $F_n=0.064$; (c) $F_n=0.128$.



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Fig. 14. Snapshots of wave profiles at (a), (b) & (c) $\omega = \omega_1''$ and (d), (e) & (f) $\omega = \omega_2''$ from 400 t=196T to 200T with time interval $\Delta t = 0.1T$.

402 The work mentioned above is for the spacing between two cylinders $l_c=8b$. In fact, the 403 resonance behaviour is also affected by the ratio l_c/b . We also made simulations at different 404 l_c/b from 5 to 9 besides $l_c/b=8$. We first give the results of maximum waves and forces versus l_c/b at ω_2'' in Fig. 15. It can be seen that both the wave peaks and force peaks at three 405 different F_n increase as l_c/b . Besides, for a given l_c/b , the maximum waves and forces also 406 increase with F_n . Similar analyses are also conducted for the results at ω_1'' and ω_3'' , which 407

are depicted in Fig. 16. It should be noted that only the situations at F_n =0.064 & 0.128 are provided due to no resonance or no peak at F_n =0. It is clearly shown that both maximum waves and forces at every l_c/b become larger when F_n increase from 0.064 to 0.128. However, for a given F_n , the maximum waves and forces at ω_1'' and ω_3'' do not just show a increase trends as those at ω_2'' .

The nondimensionalized frequencies ω_1''/ω , ω_2''/ω , ω_3''/ω and ω_{2h}''/ω versus the 413 spacing l_c/b is given in Fig. 17, in which ω_{2h}'' is the oscillational frequency at the second order 414 resonance and it is approximately half of ω_2'' in the case of $l_c/b=8$. It can be seen that all 415 resonant frequencies generally become smaller as F_n increases at every l_c/b . ω_1''/ω_2 almost 416 linearly increases as F_n increases. However, both ω_{2h}''/ω_2 and ω_3''/ω_2 rise quickly in the 417 beginning and then have a slight change as the increase of l_c/b . The situation at ω_2''/ω_2 is 418 419 similar to the linear solutions presented in Huang and Wang [33]. It is also noticed that $\omega_{2h}'' \approx \omega_2''/2$ at larger l_c/b . However, the discrepancy between ω_{2h}'' and $\omega_2''/2$ is more 420 evident at smaller l_c/b . For example, as shown in Fig. 18, ω_{2h}'' at all three F_n are around 0.41 421 at $l_c/b=5$, which is quite different from the corresponding value of $\omega_2''/2$. This is probably due 422 423 to the evident effects of narrower spacings on the lower frequency waves when resonance 424 happens.

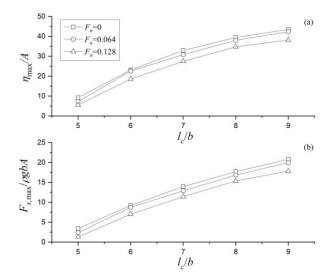


Fig. 15. Maximum waves and horizontal forces versus L_{cy}/b at ω_2'' ; (a) waves at the right side 427 of cylinder 1; (b) horizontal forces on cylinder 1.

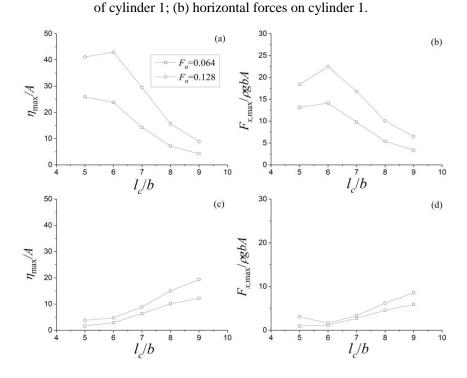
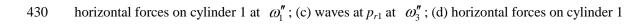




Fig. 16. Maximum waves and horizontal forces versus l_c/b ; (a) waves at p_{r1} at ω_1'' ; (b)





