

# 1 Preliminary results from the New Deformation multi-anvil 2 press at the Photon Factory: insight into the creep strength 3 of calcium silicate perovskite.

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5 Andrew R Thomson<sup>1</sup>, Y. Nishihara<sup>2</sup>, D. Yamazaki<sup>3</sup>, N. Tsujino<sup>3</sup>, Simon A Hunt<sup>4</sup>, Y. Tsubokawa<sup>5</sup>, K.  
6 Matsukage<sup>6</sup>, T. Yoshino<sup>3</sup>, T. Kubo<sup>5</sup>, David P Dobson<sup>1</sup>

7  
8 <sup>1</sup>Department of Earth Sciences, University College London, London, WC1E 6BT, United Kingdom

9 <sup>2</sup>Geodynamics Research Center, Ehime University, Matsuyama, 790-8577, Japan

10 <sup>3</sup>Institute for<sup>†</sup> Planetary Materials, Okayama University, Misasa, 682-0193, Japan

11 <sup>4</sup>Department of Materials, University of Manchester, Manchester, M1 3BB, United Kingdom

12 <sup>5</sup>Department of Earth and Planetary Sciences, Kyushu University, Nishi-ku, 819-0395, Japan

13 <sup>6</sup>Department of Natural and Environmental Science, Teikyo University of Science, Yamanashi, 409-  
14 0193, Japan

## 16 **Abstract.**

17 A D111 deformation multi-anvil press, which is a larger version of the Deformation T-cup, has  
18 been installed at beamline NE7A at PF-AR, KEK, Tsukuba, Japan. Using this apparatus,  
19 controlled deformation experiments can be performed by independently moving two  
20 opposite second-stage anvils in a Kawai-type 6/8 geometry. This allows both pure and simple  
21 shear experiments with sample strain rates of  $\sim 10^{-6} \text{ s}^{-1}$  to be conducted at pressure and  
22 temperature conditions up to at least 27 GPa and 1700 K. Here the capabilities of the D111  
23 press are demonstrated using experiments investigating the creep strength of calcium silicate  
24 perovskite at mantle conditions. Experiments performed at  $\sim 13 \text{ GPa}$  and 1150-1373K with  
25 quantitative stress and strain rate measurements have allowed preliminary evaluation of the  
26 creep strength of calcium silicate perovskite. Observations indicate that under dry and wet  
27 conditions samples possess grainsizes of between 0.5 and  $\sim 10 \mu\text{m}$ , and undergo deformation  
28 in a diffusion creep regime with an apparent activation energy of  $\sim 364 \text{ kJ mol}^{-1}$  and a stress  
29 exponent of 1.28. Qualitative comparison of preliminary results with the properties of mantle  
30 silicate minerals including bridgmanite, wadsleyite and dry olivine indicates that calcium  
31 silicate perovskite is very weak, such that it may strongly influence the geodynamics of the  
32 deep mantle especially in regions of subduction.

## 33 34 **Introduction.**

35 Compared to the other rocky planets, Earth is dynamic, with an active dynamo, volcanism,  
36 seismicity and repeated, continuous, cycling of material between the surface and deep  
37 interior for at least the last 2.5 billion years (Krusky et al., 2001). The plate-tectonic style of  
38 convection appears to be unique to the Earth and results in regions of dynamic complexity at  
39 the surface and the core-mantle boundary, the major thermal boundary layers of the mantle

40 system. Geophysical studies show a third region of complexity in the mid-mantle, associated  
41 with the stabilisation of silicate perovskite around 660 km depth. In this region, subducted  
42 slab material shows a wide range of complex behaviours, ranging from penetration into the  
43 lower mantle, through ponding around 1000-1200 km depth, to stagnation in the transition  
44 zone (van der Hilst, 1995). This tomographically-imaged complexity is accompanied by further  
45 evidence of basalt enrichment in the region around 660 km (Greux et al. 2019; Thomson et  
46 al., 2019), implying that subducted crustal mid-ocean-ridge-basalt (MORB) can mechanically  
47 decouple from the depleted, ultramafic components of the slab interior. The complex  
48 behaviour of the subducting slab is likely to be due to changes in density and, more  
49 importantly, viscosity of the slab and surrounding mantle as the  $Mg_2SiO_4$ -dominated upper  
50 mantle mineral assemblages transform into  $MgSiO_3$ -bridgmanite dominated assemblages in  
51 the lower mantle (e.g. Karato, 1997). The rheological behaviour of the crustal components of  
52 subducting slabs are further complicated in this region because of its more silica- and calcium-  
53 enriched chemistry compared with ultramafic lithologies, which results in a distinct bulk  
54 mineralogy in the transition zone and lower mantle variously containing components of  
55 stishovite,  $CaSiO_3$  perovskite, NAL phase and CF-phase (e.g. Perrillat et al., 2006).

56  
57 In order to understand this complexity and to accurately model the convective behaviour of  
58 the mantle it is necessary to measure the thermoelastic and rheological properties of the  
59 constituent rocks and minerals under the appropriate conditions of pressure, temperature  
60 and stress. There has therefore been considerable effort to develop apparatus to maintain  
61 simultaneous high pressure and temperature in macroscopic ( $\sim mm^3$ ) samples for extended  
62 durations and, recently, to modify these presses to allow controlled deformation of samples  
63 under mantle conditions. The most successful static large-volume high-pressure devices are  
64 multi-anvil presses where steel wedges transfer load from the press ram(s) to an inner  
65 arrangement of anvils composed of tungsten carbide or other, super-hard, materials (Kawai  
66 and Endo, 1970; Kawai et al., 1973; Shimomura et al., 1985; Ito et al., 2007; for a review of  
67 multi-anvil history see Liebermann, 2011). These inner anvils compress a ceramic pressure  
68 cell which itself contains an electrically conductive furnace, insulation materials, means of  
69 measuring temperature, and sample capsule. There is a very large stress gradient between  
70 the high-pressure region within the ceramic cell, which can be at several tens of gigapascals,  
71 and the air gap between the inner anvils and much effort has been invested in optimising the  
72 materials of the cell and gaskets, and the geometry of the press. Currently the highest  
73 pressures are attainable using an arrangement where an octahedral pressure cell is  
74 compressed by 8 hard inner (second-stage) anvils which pack together to form a cubic volume  
75 (figure 1 A, B). This cubic 'nest' is compressed by 6 (first-stage) steel wedges (the 6/8 multi-  
76 anvil arrangement) with either a 3-fold (111) or a 4-fold (100) axis aligned parallel to the  
77 direction of compression of the primary press ram. The last two decades have seen the  
78 development of deformation multi-anvil presses where one opposing pair of anvils can be  
79 advanced (or retracted) independently of the remaining anvils, applying an approximately axi-  
80 symmetric strain to the pressure medium and sample. The d-DIA geometry (Fig. 1C) applies

81 strain along the 4-fold axis of a cubic carbide anvil set in a single stage press (Wang et al.,  
82 2003) and has been combined with synchrotron radiation at several facilities (e.g. Nishiyama  
83 et al., 2008, Guignard and Crichton, 2015, Wang et al., 2019, Farmer et al., 2020). The single  
84 stage (6-anvil) DIA geometry is limited to about 10 GPa confining pressure, which can be  
85 increased in the 6-6 geometry using multi-staging coupled with anvil guides to reach  $\sim$  18 GPa  
86 (Nishiyama et al., 2008; Kawazoe et al., 2016). Alternatively, the d-DIA can be used with an  
87 internal 6-8 geometry cube-set to performed deformation experiments at conditions reaching  
88  $\sim$  25 GPa (Fig. 1D) (Tsujino et al., 2016). However, in the 6-8 implementation of d-DIA the  
89 deformation axis is co-axial to the (100) axis of the octahedral pressure cell (and hence  
90 centred on the gaskets, rather than through an anvil). This results in complex sample strain  
91 possibilities due to gasket relaxations along the compression axis. An alternative deformation  
92 press geometry (Fig. 1E, F), the deformation-T-cup, was developed over the last decade (Hunt  
93 et al., 2014, 2019; Hunt and Dobson, 2017). This is based on the Kawai-type 6/8 geometry and  
94 the deformation axis is oriented along the (111) axis, centred on a pair of opposed anvil faces.  
95 This geometry is capable of controlled deformation at sample pressures in excess of 23 GPa  
96 and, here, we report the implementation of this deformation geometry at beamline NE7A of  
97 the Photon Factory at KEK and demonstrate its capabilities using preliminary data collected  
98 on  $\text{CaSiO}_3$  perovskite samples.

99

## 100 The D111 Press on NE7A at KEK.

101 The deformation geometry employed in the D111 press is described elsewhere (Hunt et al.,  
102 2014) so here we will concentrate on details specific to this implementation. A cutaway  
103 schematic of the press tooling installed on beamline NE7A is shown in Figure 2A. The tooling  
104 is designed to be a compact single unit which can be replaced in the press with alternative  
105 tooling geometries. Oil-driven secondary actuators which control the uniaxial deformation of  
106 the cell are contained within the guide blocks of the tooling so the primary pressure  
107 generation is driven using a standard single-piston four-post press. This means that, if the  
108 secondary actuators are not moved during an experiment the system behaves identically to  
109 a traditional Kawai-type hydrostatic multi-anvil press. The implementation on beamline NE7A  
110 uses the existing 700 ton MAX-III press and is interchangeable for different tooling designs.  
111 In the Kawai geometry, each second-stage anvil experiences loads of up to 175 tons from the  
112 main ram. The differential actuators have a capacity of 314 tons each but only act on a single  
113 anvil – this excess load capacity in the differential actuators ensures that frictional losses can  
114 be overcome, and deformation is possible right up to the 700 ton maximum load of the press.  
115 The two deformation anvils are advanced by pumping oil into the secondary actuators. This  
116 shortens the octahedral pressure medium along its vertical (111) symmetry axis and the anvils  
117 in the equatorial plane dilate in response to the reduced component of the main-ram end  
118 load which they are supporting.

119

120 High-pressure cells and carbide tooling are constructed and loaded in the standard manner  
121 for 6/8 experiments, with the addition of hard components along the cell axis to transfer  
122 differential stress to the sample. This cubic nest of second-stage anvils and cell are loaded  
123 into the D111 tooling outside the press frame (Fig. 2B) with a (111) symmetry axis vertical.  
124 The first-stage Kawai-geometry wedges compress 6 of the 8 second-stage anvils but the two  
125 anvils which align along the vertical (111) axis (labelled (3) in Fig. 2A) are compressed by a  
126 hexagonal arrangement of pistons which communicate to the deformation actuators. The  
127 original hexagonal deformation pistons of Hunt et al. (2014) are split such that the hexagonal  
128 column which supports the deformation anvils is composed of three identical pieces, each  
129 occupying 120 degrees of rotation about the (111) symmetry axis (Hunt and Dobson, 2017).  
130 The front ends of these pieces are ground such that when installed they support the entire  
131 back faces of the second-stage carbide deformation anvils. This improves anvil performance  
132 over the original D-T-cup design (Hunt and Dobson, 2017). Similarly, to the deformation-DIA  
133 geometry the primary mode of deformation in the D111 geometry is axi-symmetric, resulting  
134 in a pure shear sample deformation mode. The axi-symmetric cell deformation can be  
135 transformed into simple shear deformation by placing the sample between pistons whose  
136 ends are cut at 45 degrees (Karato and Rubie, 1997).

