

# 1 Diagnosing Stagnant Gas Bubbles in a Polymer Electrolyte 2 Membrane Water Electrolyser using Acoustic Emission

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14 **Keywords: Acoustic Emission, PEM Water Electrolyser, Operando Diagnostics, Mass**  
15 **Transport, Flow Channels**

## 17 Abstract

18 The use of acoustic emission as a low-cost, non-destructive, and *operando* diagnostic tool has  
19 been demonstrated for a range of electrochemical energy conversion and storage devices,  
20 including polymer electrolyte water electrolysers (PEMWEs) and fuel cells. In this work, an  
21 abrupt change in acoustic regime is observed during operation of a PEMWE as the current  
22 density is increased from 0.5 A cm<sup>-2</sup> to 1.0 A cm<sup>-2</sup>. This regime change is marked by a sudden  
23 drop in the number of acoustic hits, while hit duration, amplitude, and energy increase  
24 significantly. It is found that the change in acoustic regime coincides with a significant  
25 extension of the stagnant bubble region in the flow channels of the PEMWE, observed with  
26 high-speed optical imaging. These results demonstrate that acoustic emission can be used  
27 effectively as an operando diagnostic tool to monitor bubble formation (two-phase flow  
28 conditions) in PEMWEs, facilitating rapid testing or prototyping, and contributing to  
29 operational safety.

30

## 31 **1 Introduction**

32 PEMWEs represent one of the most promising approaches to the production of ‘green’  
33 hydrogen and large-scale energy grid stabilization. The technology is likely to replace the  
34 widely commercially used alkaline electrolysis due to advantages including lower voltage at  
35 equal current density, lower gas crossover, compact build, and the possibility of high-pressure  
36 operation [1]. While currently more expensive than the alternative alkaline technology, the  
37 capital cost of a typical PEMWE system is dropping [2] and plants rated up to 6 MW are in  
38 operation [3].

39 Water flooding has been shown to be a major mass transport limitation occurring in polymer  
40 electrolyte membrane fuel cells (PEMFCs) at high current densities, particularly at high  
41 humidity when water condenses at the cathode forming droplets which coalesce. This leads to  
42 water blocking the flow channels and occupying the gas diffusion layer, causing a consequent  
43 increase in pressure drop and decrease in performance [4–6]. Similarly to water accumulation  
44 in a PEMFC, which eventually leads to flooding, product gas can accumulate in polymer  
45 electrolyte membrane water electrolyzers (PEMWEs) leading to bubbles blocking the flow  
46 channels. This occurs if the gas production from the catalyst sites exceeds the gas removal  
47 capacity of the flow channels, which is mainly determined by the cross-sectional area and the  
48 flow rate of water through the channels. The effects of bubble blockage on performance,  
49 pressure drop, and life-time of a PEMWE have not yet been investigated, but it is expected that  
50 prolonged bubble blockage results in local water starvation, causing a non-uniform current  
51 distribution over the active area and a decrease in performance [7].

52 Acoustic emission (AE) is a non-destructive, *operando* diagnostic tool traditionally used in  
53 civil engineering, e.g. for monitoring crack propagation in steel [8] or the stability of bridges  
54 [9]. It uses a piezoelectric sensor to detect mechanical perturbations emitted by an object and  
55 has been applied to a range of electrochemical energy storage devices. It has been used to

56 monitor particle fracture and morphological changes in battery electrodes during charge and  
57 discharge [10–12], has been found to be sensitive to Li-ion intercalation and formation of the  
58 solid electrolyte interphase [13,14] in Li ion batteries, and has also been applied to PEMFCs  
59 [15–17].

60 Two-phase systems, such as the water-gas mixture in the flow channels of the PEMWE  
61 analysed in this work, are also readily analysed using acoustic emission. This includes the  
62 calculation of bubble size distribution [18], recognition of different flow patterns by analysing  
63 acoustic emission data with neural networks [19], and observing the formation and collapse of  
64 single bubbles [20]. Hence, acoustic emission is a valuable alternative diagnostic tool to other  
65 techniques for the investigation of two-phase dynamics [21–23].