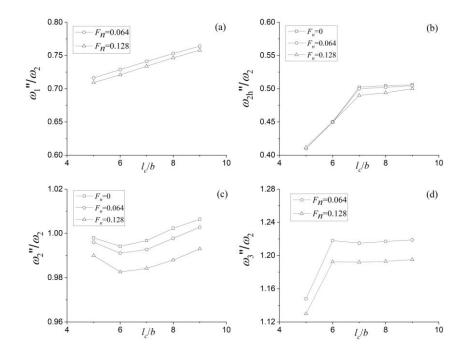


Fig. 17. Resonant frequencies versus l_c/b .

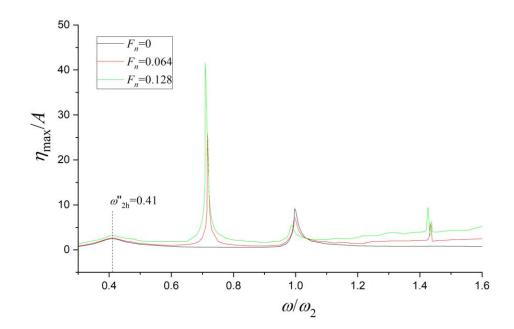






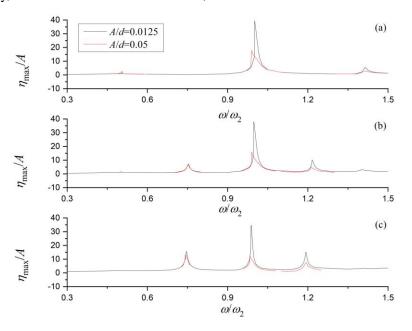
Fig. 18. Maximum values of waves at p_{r1} versus ω/ω_2 at $l_c/b=5$.

436 Fig. 19 gives the waves versus ω/ω_2 at A/d=0.0125 and 0.05 to show the nonlinearity at 437 different resonant frequencies. The maximum wave elevations clearly decline as the increase of F_n at ω_1''/ω_2 , ω_3''/ω_2 and ω_2''/ω_2 , which is in agreement with the results given in Fig. 13. 438 Furthermore, it is seen that each value of ω_1''/ω_2 , ω_2''/ω_2 or ω_3''/ω_2 generally becomes a little 439 440 smaller with the increase of F_n , and a comparison of values of oscillational frequencies 441 ω_i''/ω_2 (i = 1,2,3) at A/d=0.0125 and 0.05 in detail is given in Table 2. All these indicate that 442 stronger nonlinearity and weaker resonant characteristic for waves in larger amplitudes. Similar 443 phenomenon can be also observed in the hydrodynamic forces on cylinder 1 given in Fig. 20.

It is known that the fully nonlinear results obtained by the velocity potential theory may overpredict the results than those by experiments or simulation based on viscous flow theory. Thus, it may cause dispute that whether the velocity potential theory is suitable for simulations of wave resonance or not. As mentioned in Isaacson and Cheung [38], if the Keulegan-Carpenter number *K* is less than 3, the flow separation effect is relatively localized and need not be considered, the potential theory is still valid. The Keulegan-Carpenter number *K* is defined as

$$450 K = \pi A_e / D (21)$$

451 whre *D* is the characteristic diameter of body and A_e the excursion amplitude of fluid particle. In 452 our simulation, D=2b=2m is the width of each cylinder, A_e should be less than the maximum peaks. 453 Two maximum nondimensional peaks η_{max} / A in Fig.19 are at $F_n=0$ and ω_2'' and they are 454 around 39.5 at A/d=0.0125 and 17.9 at A/d=0.05 (see Fig. 19a), and we replace A_e with η_{max} and 455 substitute them into Eq. (21) and obtain their Keulegan-Carpenter number K are 0.77 and 1.41, 456 respectively, which are both less than 3. Hence, the aforementioned simulations are valid.