137

138 In the D111 implementation at beamline NE7A X-rays traverse the second-stage anvil set  
139 perpendicular to the vertical mirror plane of the second-stage anvils and octahedral pressure  
140 cell (Fig. 1F) passing through two diagonally opposite gaskets. The pyrophyllite gaskets  
141 through which X-rays pass are replaced by a low-absorbing, typically B-dominated, gasket  
142 material. Careful alignment of the first stage anvil wedges within the split confining ring is  
143 required to ensure that the X-ray cut-outs maintain the correct geometry with respect to the  
144 X-ray beam (Fig. 2B), which can also be adjusted by rotating the entire MAX-III load frame.  
145 The beamline delivers a photon flux of  $10^8\text{-}10^9 \text{ mm}^{-2}\text{s}^{-1}$  over a 3 mm high by 80 mm wide  
146 beam, measured at 20 m from the source. The photon energy range is 10-140 keV and the  
147 beamline can be operated in white beam or monochromatic (10-60 keV) modes. In order to  
148 perform successful rheological experiments either X-ray transparent anvils (e.g. PCD or cBN)  
149 or carbide anvils with suitable slot/cone cut-outs are used in place of the downstream second  
150 stage anvils to allow sufficient radiographic and diffraction data collection (Dobson et al.,  
151 2012; Irfune et al., 1992).

152

153 Stress-strain data on NE7A are collected by combined radiography and diffraction using a  
154 monochromatic incident X-ray beam and angle-dispersive diffraction. This is generated by  
155 passing the raw synchrotron beam through a two-crystal Si(111) monochromator to achieve  
156 an incident beam with monochromatic energy of 50-60 keV. The transmitted X-ray beam is  
157 typically imaged using a YAG(Ce) or GAGG(Ce) scintillator crystal combined with a CCD or  
158 CMOS camera positioned downstream of the sample on motorized linear translation stages.  
159 Highly absorbent foils (typically Au, Pt or Re) are placed on both ends of samples as strain  
160 markers which show up in the radiographic images, allowing changes in the sample length

161 (and strain rate) to be monitored throughout deformation experiments. Radiographic images  
162 are normally 0.5 – 5 s in duration, depending on the absorption properties of the sample  
163 assembly. Their resolution depends on the exact camera model used, however is typically  
164 around 1  $\mu\text{m}$  which is sufficient to allow strains of  $10^{-3}$  to be monitored in millimetre sized  
165 samples when an appropriate cross-correlation algorithm is employed (e.g. Li et al., 2003).  
166 Diffraction patterns are collected using a Dexela 2923 area detector, whose position is  
167 calibrated using a certified standard material ( $\text{CeO}_2$  in this study). Individual diffraction  
168 patterns are collected from an illuminated sample area defined using collimation slits placed  
169 upstream of the sample position and typically have durations of 1-4 minutes depending on  
170 sample characteristics. During experiments the lattice strain of each sample is determined  
171 from the azimuthal distortions of the Debye-Scherrer rings from the polycrystalline samples.  
172 Lattice strain is subsequently converted into a stress measurement by utilising the elastic  
173 moduli of the sample material, which are required to be known prior to experiments. This  
174 experimental approach has been widely applied in d-DIA and 6/8 geometries at global  
175 synchrotron sources and achieves stress resolution, depending on the elastic properties of  
176 the sample, of  $\sim 100$  MPa for most silicate minerals. Each data collection cycle consists of  
177 sequential X-ray radiographic images followed by X-ray diffraction pattern collections,  
178 between which both the diffraction slits and CCD/CMOS imaging camera are moved into/out  
179 of the X-ray beam path using motorized linear translation stages. The total time for each data  
180 collection cycle can vary between approximately 2 and 8 minutes depending on the required  
181 radiograph and diffraction times, and whether one or two samples are being monitored  
182 throughout deformation. A schematic of the experimental setup of the D111 on NE7A is  
183 provided in figure 3.

184

185 The D111 setup on NE7A has so far been used to perform deformation experiments using  
186 various sized multi-anvil assemblies at primary ram loads up to  $\sim 500$  tonf coupled with 2, 3  
187 or 5 mm truncations. Samples investigated to date have included hcp iron, bridgmanite,  
188 ringwoodite and  $\text{CaSiO}_3$  perovskite (Ca-Pv) which have been studied at a range of pressure  
189 and temperature ( $PT$ ) conditions extending between 12 – 27 GPa and 650 – 1700 K with strain  
190 rates of  $1 \times 10^{-6}$  –  $1.1 \times 10^{-4}$   $\text{s}^{-1}$  (figure 4, after Nishihara et al., 2020). In the subsequent  
191 sections of this paper we describe initial experiments performed to investigate the rheological  
192 properties of Ca-Pv. These provide a demonstration of the current capabilities and examples  
193 of data that can be achieved using the existing D111 system on NE7A.

194

## 195 The rheological behaviour of Ca-Pv

196 Ca-Pv is one of the major mineralogical constituents of Earth's deep mantle and is  
197 thermodynamically stable at pressures from  $\sim 10$  GPa to the core-mantle boundary. After  
198 entering the phase assemblages of subducting lithologies at  $\sim 19$ -21 GPa (Holland et al., 2013)  
199 it constitutes  $\sim 5$  to  $\sim 30$  wt.% of depleted ultramafic to mafic lower mantle assemblages  
200 respectively (e.g. Kesson et al., 1998; Perrillat et al., 2006). At these abundances, especially in  
201 subducting mafic assemblages, Ca-Pv is sufficiently abundant that it might well form an

202 interconnected network of grains (Handy et al., 1994). In this situation, depending on the  
203 rheological properties of Ca-Pv, it may dominate the strength of subducting mafic lithologies  
204 and potentially be important in controlling on the geodynamics of subduction and slab  
205 delamination throughout the transition zone and lower mantle.

206

207 Studies of Ca-Pv are complicated by the inability to recover samples of it from synthesis to  
208 ambient conditions, as it spontaneously undergoes amorphization during decompression at  
209 room temperature (e.g. Liu and Ringwood, 1975, Wang et al., 1994). This feature of Ca-Pv  
210 means that many of its physical properties, including its elastic and rheological properties, are  
211 poorly understood and can only reasonably be assessed using *in-situ* experiments where it  
212 can be synthesised and investigated in a single experimental run. Synchrotron-based large  
213 volume press experiments (e.g. Wang et al., 1994, Greaux et al., 2019, Thomson et al., 2019)  
214 provide a suitable approach which can achieve this, and here we present our initial  
215 experimental results to constrain the viscous strength of Ca-Pv at *PT* conditions inside its  
216 stability field using the KEK D111 press.

217

### 218 ***Experimental details.***

219 As the elastic moduli of Ca-Pv, which are required for experimental stress measurements, are  
220 poorly known two experimental setups were used in this study. Whilst a solitary sample of  
221 Ca-Pv was studied in one experiment, 2 further experiments utilised a deformation column  
222 containing stacked samples of olivine and Ca-Pv. Starting materials for all deformation  
223 experiments consisted of sintered cylinders of synthetic olivine and wollastonite. Cylinders of  
224 fine-grained powder, ground to  $\sim 5 \mu\text{m}$  grainsize using an agate mortar, were fabricated by  
225 pressing using a pellet die prior to sintering in a 1-atmosphere furnace. In two experiments  
226 the 17.5 wt.% of the wollastonite sample was replaced with a 1:1 mixture of  $\text{Ca}(\text{OH})_2 + \text{SiO}_2$   
227 glass, in order to provide a small quantity of water ( $\sim 2 \text{ wt.\% H}_2\text{O}$  in the bulk composition) at  
228 experimental conditions to promote the kinetics of Ca-Pv formation (e.g. Gasparik et al.,  
229 1994). In all experiments the samples were deformed between two fully dense  $\text{Al}_2\text{O}_3$  pistons  
230 which had  $10 \mu\text{m}$  thick Pt marker foils placed at either end of each sample to allow sample  
231 strain to be monitored. Deformation columns were housed within multi-anvil assemblies  
232 consisting of a Co-doped  $\text{MgO}$  octahedron of 7mm edge length, a  $\text{TiB}_2:\text{BN}$  ceramic furnace  
233 and  $\text{MgO}$  inner parts. The pyrophyllite gaskets and ceramic components within the  
234 experimental assembly along the X-ray beam path were replaced with rods of low-density  
235 boron epoxy to maximise transmission for radiographic imaging and diffraction. Type-D  
236 thermocouples with junctions placed adjacent to the samples were used to monitor  
237 experimental temperatures.

238

239 Experimental assemblies were compressed using secondary anvils with 3mm truncations for  
240 pressure generation. 6 x 26 mm TF05 carbide anvils were combined with two X-ray  
241 transparent composite anvils placed downstream of the sample to allow collection of angle  
242 dispersive diffraction data. These composite anvils consisted of 14mm PCD cubes backed by

243 tungsten carbide spacers which bring the composite cube size up to the 26 mm size of the  
244 remaining second-stage anvils. The backing spacers are chamfered to provide a solid cone  
245 angle of 20° from the sample position permitting 360° azimuthal diffraction to a  $2\theta$  angle of  
246  $\sim 10^\circ$  (figure 5). Pressure was applied by gradually increasing the primary ram's oil pressure  
247 to 190 ton force over 2-3 hours, corresponding to  $\sim 15\text{-}16$  GPa as determined using the shift  
248 of X-ray diffraction peaks from the Pt marker foils (Matsui et al., 2009). The sample was then  
249 gradually heated by applying power to the  $\text{TiB}_2\text{:BN}$  furnace at a rate of between 20-100  
250 K/minute until the target temperature (1150 – 1373K) was achieved. During this heating cycle  
251 the wollastonite sample was observed to undergo transformation to Ca-Pv at  $\sim 1000$  K,  
252 indicated by an abrupt shortening of the sample (due to large volume change from  
253 wollastonite to perovskite structure) and the identification of diffraction rings corresponding  
254 to Ca-Pv in subsequent diffraction patterns. After heating all experiments were observed to  
255 be at a pressure of 12-13 GPa, which was maintained throughout deformation.