66 In previous work, the authors demonstrated the ability of acoustic emission to detect changes  
67 in the number and size of bubbles passing through the flow channel of a PEMWE. This enabled  
68 the prediction of the change from bubbly to slug flow and showed that acoustic emission is a  
69 valuable *operando* tool for PEMWE diagnosis [24]. Here, we demonstrate that the acoustic  
70 emission signal changes dramatically when, rather than normal two-phase flow, stagnant  
71 bubbles are located within the vicinity of the acoustic emission sensor. This feature can be used  
72 to detect and locate bubble ‘blockage’ (channel dehydration) in PEMWEs, for *operando*  
73 monitoring or design optimization.

## 74 **2 Experimental**

### 75 **2.1 PEMWE Cell**

76 The electrolyser used in this work (Figure 1) had a 9 cm<sup>2</sup> active area and consisted of  
77 transparent Perspex end-plates, parallel titanium flow-fields, a titanium sinter liquid-gas  
78 diffusion layer (LGDL) on the anode side, a Toray H-060 carbon paper as the gas diffusion  
79 layer (GDL) on the cathode side, and a catalyst coated membrane (CCM), which was based on

80 Nafion 115 with  $0.6 \text{ mg cm}^{-2}$  platinum on the cathode and  $3.0 \text{ mg cm}^{-2}$  iridium/ruthenium oxide  
81 on the anode (ITM Power, UK). The flow-field consisted of nine parallel channels, with a  
82 length of 3 cm and a land and channel width of 1.76 mm. The electrolyser was run at ambient  
83 pressure with a deionised water inflow temperature of  $50 \text{ }^\circ\text{C}$  and a water inflow rate of  $10 \text{ ml}$   
84  $\text{min}^{-1}$  at the anode and cathode. Electrochemical testing was performed between 0.0 and 2.0 A  
85  $\text{cm}^{-2}$  using a potentiostat (Gamry Reference 3000 Galvanostat/Potentiostat with a Gamry 30k  
86 Booster; Gamry Instruments, USA).

## 87 **2.2 Acoustic Emission**

88 Acoustic emission was measured with a cylindrical piezoelectric sensor (S9208, Mistras NDT,  
89 UK), with a diameter and height of 25 mm. The sensor was placed in the centre of the flow-  
90 field on the anode side; data acquisition lasted 1 min during galvanostatic operation of the  
91 PEMWE. Due to the nature of sound transmission, no clear area can be defined within which  
92 acoustic data is collected. Whether a mechanical perturbation is detected by the sensor is  
93 contingent on the location and intensity of the perturbation, with the intensity necessary for  
94 detection increasing with the distance between acoustic source and sensor. Therefore, detection  
95 of stagnant bubbles is increasingly likely as they are located closer to the sensor (bubbles  
96 ‘grow’ from the top end of the channel towards the centre). Data were processed using the  
97 software AEWIn (Physical Acoustics, USA). The sensor produces a continuous voltage/time  
98 signal, with strong mechanical perturbations producing high voltage values. After filtering and  
99 pre-amplification by 26 dB, acoustic hits exceeding a noise threshold of 37 dB were extracted  
100 from the continuous signal. An acoustic hit is defined as an acoustic event initiated by the  
101 acoustic emission signal exceeding the noise threshold and ending when the signal falls back  
102 below that threshold (Figure 2). Strong acoustic activity is marked by a high number of separate  
103 acoustic hits (events). The number of hits per unit time (hit rate  $H$ ), the maximum of each  
104 waveform averaged over all hits (average hit amplitude  $A$ ), the averaged time from exceeding

105 the threshold until falling back below it (average hit duration  $D$ ) and the average hit energy  $E$   
106 were recorded. The hit energy was determined by integrating the area under the waveform with  
107 respect to time. Further details on acoustic emission data analysis can be found in previous  
108 work [24].