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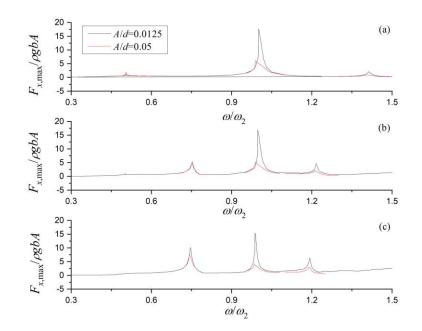
Fig. 19. Comparisons of maximum values of waves at p_{r1} versus ω/ω_2 at A/d=0.0125 &

459
$$0.05$$
; (a) $F_n=0$; (b) $F_n=0.064$; (c) $F_n=0.128$.

460

Table 2 The best approximations for $C_i = \omega_i'' \omega_2$ (i = 1, 2, 3)

	A/d	ω_1''/ω_2	ω_2''/ω_2	ω_3''/ω_2
$F_n=0$	0.0125	-	1.001	-
	0.05	-	0.990	-
<i>F</i> _n =0.064	0.0125	0.7530	0.998	1.217
	0.05	0.753	0.990	1.212
F _n =0.128	0.0125	0.747	0.988	1.193
	0.05	0.743	0.984	1.193



463

Maximum horizontal forces on (a) cylinder 1 versus ω/ω_2 at A/d=0.0125 & 0.05; (a) Fig. 20.

464 $F_n=0$; (b) $F_n=0.064$; (c) $F_n=0.128$.

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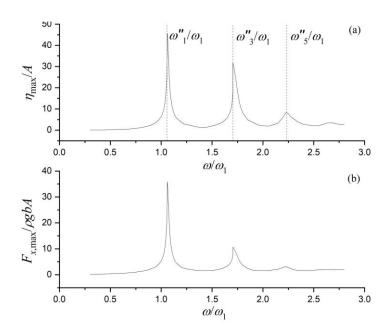
4.2. Wave resonance induced by horizontal motions of the cylinder

467 In addition to wave resonance induced by vertical motions of the cylinder, the resonances 468 by horizontal motion of two cylinders in an identical direction given in Eq. (18) are also 469 analysed here. The case at $l_c/b=8$ is first considered. Fig. 21 gives the maximum wave at p_{r1} 470 and the horizontal force on cylinder 1 versus ω/ω_1 at A/d=0.0125 & $F_n=0$. It is shown that three peaks for waves or forces can be clearly seen at $\omega/\omega_1 = \omega_i''/\omega_1$ (i = 1,3,5) = 1.060, 471 1.705 and 2.230, respectively, which are quite close to ω_i / ω_1 (*i*=1,3,5) predicted by Eq. 472 (20) and they are 1.0, 1.732 and 2.236, respectively. As discussed by Wang and Wu [12], the 473 first- and second-order resonances should have occur at $\omega = \omega'_{2i-1}$ $(i = 1, 2 \cdots)$, and 474 $\omega = \omega'_{2i} / 2(i = 1, 2, \dots)$, respectively, for antisymmetric or horizontal motions in an identical 475 direction. However, for the current fully nonlinear analysis, it is seen that no peak graphically 476 appears at $\omega = \omega'_{2i} / 2 (i = 1, 2, \cdots)$. 477