256

257 After initial heating the target *PT* conditions were maintained for a minimum of 30 minutes  
258 to anneal the samples, and until no diffraction evidence of remnant low pressure  $\text{CaSiO}_3$   
259 phases was present. Prior to deformation the differential actuators were pre-loaded to an oil  
260 pressure of 3 MPa. Sample deformation was commenced by driving both differential  
261 actuators, which are controlled by linear displacement transducers, at a fixed rate of 0.5 – 10  
262  $\mu\text{m min}^{-1}$  such that the sample was shortened along an axis parallel to the furnace and the  
263 stress-strain data collection loop was commenced. We have observed that after commencing  
264 differential ram motion that their pre-load increases to approximately 25% of the main ram's  
265 load before motion and sample deformation commences (Nishihara et al., 2020). For these  
266 experiments radiographic images of 0.5 – 2 s duration with resolutions of  $\sim 1 \mu\text{m}$  were  
267 coupled with 180 s sample diffraction patterns using 200x200  $\mu\text{m}$  illumination slits. Diffraction  
268 counting times were reduced to 60s when differential actuator velocities of  $10 \mu\text{m min}^{-1}$  were  
269 being used to ensure sufficient data were collected at high strain rates. Data collections at  
270 constant actuator velocities were repeated for approximately 1 hour to ensure both sample  
271 strain rate and stress had reached steady state equilibrium. Multiple strain rates, controlled  
272 by three or four differential actuator velocities, were studied in each experiment. All  
273 experiments were performed at a single sample temperature of 1150 – 1373K. Following  
274 completion of data collection at the final experimental strain rate the sample temperature  
275 was quenched by turning off the furnace power and the differential actuators were stopped.  
276 The sample was then gradually decompressed at room temperature whilst the actuators were  
277 also decompressed over the same time duration in attempt to minimise breakage of the PCD  
278 anvils.

279

### 280 **Stress-strain data processing**

281 X-ray radiographs were sequentially processed using correlative image processing to  
282 determine the relative length change throughout each experiment (e.g. Hunt et al., 2019).

283 Changes in sample length were subsequently converted into the strain ( $\varepsilon = \frac{l-l_0}{l_0}$ ) experienced  
 284 by each sample as a function of experimental time. Examples of strain measurement data are  
 285 provided in figure 6. Strain rates ( $\dot{\varepsilon}$  in  $\text{s}^{-1}$ ) were calculated using these strain measurements  
 286 after steady state was achieved at each subsequent differential actuator velocity. Observed  
 287 strain rates range between  $3 \times 10^{-6}$  and  $2 \times 10^{-4} \text{ s}^{-1}$ .

288

289 X-ray diffraction data were initially processed using a combination of IPAnalyzer and  
 290 PDIndexer (Seto et al., 2010), as available at NE7A, to allow evaluation of experiments in real  
 291 time. Latterly, the diffraction datasets were processed using the newly developed *Continuous*  
 292 *Peak Fit* package (Hunt and Fenech, *in prep*, Chen et al., 2021). This package implements a  
 293 new approach to fitting 2D diffraction (or any other continuous 2D data) by assuming that  
 294 each diffraction peak, which is normally described in 1D data as a peak function (e.g. a  
 295 pseudo-Voigt or Gaussian), varies smoothly as a function of azimuth. This description is  
 296 achieved by fitting each peak parameter (d-spacing, amplitude, half-width etc.) as a Fourier  
 297 series in azimuthal space. In this case the d-spacing of a single Debye-Scherrer ring was  
 298 described as:

299

300 
$$d^{hkl} = a_0^{hkl} + a_1^{hkl} \sin \psi + b_1^{hkl} \cos \psi + a_2^{hkl} \sin 2\psi + b_2^{hkl} \cos 2\psi \quad (\text{eq.1})$$

301

302 where  $a_0^{hkl}$  is the mean d-spacing of the ring, the two first order terms ( $a_1^{hkl}$  and  $b_1^{hkl}$ )  
 303 represent the displacement of the centre of the diffraction ring relative to the calibration  
 304 centre and the second order terms ( $a_2^{hkl}$  and  $b_2^{hkl}$ ) represent the ellipticity of the diffraction  
 305 ring and contain the information corresponding to the sample's differential strain. This model  
 306 is fitted sequentially to each of the Debye-Scherrer rings of interest that are not significantly  
 307 overlapped by peaks from other cell components, in the 2D diffraction pattern. In this case  
 308 the 110, 200, 211 and 220 peaks of Ca-Pv and the 131, 222, 240, 130, 021, 122 and 140 peaks  
 309 of olivine samples were fitted using continuous pseudo-Voigt functions, although not all fitted  
 310 peaks were used for stress evaluations for every experiment. *Continuous Peak Fit* relies on  
 311 knowledge of the sample-detector geometry as calibrated using an ambient diffraction  
 312 collection from a  $\text{CeO}_2$  standard processed using *Dioptas* (Prescher et al., 2015). The fitting  
 313 procedure directly provides the lattice strain indicated by each peak accompanied by an  
 314 uncertainty based on fitting statistics from input of the unprocessed diffraction images in one  
 315 computational process. A typical example of a fitted Deybe-Scherrer ring for the Ca-Pv 200 at  
 316  $\sim 13 \text{ GPa}$ ,  $1373 \text{ K}$  is given in figure 7.

317

318 The output models from *Continuous Peak Fit* provide the deviatoric lattice strain and the  
 319 minimum/maximum d-spacings for each reflection as a function of azimuth, which are  
 320 evaluated from the second order  $a_2^{hkl}$  and  $b_2^{hkl}$  Fourier coefficients and trigonometric  
 321 relations. These parameters can then be used to calculate the differential stress following the

322 approach of Singh et al. (1998), where the relationship between axial stress, lattice strain and  
323 azimuthal variations in the peak position is:

324

325 
$$d_{hkl}(\psi) = d_{hkl}^0 \left[ 1 + (1 - 3\cos^2\psi) \frac{\sigma}{6(G_{hkl})} \right] \quad (\text{eq. 2})$$

326

327 In equation 2  $d_{hkl}$  is the *d-spacing* measured as a function of azimuthal angle  $\psi$ ,  $d_{hkl}^0$  is the *d-spacing*  
328 under hydrostatic pressure,  $G_{hkl}$  is the appropriate shear modulus for a given  $hkl$   
329 orientation and  $\sigma$  is the axial differential stress for that  $hkl$ .

330

331 An approximate evaluation of the differential stress in each sample has been calculated using  
332 the maximum and minimum *d-spacing* from fitted models of each diffraction peak combined  
333 with either (i) an isotropic shear modulus for olivine or (ii) an appropriately adjusted elastic  
334 tensor for Ca-Pv (following the relations in Singh et al., 1998). This approach neglects the  
335 effects of crystallographic orientations and elastic anisotropy in olivine samples, but sufficient  
336 diffraction peaks are observed that this shouldn't add significant uncertainty to stress  
337 estimates. As there are fewer diffraction peaks from Ca-Pv available, and because Ca-Pv has  
338 large elastic anisotropy (Kawai and Tsuchiya, 2015), orientation adjusted elastic moduli were  
339 used in eq. 2. Throughout stress estimations performed in this paper it was assumed that the  
340 isotropic shear modulus of olivine at run conditions ( $\sim 13$  GPa and  $1150 - 1373$  K) was  $90 \pm$   
341 10 GPa, based on recent experimental measurements (Mao et al., 2015). An elastic tensor for  
342 Ca-Pv providing values of  $c_{11}$ ,  $c_{12}$  and  $c_{44}$  (of 347.9, 158.7 and 179.9 GPa respectively) from the  
343 molecular dynamics *ab initio* calculations of Kawai & Tsuchiya (2015) was used to derive  
344 differential stresses in perovskite samples. We note that the isotropic adiabatic shear  
345 modulus of Ca-Pv reported by Kawai & Tsuchiya (2015) of  $\sim 155$  GPa is significantly larger than  
346 those determined in recent ultrasonic interferometry experiments by Greux et al. (2019) and  
347 Thomson et al. (2019) which are  $\sim 130$  and  $\sim 105$  GPa respectively. Thus, the true adiabatic  
348 shear modulus of Ca-Pv remains unclear, and the results from Kawai & Tsuchiya (2015) are  
349 preferred here because this is the only study to report full  $c_{ij}$ 's required to calculate  
350 orientation adjusted values of the shear modulus. However, due to these discrepancies, we  
351 caution that the differential stresses derived in this study are based on the largest recent  
352 estimate of Ca-Pv's shear modulus and may overestimate the true values of differential stress  
353 in these experiments by more than 25%. Uncertainties caused by errors in  $G_{hkl}$  of Ca-Pv were  
354 assumed to be  $\pm 25\%$ , such that estimated stresses incorporate this source of uncertainty,  
355 however in several cases the fitting uncertainties dominate. After calculating the apparent  
356 stress from each fitted diffraction ring an average differential stress for the olivine and/or Ca-  
357 Pv samples was calculated as a weighted mean of all observed stresses. The reported  
358 differential stress at each strain rate was calculated as the mean of these weighted averages  
359 from each data collection cycle, with uncertainty estimated as two standard deviations.  
360 Examples of differential stress measurements are provided in figure 8.

361

362 **Results.**

363 A summary of conditions, starting materials, measured strain rates and estimated differential  
364 stresses from all experiments is provided in Table 1. In all experiments the wollastonite  
365 sample material was observed to very rapidly transform into Ca-Pv structure. In the dry  
366 experiment diffraction peaks corresponding to Ca-Pv possessed sharp, complete and non-  
367 spotty diffraction rings suggesting the Ca-Pv sample had an average grainsize that was large  
368 enough to reduce peak broadening, but still small enough that a very large number of grain  
369 orientations is being sampled during diffraction. Although this cannot be verified upon  
370 recovery, it is assumed samples possess a grainsize between  $0.5 - 5 \mu\text{m}$ , somewhat smaller  
371 than those of olivine starting material which were  $10-15 \mu\text{m}$ . In wet experiments diffraction  
372 rings from the Ca-Pv were pseudo-continuous, but have a slightly spotty texture implying a  
373 larger sample grainsize. Again this cannot be rigorously quantified, but we suggest a similar  
374 grainsize to the olivine samples (which have similarly spotty diffraction rings) of  $\sim 10 \mu\text{m}$ .

375

376 In the single experiment performed on nominally dry starting materials strain was observed  
377 to preferentially partition into the Ca-Pv sample relative to olivine, with strain rates in the dry  
378 Ca-Pv sample  $1.9 - 5.4$  times higher than those of the dry olivine sample. Additionally, despite  
379 being simultaneously deformed within the same column, the differential stress appears to be  
380 significantly lower in the Ca-Pv than olivine in this experiment. As observed in previous  
381 studies, dry olivine exhibits a creep strength of  $1-2 \text{ GPa}$  at strain rates of approximately  $1-2 \times$   
382  $10^{-5} \text{ s}^{-1}$  (e.g. Li et al., 2006, Kawazoe et al., 2009). In contrast, the simultaneously deforming  
383 Ca-Pv sample in our experiments has an apparent creep strength that appears to be an order  
384 of magnitude smaller at similar strain rates. This is unusual, as it is normally expected that all  
385 samples in a single deforming column should experience the same differential stress, which  
386 is clearly not the case in this experiment. In the case where two samples being simultaneously  
387 deformed have very different creep strength's it is plausible that the flow in the weaker phase  
388 is sufficiently rapid that deformation of the surrounding pressure medium becomes rate-  
389 limiting for this sample. That would then cause the differential stress in the weaker sample  
390 to be smaller than that in the stronger sample as the pressure medium would be confining  
391 the weak sample more strongly. Assuming this is indeed the situation this experiment  
392 suggests Ca-Pv is significantly weaker than dry olivine, as indicated by observations of higher  
393 strain rate at lower differential stress within the Ca-Pv sample. We note that the differential  
394 stress for Ca-Pv in this experiment is derived using the weighted mean stress from 2 Debye-  
395 Scherrer rings, as opposed to 5 for olivine samples. In combination with the large uncertainty  
396 for Ca-Pv's shear modulus the differential stress estimates for Ca-Pv are relatively larger than  
397 those for olivine. Even accounting for this, however, the Ca-Pv appears very significantly  
398 weaker than olivine under dry conditions.