### 109 **2.3 High-Speed Imaging**

110 To visualize the movement of bubbles and the effect of increasing current density on the rate  
111 of removal of bubbles in the flow channels, high-speed imaging was employed. A Photron  
112 FASTCAM SA1 high-speed camera with a Tokina MACRO 100 F2.8 D lens was used to image  
113 the full flow-field on the anode side (1024×1024 pixel resolution, 2000 frames per second, 5.46  
114 s acquisition). The transparent end-plates allowed for direct optical access to the flow-field  
115 [25,26].

## 116 **3 Results and Discussion**

117 The bubble evolution as a function of the current density has been captured with high-speed  
118 imaging experiments, which are shown as a function of increasing current density (Figure 3).  
119 As the cross-sectional area of the flow channels is finite and as all bubbles have to leave the  
120 flow-field through the manifold at the top end of the flow channels, the ability of the PEMWE  
121 cell to remove product gas is limited. This leads to bubbles blocking the top end of the flow  
122 channels at high current densities. For a given flow rate, the length of channel that contains  
123 stagnant bubbles at the top end of the flow channel increases significantly with current density.  
124 Here, a stagnant bubble is defined as a bubble which does not change its location, and  
125 particularly a bubble at the top end of the channel not entering the combining manifold, but  
126 remaining at the top end of the flow channel. The location of the largest stagnant bubble in  
127 each image in Figure 3 is marked in red. The amount of oxygen produced at the anode increases  
128 as a function of current density (Faraday's law); hence, a growth in the length of stagnant  
129 bubbles is expected with increasing current density. At a current density of  $0.3 \text{ A cm}^{-2}$  (Figure

130 3 (a)) the top end of each channel is almost free of stagnant bubbles, while a clear growth of  
131 these bubbles can be observed at  $0.6 \text{ A cm}^{-2}$  (Figure 3 (b)). At  $1.0 \text{ A cm}^{-2}$  (Figure 3 (c)), bubble  
132 blockage covers more than a quarter of the channel length.

133 The acoustic emission parameters are strongly influenced by the current density (Figure 4). As  
134 illustrated above, current density leads to bubble blockage at the top end of the flow channels;  
135 hence, Figure 4 can be interpreted as the correlation between the acoustic emission signal and  
136 the formation of stagnant bubbles. The acoustic hit rate drops from  $80.0 \text{ s}^{-1}$  to the limit of  
137 detection for the acoustic emission system used in this work ( $1.0 \text{ s}^{-1}$ ) between  $0.5 \text{ A cm}^{-2}$  and  
138  $1.0 \text{ A cm}^{-2}$  (Figure 4 (a)). The limit of detection is an artefact of the data acquisition, which  
139 cuts off any hit longer than 1.0 s, which means that from  $1.0 \text{ A cm}^{-2}$  onwards the AE signal  
140 continuously exceeds the noise threshold, with no individual acoustic hits discernible. This  
141 significant decrease of acoustic hits highlights a dramatic change of two-phase flow within the  
142 flow channels. The relationship between the number of acoustic hits and the number of bubbles  
143 passing through the flow channels has been established in previous work [24], which found  
144 that the number of acoustic hits scales directly with the number of bubbles passing through the  
145 flow channels. Hence, a drop in the number of acoustic hits indicates a decrease in the number  
146 of bubbles generated and passing through the flow channels, which is likely due to the blocking  
147 of the flow channel by a stagnant bubble. This stagnant bubble stops smaller bubbles from  
148 traveling upwards through the flow channels; instead the bubbles coalesce into the stagnant  
149 bubble. Hence, the drop in the number of acoustic hits between  $0.5 \text{ A cm}^{-2}$  and  $1.0 \text{ A cm}^{-2}$  is  
150 likely caused by the extension of stagnant bubbles into the sensor area.