478 Fig. 22 made further comparisons of maximum waves at p_{r1} and forces in the x-direction 479 at five Froude numbers F_n =-0.128, -0.64, 0, 0.064 and 0.128. It can be seen from Fig. 22a that 480 the magnitudes of five main peaks of waves at the oscillational frequencies ω_1'' do not change too much when the Froude number increases or decreases, However, the peaks at ω_3'' 481 482 and ω_5'' clearly decrease as the absolute value of F_n increases. As pointed out by Wang and 483 Wu [12], Wang et al. [14], Huang and Wang [33], no resonance happen at $\omega = \omega'_{2i}$ $(i = 1, 2, \dots)$ for horizontal motions in an identical direction when $F_n=0$. However, it is interesting to see 484 that four bigger peaks at ω_2'' and four smaller peaks at ω_4'' appear when $F_n \neq 0$ and ω_2'' / ω_2 485 & ω_4''/ω_2 are approximately 1.396, 1.415, 1.415 & 1.398, as well as 1.94, 1.98, 1.98 & 1.93 486 for F_n =-0.128, -0.064, 0.064 & 0.128, respectively. It can be seen that the peak at ω_2'' also 487 increases as the increase of the absolute value of F_n and that at ω_4'' increases as the increase 488 489 of F_n . Similarity can be also for the forces in Fig. 22b.

Fig. 23 gives the waves versus ω/ω_1 at A/d=0.0125 and 0.05 to exhibit the nonlinearities of waves and forces at different resonant frequencies. Just like the situations of vertical oscillations, the maximum nondimensionalized waves decreases as the increase of F_n at ω_i''/ω_1 ($i = 1, 2, \dots, 5$) and each ω_i''/ω_1 at A/d=0.05 are generally smaller than those at A/d=0.0125. The corresponding hydrodynamic forces on cylinder 1 are given in Fig. 24 and similarity can be found.

Similar to the analyses about Keulegan-Carpenter number in Fig. 19, the maximum wave peak η_{max} is about 37.7*A* at ω_1'' , *A/d*=0.05 and *Fn*=-0.128 in Fig. 23, and its corresponding Keulegan-Carpenter number is 2.96, which is also less than 3. Hence, the simulations of the horizontal motions are also valid.





501

Fig. 21. Maximum values of waves at p_{r1} and maximum horizontal forces on cylinder 1

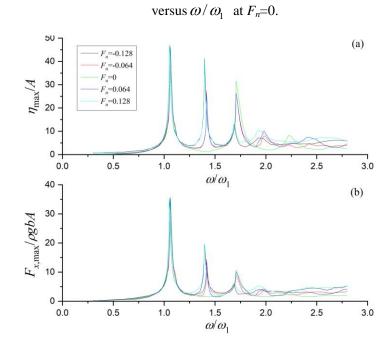
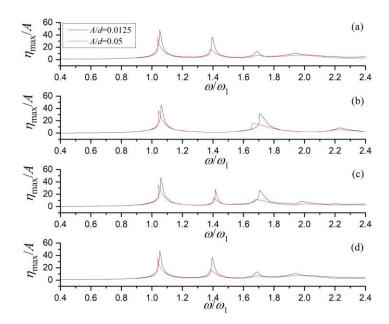




Fig. 22. Maximum values of waves at p_{r1} and maximum horizontal forces on cylinder 1

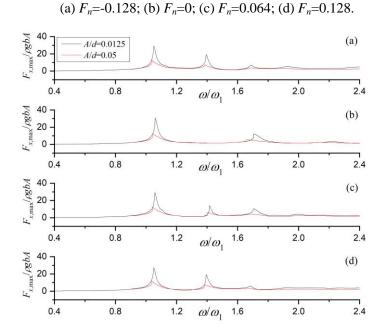
505

versus $\omega/\omega_{\rm l}$.



Comparisons of maximum values of waves at p_{r1} versus ω / ω_1 at A/d=0.0125 & 0.05; 507 Fig. 23.