399

400 Two further experiments were performed using Ca-Pv starting materials containing  $\text{H}_2\text{O}$   
401 provided by 2 wt.% of the starting mix being replaced by a mixture of  $\text{Ca}(\text{OH})_2$  and  $\text{SiO}_2$  glass.  
402 This means that these latter deformation experiments are effectively performed in a hydrous

403 environment. Samples of Ca-Pv and olivine simultaneously deformed under hydrous  
404 conditions at  $\sim 13$  GPa and 1273 K have more comparable strengths. Strain rates in the  
405 hydrous olivine sample were observed to be 1.7 – 2.3 times higher than those for Ca-Pv, and  
406 differential stress appears to be similar in both samples at strain rates of  $2-4 \times 10^{-5} \text{ s}^{-1}$ , with  
407 olivine becoming relatively weaker at lower strain rates. The final experiment was performed  
408 on a solitary sample of Ca-Pv at a temperature of 1373 K and under hydrous conditions. This  
409 solitary Ca-Pv experiment was performed as the strain rate of Ca-Pv samples in previous  
410 experiments had been high, and including only Ca-Pv permitted a longer initial sample length.  
411 At equivalent differential stress increasing temperature weakens the Ca-Pv sample, which  
412 was observed to strain faster than at 1273K (figure 9).

413

#### 414 **Discussion.**

415 The presented experiments and data analysis approach using the *Continuous Peak Fit*  
416 package, as described above, demonstrate the capabilities of the D111 at KEK NE7A for  
417 deformation experiments at mantle conditions. Experiments are reported with strain rates as  
418 low as  $\sim 3-7 \times 10^{-6} \text{ s}^{-1}$  with differential stresses of  $\sim 20 \pm 10$  MPa in hydrous olivine samples.  
419 Equally, anhydrous olivine samples deformed at similar strain rates were observed to support  
420 differential stress of  $1300 \pm 70$  MPa at a strain rate of  $\sim 5 \times 10^{-6} \text{ s}^{-1}$ . These observations for  
421 both hydrous and anhydrous samples overlap published rheological properties for wet and  
422 dry olivine respectively (e.g. Ohuchi et al., 2017, Kawazoe et al., 2009), verifying the  
423 capabilities of the D111 to perform rheological experiments similar to other devices available  
424 (e.g. d-DIA and RDA) at synchrotron beamlines worldwide. The apparent slope of data for  
425 strain rate vs. differential stress suggests that hydrous samples of olivine may be deforming  
426 in the diffusion creep regime ( $n < 1$ ) whilst anhydrous samples are deforming in dislocation  
427 creep ( $n > 3$ ) in the current study (figure 9, equation 3).

428

429 Observations on Ca-Pv samples, although preliminary, allow some initial observations of its  
430 rheological properties at mantle *PT* conditions. Across all three experiments, in both dry and  
431 hydrous sample conditions, the maximum average differential stress observed in Ca-Pv  
432 samples was  $430 \pm 129$  MPa. Whilst these stress estimates are subject to large errors in part  
433 due to the uncertainty in the elastic tensor of Ca-Pv, it is unambiguous that they are low  
434 compared with other high-pressure silicate phases at equivalent strain rates. In the anhydrous  
435 experiment it appeared, comparing both differential stresses and observed sample strain  
436 rates, that Ca-Pv may be more than 1 order of magnitude weaker than coexisting olivine.  
437 Taken absolutely at face value these observations point to Ca-Pv being substantially weaker  
438 than dry olivine (figure 9). However, it is noted that Ca-Pv samples are synthesised *in-situ* and  
439 their grainsize is not known accurately. Whilst the diffraction characteristics described above  
440 imply Ca-Pv samples probably have a grainsize of  $0.5-5 \mu\text{m}$  which is smaller than that of the  
441 olivine starting material, and is potentially sufficiently small to make it anomalously weak.  
442 Since the spontaneous amorphization of Ca-Pv during decompression prevents a rigorous  
443 grainsize measurement this could not be verified, and it was in order to try and study Ca-Pv

444 samples with larger average grainsizes that subsequent experiments were performed under  
445 hydrous conditions. Whilst the slight spottiness of Ca-Pv diffraction rings in hydrous  
446 conditions suggested the success of this approach in creating coarser perovskite samples, it  
447 also induced a significant hydrolytic weakening in coexisting olivine (e.g. Mei and Kohlstedt,  
448 2002a, 2002b). However, the presence of hydrogen did not appear to weaken Ca-Pv in a  
449 similar manner as hydrous Ca-Pv deforming at 1273K (123 K above the dry experiment)  
450 appeared to be stronger than that under dry conditions. We assume this increase in strength  
451 is the expression of increased sample grainsize. The strength of Ca-Pv under hydrous  
452 conditions did reduce with temperature increasing from 1273 to 1373 K, as is expected. A  
453 brief inspection of the slope of data for all Ca-Pv sample in figure 9 suggests in all three  
454 experiments Ca-Pv was deforming in a diffusion creep regime at run conditions.

455

456 In order to consider this further the strain rate vs. stress data for Ca-Pv were fitted to a  
457 thermally activated creep flow law of the form:

458

$$459 \dot{\varepsilon} = A \frac{\sigma^n}{d^m} \exp\left(-\frac{Q}{RT}\right) \quad (eq. 3)$$

460

461 Where  $A$  is the constant of proportionality,  $n$  is the dimensionless stress dependence,  $d$  is the  
462 grainsize and  $m$  is the dimensionless grainsize dependence,  $Q$  is the activation energy,  $R$  is the  
463 universal gas constant and  $T$  is the temperature. By utilising a flow law of this form we are  
464 inherently assuming that the presence (and concentration) of water has no effect on the  
465 creep strength of Ca-Pv. Whilst this is a significant, and unjustified, assumption our qualitative  
466 observations all suggest Ca-Pv is relatively weak compared with other silicates irrespective of  
467 the presence or lack of water in our experiments, thus it is arguably not the most significant  
468 component in controlling Ca-Pv's creep strength. Additionally, by making this assumption  
469 estimates for other flow law parameters can be obtained. Finally, in order to fit the data for  
470 Ca-Pv we assumed that wet experiments had a grainsize of 10  $\mu\text{m}$  and that the grainsize  
471 dependence of Ca-Pv's creep is fixed at  $m = 2$ , that is, we assume Nabarro-Herring creep.  
472 Making these assumptions and performing a weighted regression we obtain values of  $Q$  and  
473  $n$  of 364  $\text{kJ mol}^{-1}$  and 1.28 respectively, with an inferred grainsize in the dry experiment of 0.6  
474  $\mu\text{m}$ . If we assume Coble creep ( $m=3$ ) the dry grainsize changes to 0.7  $\mu\text{m}$ . This predicted  
475 activation energy is entirely dependent on data from the two wet experiments and is not  
476 strongly influenced by our assumptions about the effect of water on creep strength or the  
477 exact grainsize in the experiments. Additionally, an activation energy of 364  $\text{kJ mol}^{-1}$  is very  
478 similar to the activation energy for Si diffusion in bridgmanite ( $\sim 330\text{--}350 \text{ kJ mol}^{-1}$ , Dobson et  
479 al., 2008, Yamazaki et al., 2000) and as such appears both reasonable and fairly robust. This  
480 implies the fitted value for  $n$ , of 1.28, and the relative grainsizes of wet/dry experiments are  
481 also likely to be reliable since the exact grainsizes are effectively an adjustable parameter,  
482 such that we conclude Ca-Pv in these experiments is deforming in a diffusion creep regime.

483

484 Irrespective of Ca-Pv's deformation regime in experiments here, comparison with stress-  
485 strain data from similar experiments allows a direct comparison of its strength with additional  
486 mantle silicates. Ringwoodite samples deformed using the d-DIA at  $\sim$  17 GPa and 1300-1700  
487 K sustain similar differential stress (130 – 560 MPa) at strain rates of  $10^{-5}$  s $^{-1}$  (figure 9, Kawazoe  
488 et al., 2016). This suggests that Ca-Pv and ringwoodite possess broadly similar rheological  
489 properties. Comparisons with data for wadsleyite (Kawazoe et al., 2010, Hustoft et al., 2013)  
490 and/or bridgmanite (Girard et al., 2016) samples suggests Ca-Pv is more than an order of  
491 magnitude weaker than either of these materials at the strain rates probed in this study  
492 (figure 9). Such comparisons only provide a qualitative understanding of relative strengths of  
493 mantle phases, but suggest that Ca-Pv may be capable of inducing rheological contrasts at  
494 deep Earth conditions. During subduction, the similar properties of Ca-Pv and ringwoodite  
495 might suggest that basaltic and harzburgitic slab assemblages retain similar strengths  
496 throughout subduction within the upper mantle and transition zone. However, after entry to  
497 the lower mantle the rheology of these lithologies may significantly diverge. The rheological  
498 behaviour of subducting basalts, which contain up to 30 vol.% Ca-Pv (Perrillat et al., 2006),  
499 may be controlled by interconnected grains of this phase whilst harzburgite assemblages  
500 contain  $>$  90% bridgmanite (Ishii et al., 2019). In this situation the strength contrast of Ca-Pv  
501 and bridgmanite may cause downwelling slabs to delaminate and could promote slab  
502 stagnation in the upper/lower mantle boundary region (e.g. Fukao et al., 2013). Additionally,  
503 in more fertile ultramafic assemblage throughout the lower mantle, both Ca-Pv and MgO may  
504 act as weak phases coexisting with bridgmanite and together may constitute  $>$  20 vol.% of  
505 phase assemblages (Perrillat et al., 2006). If these grains of Ca-Pv and MgO are sufficient to  
506 generate an interconnected network within a bridgmanite matrix this will allow strain  
507 partitioning into these phases and cause an overall weakening of peridotitic assemblages in  
508 the lower mantle. Such rheological contrasts between depleted and fertile components of an  
509 ultramafic lower mantle assemblage may allow generation of 3-dimensionally distributed  
510 domains of rigid materials (e.g. BEAMs, Ballmer et al., 2017). Additional studies of the  
511 rheological properties of Ca-Pv in relation to those of lower mantle materials are required to  
512 further investigate these possibilities.