151 Further, the average hit amplitude (Figure 4 (b)) increases steeply by around 50 % between  $0.5$   
152  $\text{ A cm}^{-2}$  and  $1.0 \text{ A cm}^{-2}$ , the same range within which the hit rate drops. The average hit duration  
153 increases from less than 0.1 ms to the cut off value of 1.0 s mentioned above (Figure 4 (c)). For  
154 current densities above  $1.0 \text{ A cm}^{-2}$ , a constant signal is detected, indicating permanent contact

155 between a bubble and the end-plate. Finally, an increase in hit duration and amplitude causes  
156 an increase in acoustic energy (Figure 4 (d)). All these changes occur in a step-like manner  
157 between  $0.5 \text{ A cm}^{-2}$  and  $1.0 \text{ A cm}^{-2}$ .

158 The decreasing number of hits, while hit amplitude and contact time between bubble and end-  
159 plate increase, all suggest that the signal change is caused by the extension of the stagnant  
160 bubble region towards the sensor location in the current density range between  $0.5 \text{ A cm}^{-2}$  and  
161  $1.0 \text{ A cm}^{-2}$  (Figure 4). This is supported by the extension of the stagnant bubble region (Figure  
162 3) observed via high-speed imaging, a major part of which occurs between  $0.6 \text{ A cm}^{-2}$  and  $1.0$   
163  $\text{ A cm}^{-2}$ .

#### 164 **4 Conclusion**

165 Acoustic emission has been demonstrated as a useful technique for *operando* diagnosis of  
166 bubble blockage in PEMWEs. High-speed imaging of an optically-transparent PEMWE cell  
167 was used to visualize the bubble movement in the flow channels. The length of the part of the  
168 flow channel containing stagnant bubbles was found to increase with current density,  
169 eventually reaching the location of the acoustic emission sensor. With increasing flow channel  
170 blockage, a dramatic change in acoustic activity was observed. The acoustic hit rate dropped  
171 from  $80.0 \text{ s}^{-1}$  to  $1.0 \text{ s}^{-1}$ , average hit amplitude increased from 32 dB to 50 dB, average hit  
172 duration from 0.1 ms to 1.0 s, and average hit energy from 0.004 aJ to 3400 aJ. These changes  
173 occurred abruptly between  $0.5 \text{ A cm}^{-2}$  and  $1.0 \text{ A cm}^{-2}$ , which coincides with a significant  
174 extension of the stagnant bubble region in the flow channels. This leads us to conclude that the  
175 change in acoustic activity is caused by the flow regime in the channels changing from two-  
176 phase flow to stagnant bubbles. The accumulation of gas in the flow channels occurs when gas  
177 production exceeds the capacity of the system for gas removal, which can affect the water  
178 distribution in the PEMWE. Insufficient water supply at the anode causes a voltage increase  
179 [7], hence lowers PEMWE efficiency and reduces hydrogen production at equal voltage. It is

180 expected that acoustic emission can be used to detect local bubble blockage and insufficient  
181 water supply in specific areas of a PEMWE.

182 The use of this *operando* diagnostic tool has successfully been applied to a PEMWE, but could  
183 be extended to other applications. The accumulation of gas within a system or plant can cause  
184 inefficiencies or pose a hazard in many areas of chemical production and transport. Moreover,  
185 it has been shown that the change of two-phase flow regime influences the pressure drop  
186 [27,28]. Hence, the technique presented in this work could be deployed to screen various flow-  
187 field configurations or monitor safe limits of operation, replacing less cost-effective or  
188 accessible diagnostic tools such as neutron or X-ray imaging [29–31].

### 189 **Captions**

190 Fig. 1: Assembly of a PEMWE with the AE sensor, two end-plates, two flow-fields, the liquid-  
191 gas diffusion layer (LGDL), the catalyst coated membrane (CCM), and the gas diffusion layer  
192 (GDL) on the anode side.

193 Fig. 2: Typical structure of an acoustic hit as voltage profile as a function of time. The acoustic  
194 hit is initiated when the signal exceeds the noise threshold and ends when the signal falls back  
195 below the threshold. The hit amplitude is the intensity of the most prominent peak within the  
196 hit, and its energy is the integrated area of the hit (adapted from [32]).