509

510 Fig. 24. Maximum horizontal forces on (a) cylinder 1 versus ω/ω_1 at A/d=0.0125 & 0.05; (a)

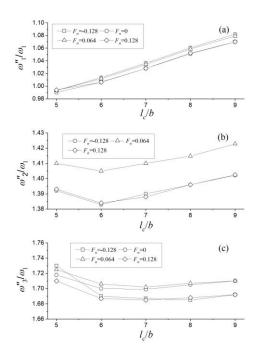
- 511 F_n =-0.128; (b) F_n =0; (c) F_n =0.064; (d) F_n =0.128.
- 512

Simulations at $l_c/b = 5$, 6, 7 and 9 are also made in addition to $l_c/b = 8$ for horizontal motions. 513 The oscillational frequencies ω_1''/ω_1 , ω_2''/ω_1 and ω_3''/ω_1 versus l_c/b are given in Fig. 25. 514 515 Four Froude numbers F_n =-0.128, 0, 0.064 and 0.128 are used. It can be seen that the 516 nondimensionalized frequency at each Froude number is nearly linearly increases as l_{cy}/b

517 increases for ω_1''/ω_1 within the whole range of l_c/b and for ω_2''/ω_1 when $l_{cy}/b>6$, and it 518 becomes smaller as the absolute value of F_n increases at each l_{cy}/b (see Figs. 25a, 25b).

519 The maximum waves and horizontal forces on cylinder 1 as functions of l_c/b at ω_1'' , ω_3''

and ω_2'' are shown in Figs. 26 and 27. The maximum waves at ω_1'' in Fig. 26a decrease as 520 the increase of l_c/b at each Froude numbers and they are clearly different at smaller l_c/b and 521 then they almost coincide with each other when $l_c/b \ge 7$. The horizontal forces given in Fig. 522 523 26b, however, show more complicate change with the spacing and the Froude number. All maximum values are at $l_c/b=7$ and they decline at other values of l_c/b . The maximum waves 524 and forces at ω_3'' generally increase as the increase of l_c/b and decrease as the absolute value 525 of F_n at each l_c/b . As to the situation at ω_2'' , the cases at F_n =-0.128, 0.064 and 0.128 are given 526 527 in Fig. 27, in which the results at $F_n=0$ are not provided because of no resonance happens and 528 hence there is no peak. It can be seen that both maximum wave and force gradually grow up as the spacing l_c/b becomes larger at every F_n , and they are generally enlarged with the 529 530 increase of the absolute value of F_n at every l_c/b .



532 Fig. 25. The oscillational frequency at resonance versus l_c/b in horizontal motions; (a) ω_1''/ω_1 ;

533 (b)
$$\omega_2'' / \omega_1$$
; (c) ω_3'' / ω_1

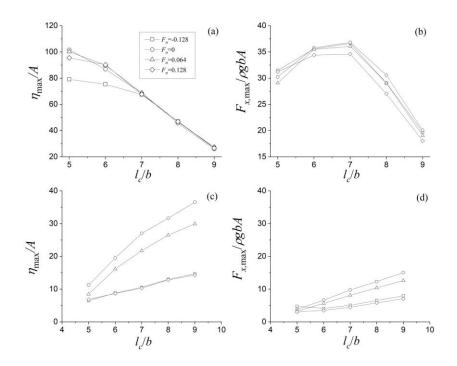
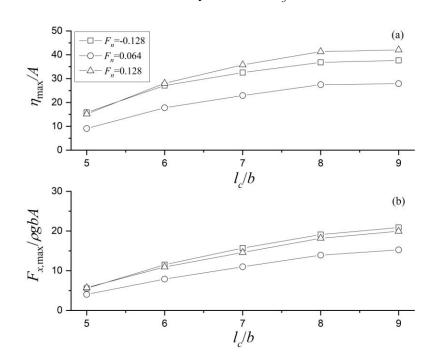


Fig. 26. Maximum waves and horizontal forces versus L_{cy}/b at ω_1' and ω_3' ; (a) waves at p_{r1} at ω_1'' ; (b) horizontal forces on cylinder 1 at ω_1'' ; (c) waves at p_{r1} at ω_3'' ; (d) horizontal forces on 537 cylinder 1 at ω_3'' .