513

#### 514 **Conclusions.**

515 A D111 deformation multi-anvil press has been successfully installed at beamline NE7A of KEK  
516 and utilised to performed deformation experiments at controlled strain rates of  $10^{-6}$  to  $10^{-4}$  s $^{-1}$  at mantle pressure and temperature conditions. In this study we have demonstrated the  
517 capabilities of the D111 geometry using controlled strain rate experiments of Ca-Pv and  
518 olivine samples under both wet and dry conditions with sample strain rates between  $3 \times 10^{-6}$   
519 s $^{-1}$  and  $2 \times 10^{-4}$  s $^{-1}$  occurring in response to differential stresses of  $\sim$  20 to 1760 MPa. Preliminary  
520 data suggest that Ca-Pv is up to 1 order of magnitude weaker compared with other deep  
521 mantle silicate minerals including olivine, wadsleyite and bridgmanite and may strongly  
522 influence the geodynamics of the Earth's deep mantle.

524

525 The stability of the Kawai 6/8 geometry, which forms the basis of the D111 deformation press,  
526 means that *PT* conditions at controlled strain rates may be extended significantly beyond  
527 those achievable in other existing deformation geometries, such as the d-DIA and Rotational  
528 Drickamer. To date experiments have been performed at conditions up to ~ 27 GPa and 1700  
529 K, to investigate the creep strength of Earth-forming materials including hcp-structured iron,  
530 ringwoodite and bridgemanite (Nishihara et al., 2020). Further developments, including use of  
531 harder anvil materials (e.g. Yamazaki et al., 2019) and new X-ray transparent ceramic  
532 components (e.g. Xie et al., 2020a, 2020b, Xu et al., 2020) should allow additional expansion  
533 of the accessible *PT* conditions using this deformation geometry.

534

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751 **Tables.**752 **Table 1:** Summary of experimental run conditions and results from deformation

expt	P (GPa)	T (K)	starting materials	Sample hkl's used for stress	Deformation velocity ( $\mu\text{m min}^{-1}$ )	$\dot{\varepsilon}$ ( $\text{s}^{-1}$ )	$\pm$	$\sigma$ (MPa)	$\pm$	
A (dry)	13	1150	CaSiO <sub>3</sub>	Ca-Pv 200, 110	4	$1.91 \times 10^{-5}$	$4.48 \times 10^{-5}$	116	24	
					1	$2.51 \times 10^{-5}$	$1.83 \times 10^{-5}$	109	27	
					10	$1.83 \times 10^{-4}$	$8.12 \times 10^{-5}$	260	99	
	(Mg <sub>1.8</sub> Fe <sub>0.2</sub> )SiO <sub>4</sub>		olivine 021, 122, 130, 140, 222		4	$1.00 \times 10^{-5}$	$1.18 \times 10^{-5}$	1480	400	
					1	$4.65 \times 10^{-6}$	$5.8 \times 10^{-6}$	1300	70	
					10	$4.87 \times 10^{-5}$	$1.93 \times 10^{-5}$	1760	240	
B (wet)	13	1273	CaSiO <sub>3</sub> + 2wt.% H <sub>2</sub> O	Ca-Pv 200, 110, 211	4	$2.54 \times 10^{-5}$	$3.1 \times 10^{-6}$	430	129	
					1	$7.72 \times 10^{-6}$	$2.4 \times 10^{-6}$	164	23	
					0.5	$3.28 \times 10^{-6}$	$4.3 \times 10^{-6}$	132	25	
	Mg <sub>2</sub> SiO <sub>4</sub>		olivine 131, 222, 130, 021, 122, 140		4	$4.27 \times 10^{-5}$	$1.2 \times 10^{-6}$	396	44	
					1	$1.58 \times 10^{-5}$	$1.1 \times 10^{-6}$	92	25	
					0.5	$7.67 \times 10^{-6}$	$8.6 \times 10^{-7}$	19	11	
C (wet)	13	1373	CaSiO <sub>3</sub> + 2wt.% H <sub>2</sub> O	Ca-Pv 200, 110, 220	4	$6.42 \times 10^{-5}$	$9.2 \times 10^{-6}$	91	79	
					1	$2.04 \times 10^{-5}$	$1.7 \times 10^{-6}$	52	23	
					0.5	$9.98 \times 10^{-6}$	$1.3 \times 10^{-6}$	68	13	
					10	$1.73 \times 10^{-4}$	$1.02 \times 10^{-5}$	316	177	

753

754 **Figure captions.**

755 **Figure 1:** Schematic illustrations showing the geometries, hydrostatic compression  
 756 directions (white arrows) and differential deformation (black arrows) of various high-  
 757 pressure experimental apparatus. The (a) DIA 6/8 and (b) Kawai 6/8 (which may also be  
 758 named the “111 6/8”) geometries both utilise 6 primary anvils in combination with 8  
 759 secondary truncated cubic anvils and an octahedral pressure medium to perform  
 760 hydrostatic experiments, with the significant difference being the wedge-shaped primaries  
 761 and rotated orientation of the secondary anvils in the Kawai 6/8 geometry. The (c) d-DIA  
 762 geometry utilises 6 secondary anvils and a cubic pressure medium to apply differential  
 763 strain in the vertical direction whereas (d) the D-dia 6/8 geometry uses the same primary  
 764 anvils to deform an octahedral pressure medium within 8 secondary anvils, with differential  
 765 strain loading the pyrophyllite gaskets. (e) and (f) show two alternative cross sections of the  
 766 D111 / D-T-cup drawn (e) parallel and (f) perpendicular to the incident X-ray beam. The  
 767 D111/D-T-cup geometry uses a Kawai-type geometry of primary wedges with differential  
 768 strain applied onto two opposing anvil truncations along the 111 axis of the secondary anvil  
 769 set.

770 **Figure 2:** (a) a schematic of the D111 guide block at NE7A of KEK depicting the Kawai 6/8  
 771 geometry arrangement within a split confining ring and position of the differential  
 772 deformation actuators. (b) A view of D111 module consisting of the split confining ring (1)  
 773 and lower differential actuator (2) next to the MAX-III load frame on NE7A taken from an  
 774 upstream position and showing the direction of the synchrotron X-ray beam in relation to  
 775 the press.

776 **Figure 3:** A schematic of beamline layout on NE7A at KEK when setup for monochromatic  
 777 diffraction experiments using the D111 module, including the position of the X-ray

778 collimation slits, radiographic CCD/CMOS camera and image plate detector and the  
779 motorized linear stages used to switch between imaging and diffraction modes.

780 **Figure 4:** Pressure and temperature conditions of deformation experiments performed  
781 using the D111 at NE7A up until now, plotted alongside relevant phase relations. Samples  
782 studied are indicated by symbols as follows: circles = fcc-iron, large white stars = Ca-  
783 Pv/olivine (this study), small grey stars = olivine, dark grey triangles = ringwoodite, squares =  
784 bridgmanite.

785 **Figure 5:** (a) WC spacers for monochromatic diffraction, consisting of 3 variously shaped  
786 trapezoidal WC spacers with cone cut-out for diffraction, adjacent to a fully assembled  
787 composite anvil consisting 3 spacers combined with a 14mm PCD cube. (b) An example X-  
788 ray diffraction pattern collected using two downstream composite anvils collected from a  
789 Ca-Pv sample at  $\sim$  13 GPa and 1273 K. The direct beam can be observed as a small spot in  
790 the centre of the diffraction rings within the Pb beamstop that was attached to the image  
791 plate detector, and Debye-Scherrer rings extend to  $10^\circ$  2 theta (equivalent to a d-spacing of  
792  $\sim$  1.17 Å using monochromatic X-rays of 0.2066 Å). The more intense stripe inclined from  
793 the lower left to upper right is due to the increased X-ray transmission through the anvil  
794 gap.

795 **Figure 6:** (a) length of Ca-Pv (filled circles) and olivine (filled squares) at 13 GPa and 1273K  
796 under hydrous conditions as a function of time throughout deformation, as derived from  
797 radiographic images, and coloured by the differential ram velocity (as annotated). (b) the  
798 strain of Ca-Pv and olivine samples as a function of time throughout the same experiment.  
799 Small symbols were not used to derive strain rates (annotated and indicated by dashed  
800 lines) as these had not yet reached steady state after change in ram velocities.

801 **Figure 7:** Example of the fitted output from *Continuous Peak Fit* for wet Ca-Pv 200 at 13 GPa  
802 and 1373K. The left-hand panel plots the raw data as a function of diffraction azimuth and  
803  $2\theta$  (both in degrees). Regions of the data that are white are masked due to large intensity  
804 changes in the anvil gap, which hampers successful fitting of the diffraction rings. The  
805 middle panel plots the calculated model of the fitted peak, with the black dashed line  
806 indicating the model peak position. The right-hand panel plots the residual misfit between  
807 the raw data and the fitted peak model. All panels are coloured by intensity, indicated by  
808 the adjacent colour bars (colour figure provided as supplementary figure).

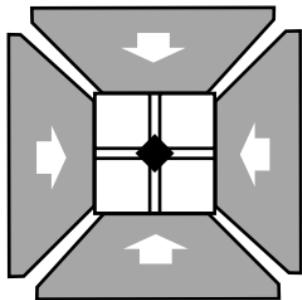
809 **Figure 8:** Examples of stress data collected throughout (a) experiment B for hydrous olivine  
810 and (b) experiment C for hydrous Ca-Pv.

811 **Figure 9:** Summary of the creep strength of Ca-Pv (large, coloured circles) and olivine  
812 samples (large, coloured squares), plotted as strain rate vs. differential stress, as observed in  
813 experiments performed using the D111 at KEK in this study. Uncertainties in observed strain  
814 rates and differential stresses, as reported in Table 1, are plotted and in some cases are  
815 smaller than the symbol size. There are plotted alongside creep strength data for other

816 silicate minerals from similar experiments using D-dia or Rotational Drickamer apparatuses  
817 for comparison; white triangles = creep strength data for ringwoodite (Kawazoe et al.,  
818 2016), green triangles = wadsleyite (Kawazoe et al., 2010, Hustoft et al., 2013), light green  
819 squares = bridgmanite (Girard et al., 2016), light green diamonds = wet olivine (Ohuchi et  
820 al., 2017), light blue diamonds = dry olivine (Kawazoe et al., 2009).