197 Fig. 3: Exemplary results from high-speed imaging of the anode flow field of the PEMWE at  
198 (a)  $0.3 \text{ A cm}^{-2}$ , (b)  $0.6 \text{ A cm}^{-2}$ , and (c)  $1.0 \text{ A cm}^{-2}$  at a water inflow rate of  $10 \text{ ml min}^{-1}$ . The  
199 largest stagnant bubble at the top end of the flow channels is marked in red for each current  
200 density.

201 Fig. 4: Acoustic emission parameters as a function of current density for a water inflow rate of  
202  $10 \text{ ml min}^{-1}$ . Acoustic hit rate (a), average hit amplitude (b), average hit duration (c), and  
203 average hit energy (d) are shown.

## 204 Acknowledgements

205 The authors acknowledge financial support into the EIL's hydrogen and fuel cell activity from  
206 the EPSRC through grants (EP/R023581/1; EP/P009050/1; EP/N032888/1; EP/M014371/1;  
207 EP/M009394; EP/L015749/1; EP/K038656/1). Support from the National Measurement  
208 System of the UK's Department of Business, Energy & Industrial Strategy is also gratefully  
209 acknowledged. PRS acknowledges funding from The Royal Academy of Engineering  
210 (CiET1718/59).

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319

320

Figure 1.JPEG

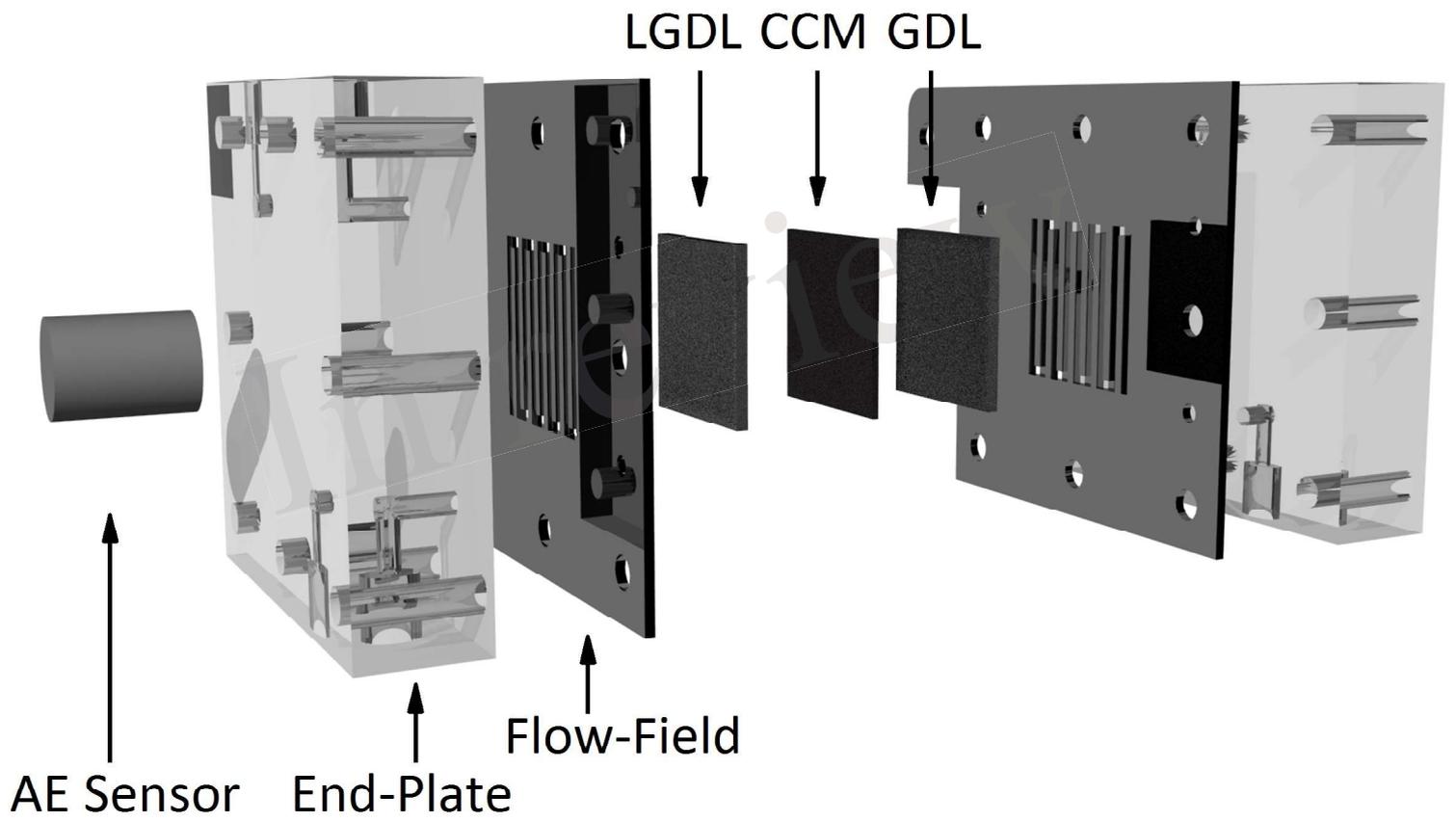


Figure 2.JPEG

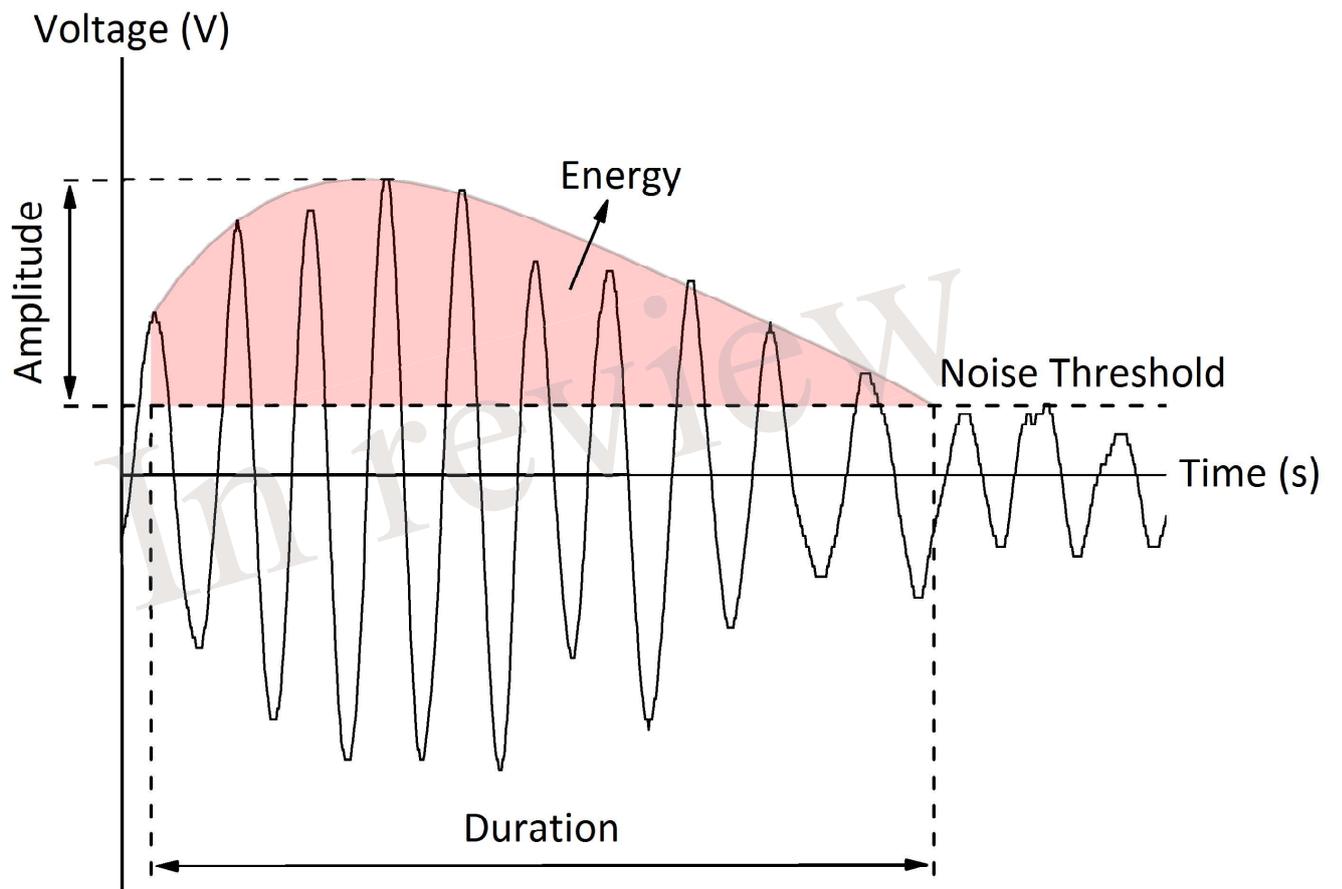


Figure 3.JPEG

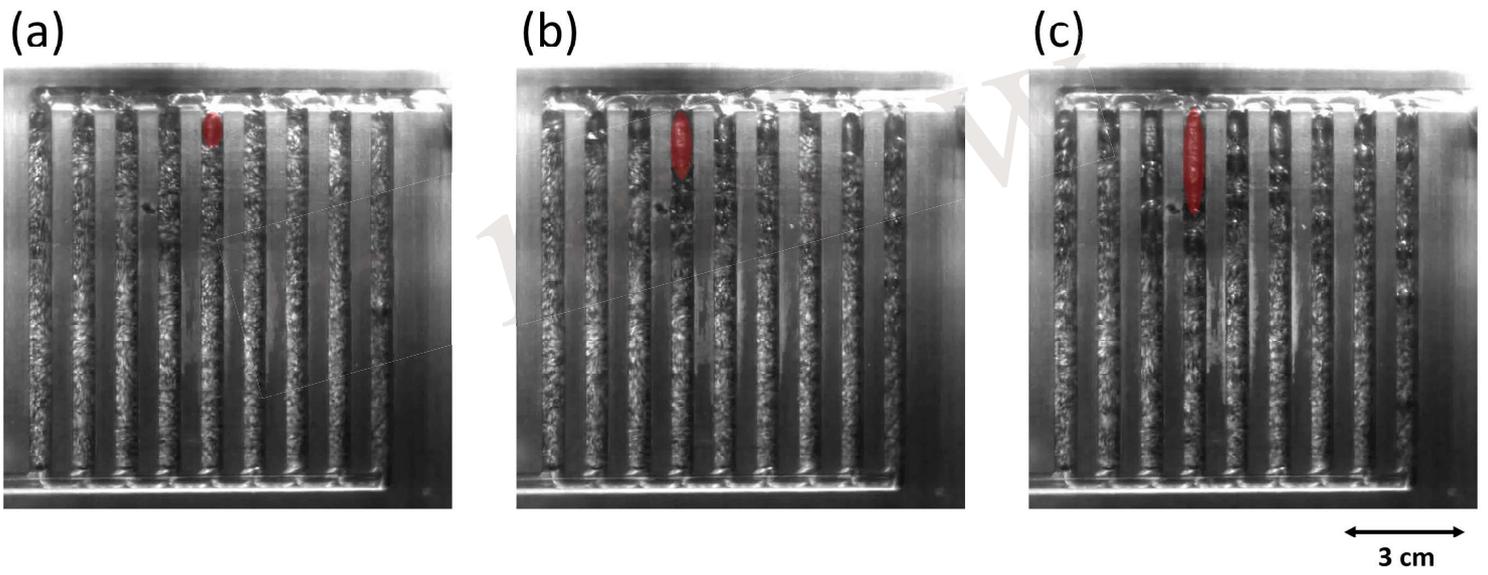


Figure 4.JPEG