539 **Fig. 27.** Maximum waves and horizontal forces versus L_{cy}/b at ω_2'' in horizontal motions; (a) 540 waves at the right side of cylinder 1; (b) horizontal forces on cylinder 1. 541

542 **5. Conclusions**

A fully nonlinear potential flow model based on a higher order finite element method with 8-node curve element is used to analyse the wave resonance between twin cylinders in specified oscillations in a uniform current. The 4th order Runge-Kutta algorithm is employed to track the node positions and corresponding potentials on them at each time step. A damping zone method is used for satisfying the radiation condition.

Numerical simulations have been made for twin rectangular cylinders in the free surface in vertical and horizontal motions in a uniform current at resonant frequencies. Waves and hydrodynamic forces are calculated, and comparisons are made at different Froude numbers. The current effect on the wave and force has been analysed at odd and even-order resonances. Besides, the nonlinearity of the wave and forces are also discussed. The simulation shows the current has a critical influence on the waves and forces at resonant frequencies in both vertical and horizontal oscillations. The conclusion of this study is summarized as below:

555 As discussed in Section 4, the first and second order resonances happen at ω'_{2i} (i = 1, 2, ...) and $\omega'_{2i}/2$ (i = 1, 2, ...), respectively, for vertical oscillations or the 556 horizontal in opposite directions at $F_n=0$. Similarly, the first and second order resonances also 557 occur at $\omega = \omega'_{2i-1}$ $(i = 1, 2 \cdots)$, and $\omega = \omega'_{2i} / 2$ $(i = 1, 2, \cdots)$, respectively, for horizontal 558 oscillations in an identical direction at $F_n=0$. However, when a current exists or $F_n\neq 0$, it is 559 found that the first order resonance happens at all frequencies $\omega_i''(i=1,2,...)$ for both 560 vertical and horizontal motion, and the second-order resonant effect is generally weak. For the 561 vertical motions, the maximum wave and horizontal force at ω_{2i}'' (i = 1,2) become smaller as 562 F_n increases. However, they are clearly increases as the increase of F_n at ω''_{2i-1} (i = 1, 2); For 563 the horizontal motions, the maximum wave and horizontal force have only a little change as 564 F_n changes at ω_1'' , which is not regular. However, they generally decrease at ω_3'' and 565 increase at ω_2'' as the increase of the absolute value of F_n . 566

567 The oscillational frequencies $\omega_i''(i=1,2,3)$ and ω_{2h}'' at resonance become somewhat 568 smaller as the increase of F_n in vertical motions and $\omega_i''(i=1,2)$ decrease as the increase of the absolute value of F_n in horizontal motions within the whole range of l_c/b . Besides, they generally increase as l_c/b when $l_c/b \ge 6$ for both vertical and horizontal motions.

The wave and force at $\omega_i''(i = 1, 2...)$ versus the spacing l_c/b are also studied. For vertical motions, the maximum values of wave and horizontal force at ω_2'' always enhance as the increases of l_c/b at every F_n , and they are generally decline or increase as the increases of l_c/b within $l_c/b \ge 6$ at ω_1'' or ω_3'' , respectively; For horizontal motions, as l_c/b increases, the maximum value of wave at ω_1'' decreases as the increases of l_c/b at every F_n . By contrast, both the maximum wave and force increase as the increases of l_c/b at $\omega_i''(i = 2,3)$.

For oscillations of both cylinders in larger amplitudes, the oscillational frequencies $\omega_i''(i=1,2,...)$ are clearly smaller than those under smaller amplitude oscillations, and the nondimensionalized maximum values of wave and horizontal force become smaller under larger amplitude oscillations, which weakens resonant characteristics.

581

582 Acknowledgement

The authors wish to express our appreciation for the support from the National Natural Science Foundation of China (Grant No. 52171325, 51679096). The second author is also sponsored by the joint scholarship form Lloyd's Register Foundation and China Scholarships Council, to which he is most grateful.

587

588 Data availability statement

589

The data that supports the findings of this study is available within the article.

590

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