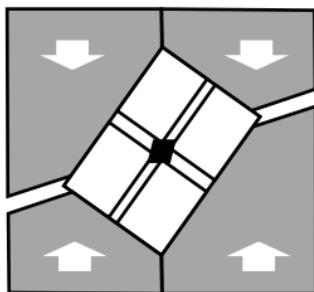
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(a)



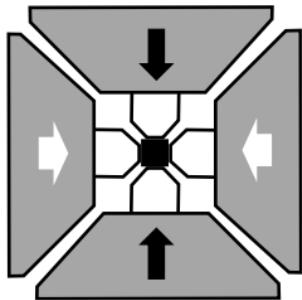
DIA 6/8

(b)



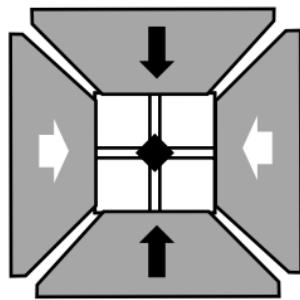
Kawai 6/8

(c)



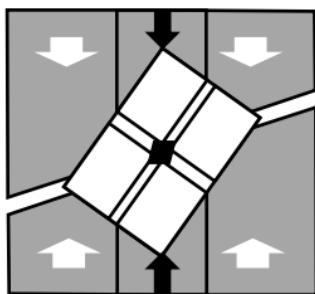
d-DIA

(d)



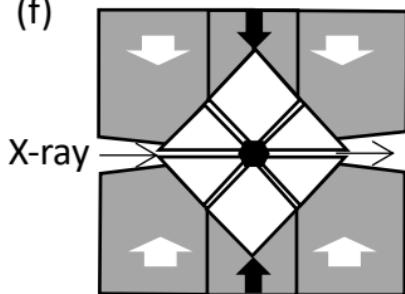
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(e)

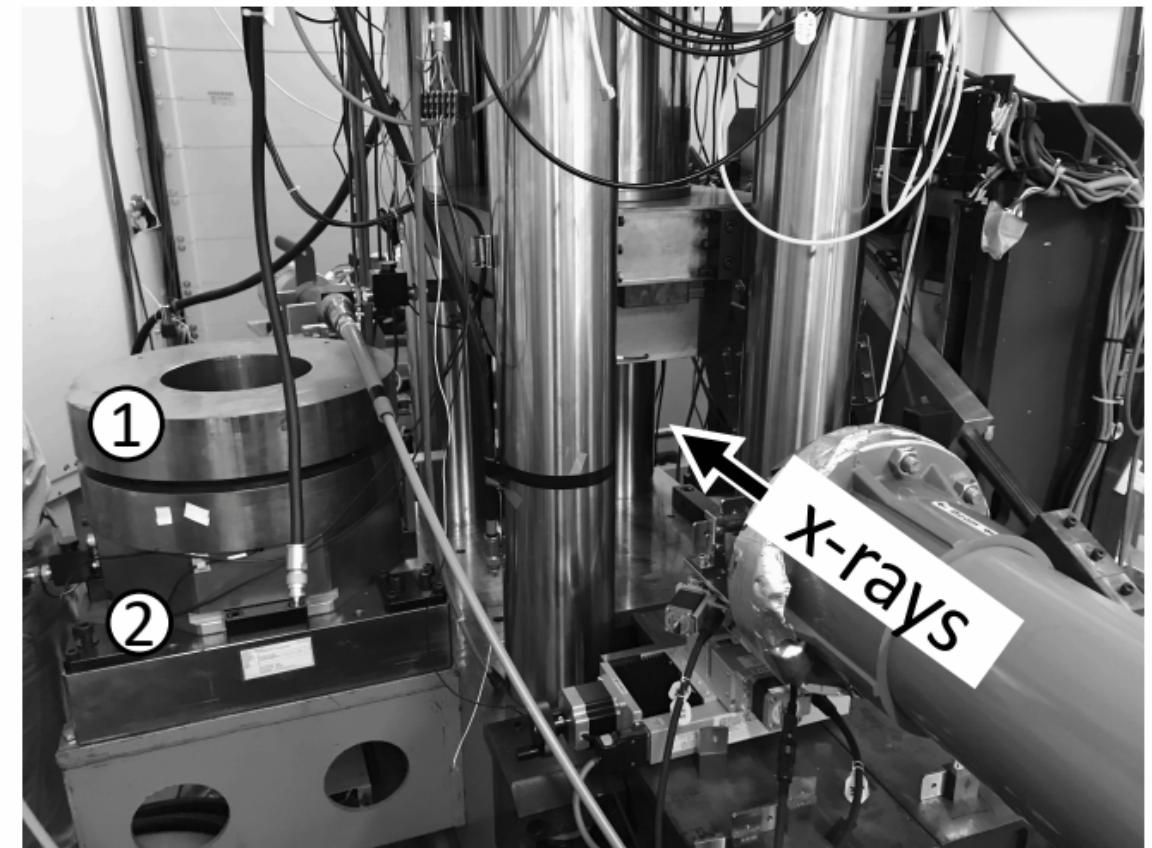
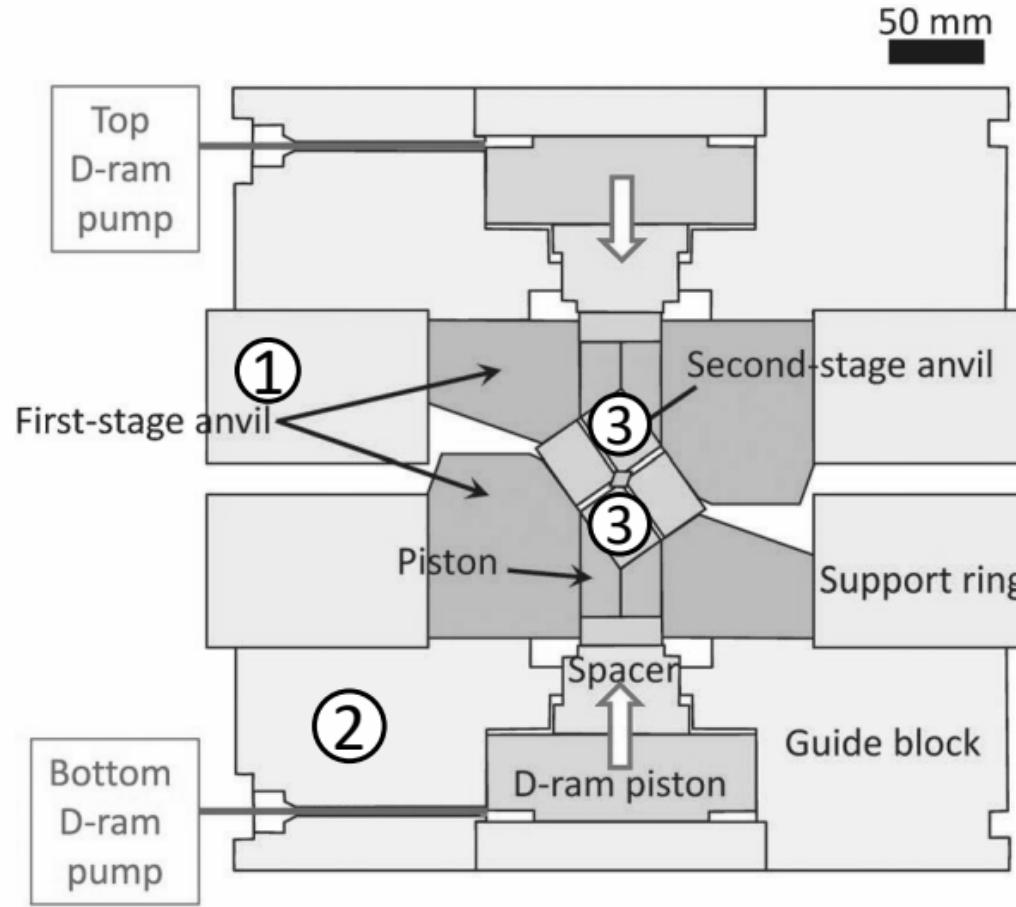


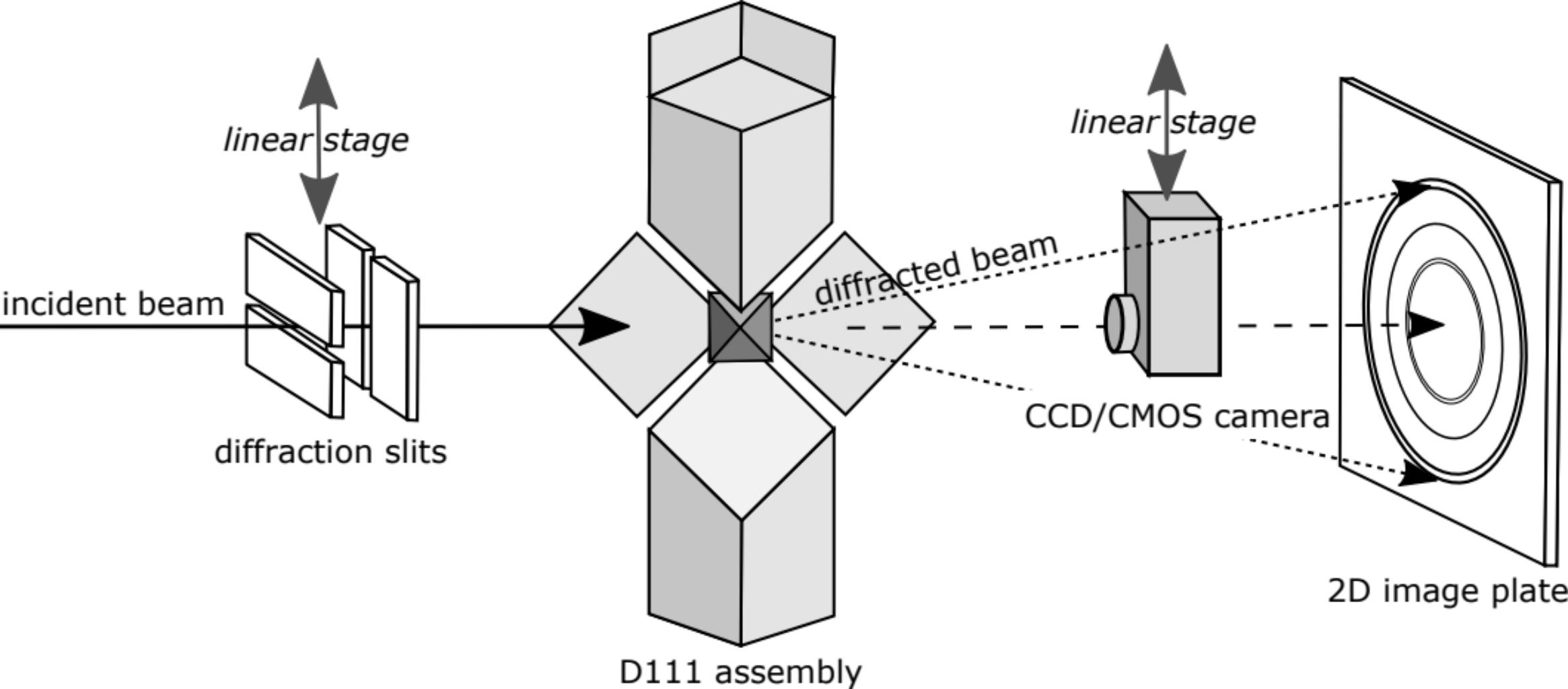
D111 / D-T-cup

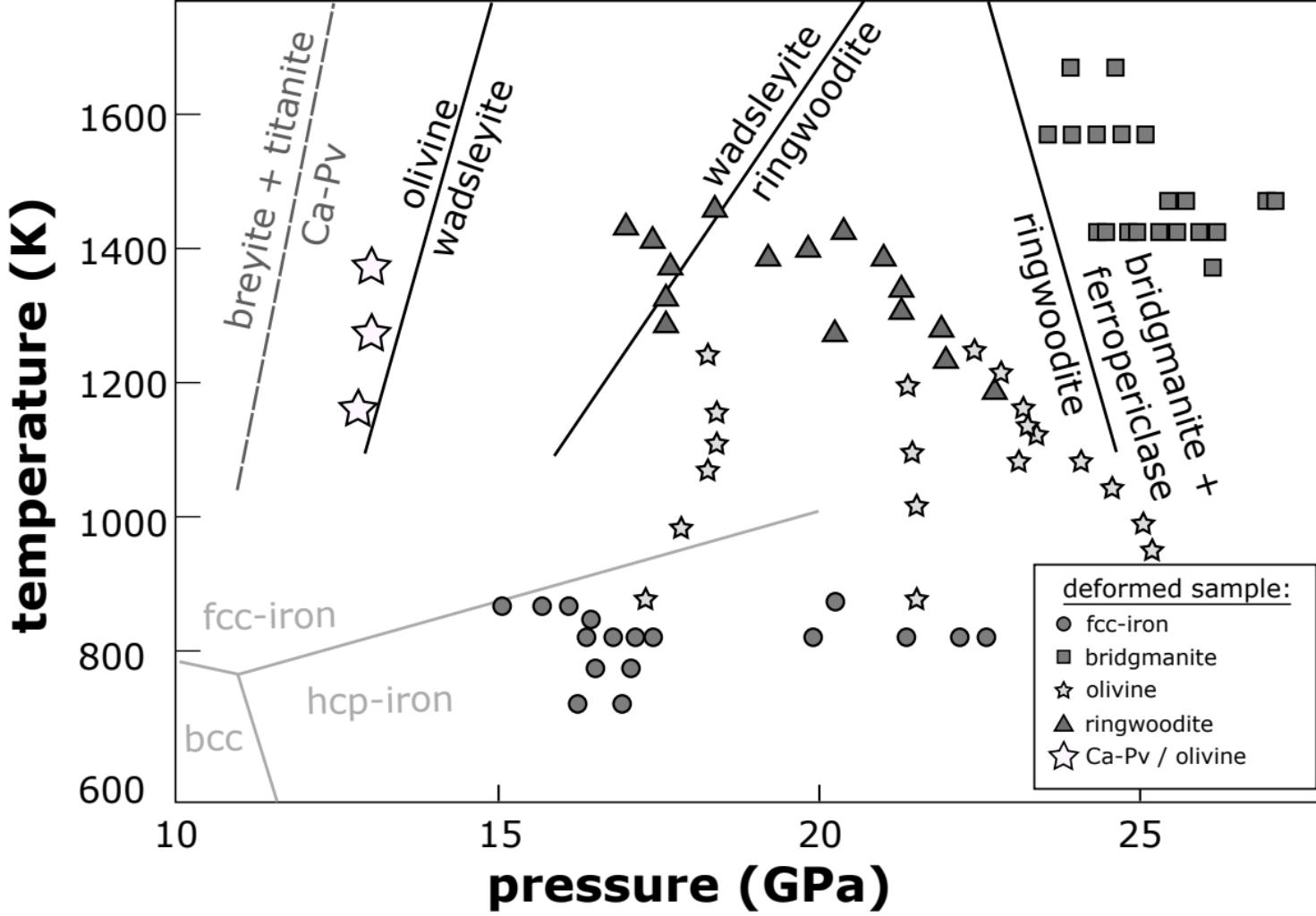
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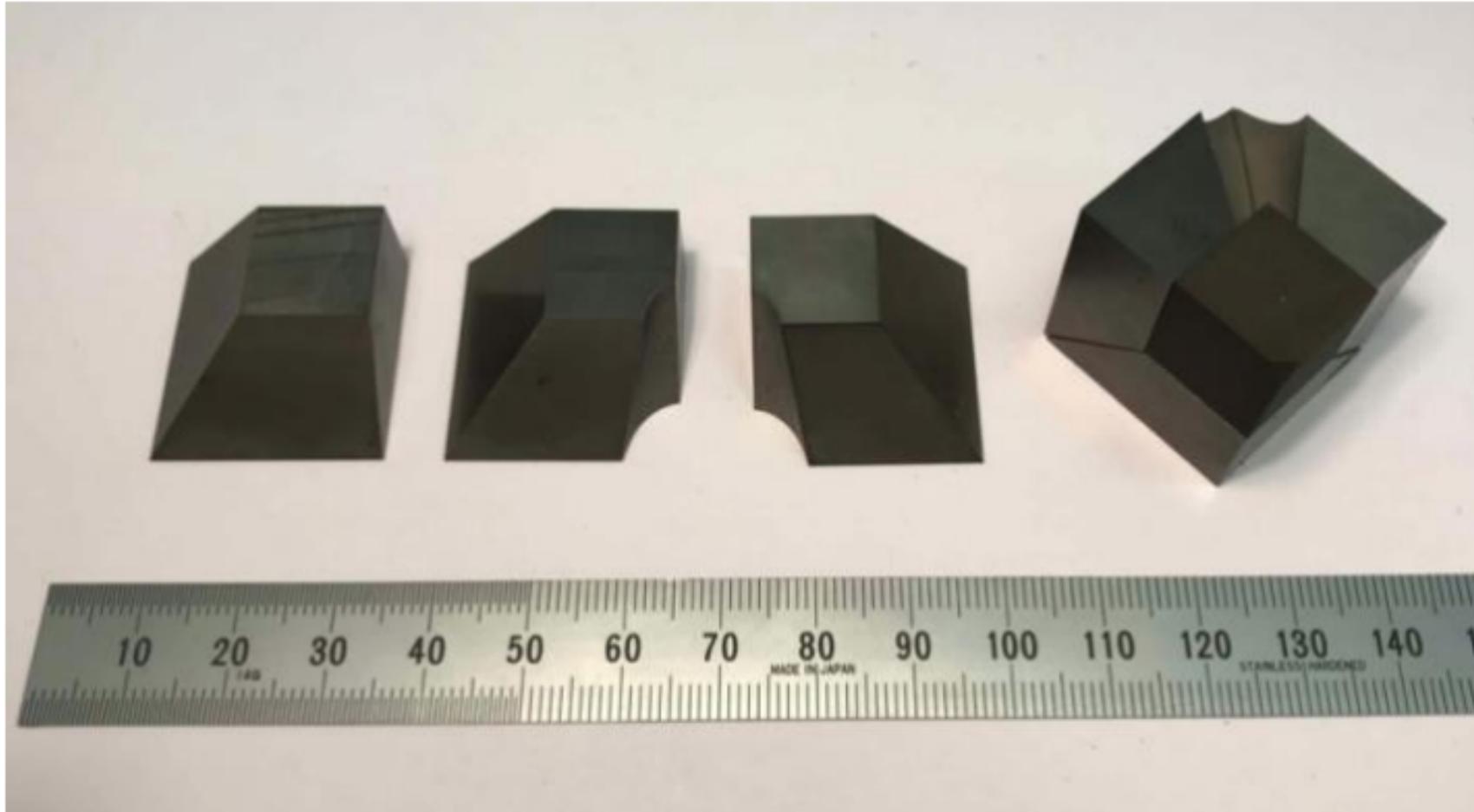
D111 / D-T-cup



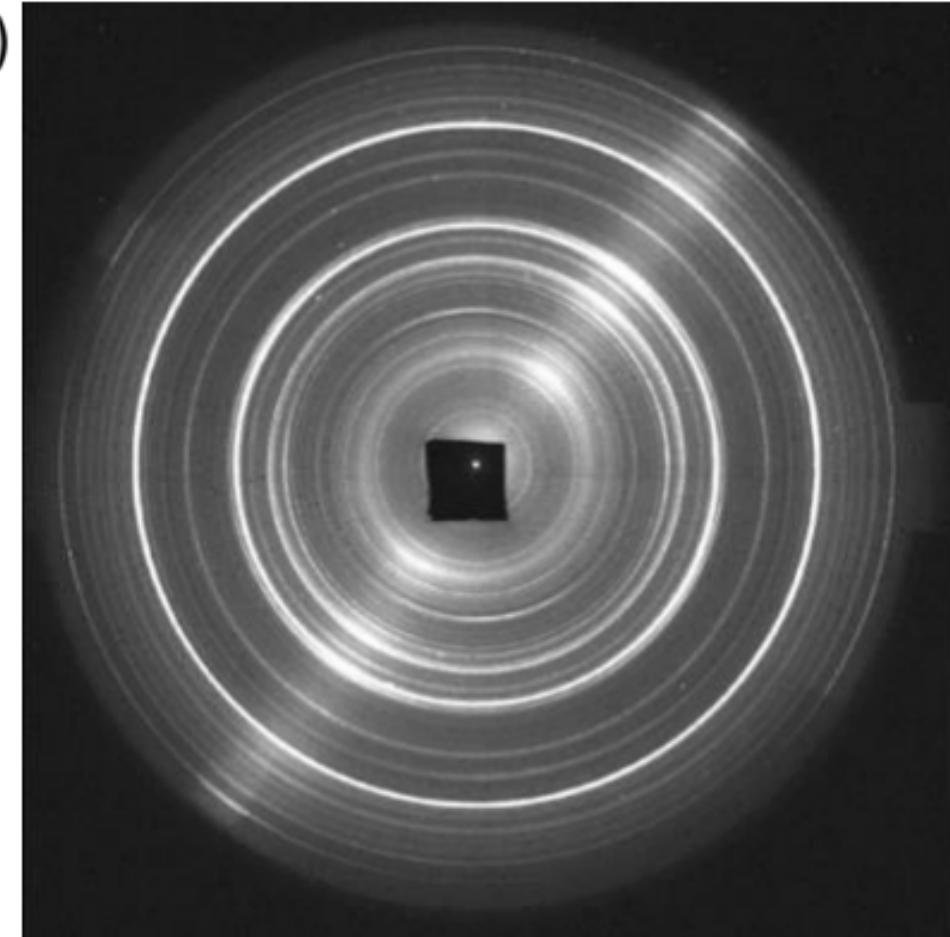


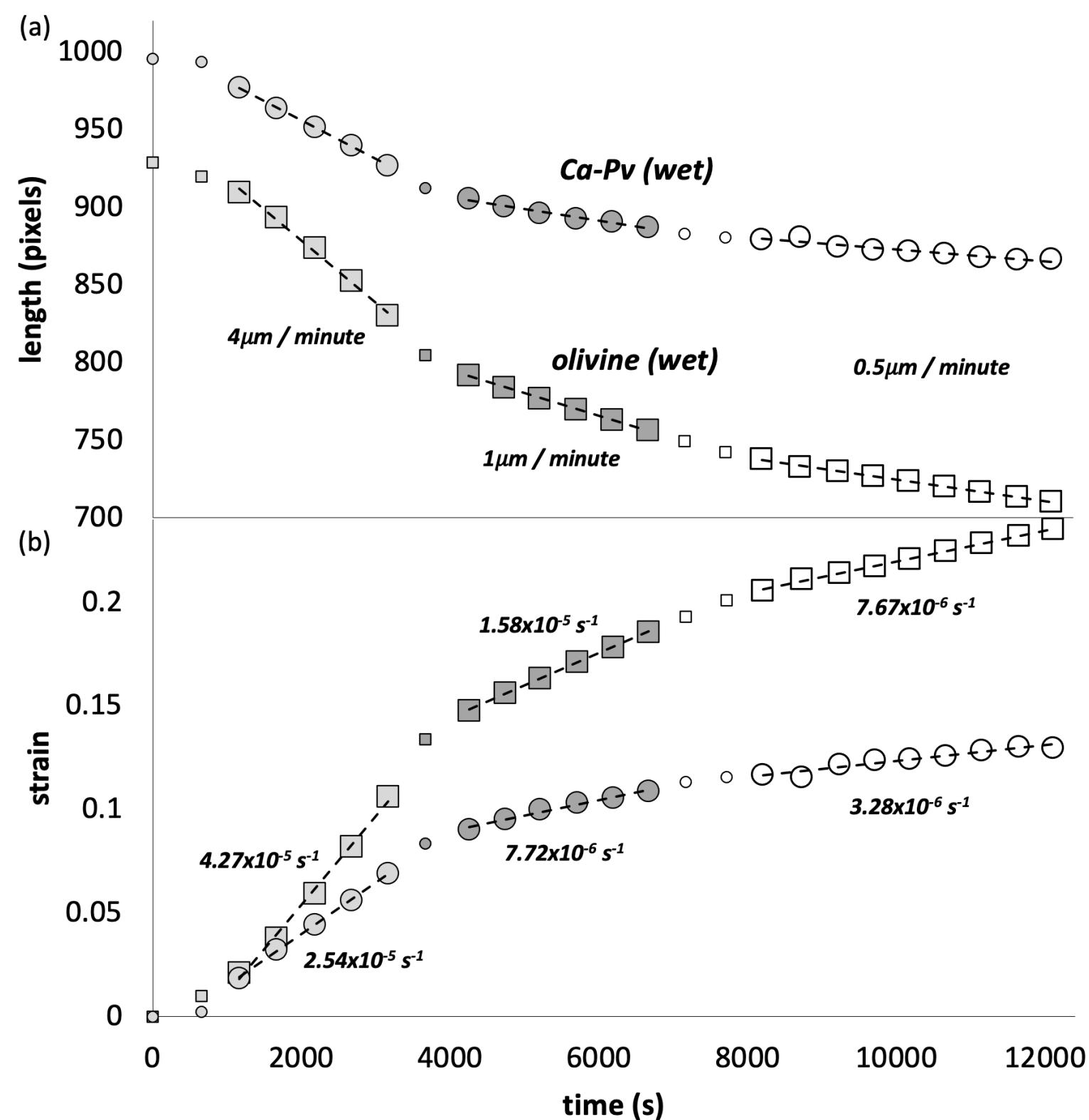


(a)

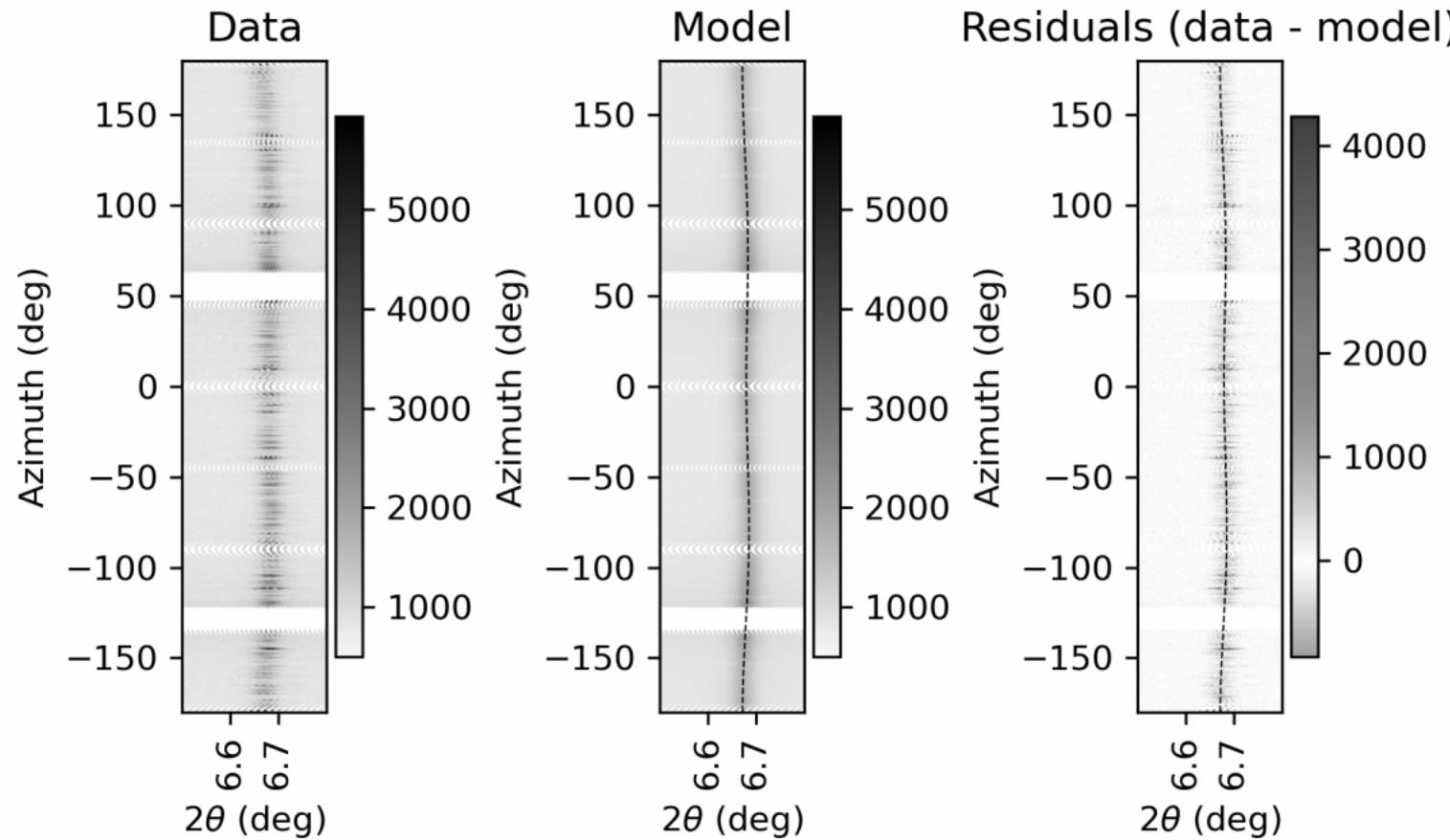


(b)

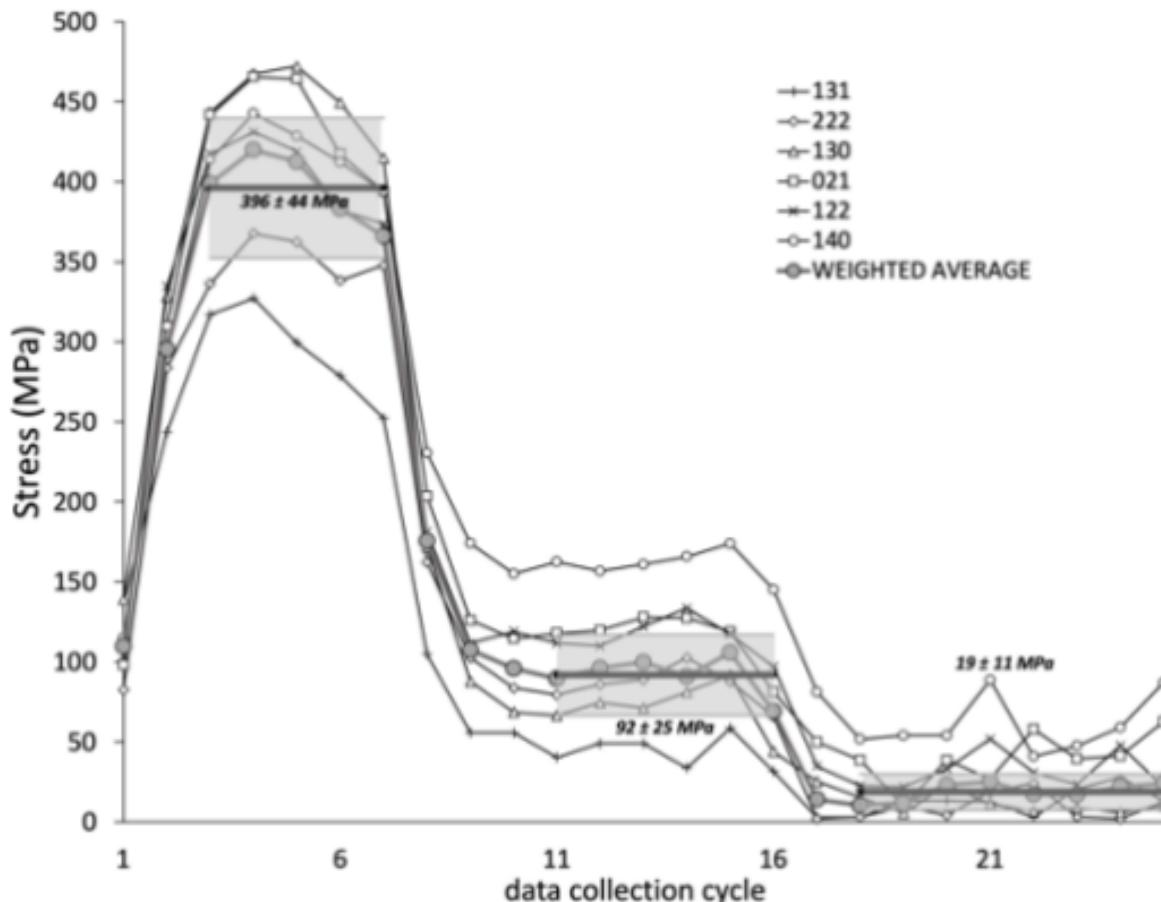




# CaSiO<sub>3</sub>-pv (200); final fit



(a)



(b)

