The Benefit of Split Nonlinearity Compensation for Single Channel Optical Fiber Communications

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Abstract—In this Letter we analyze the benefit of digital compensation of fiber nonlinearity, where the digital signal processing is divided between the transmitter and receiver. The application of the Gaussian noise model indicates that, where there are two or more spans, it is always beneficial to split the nonlinearity compensation. The theory is verified via numerical simulations, investigating transmission of single channel 50 Gbd polarization division multiplexed 4- and 256-ary quadrature amplitude modulation signals over 100 km standard single mode fiber spans, using lumped amplification. It is shown, theoretically, that the SNR gain for long distances and high bandwidth transmission is 1.5 dB versus transmitter- or receiver-based nonlinearity compensation.

Index Terms—Coherent Optical Communications, Quadrature Amplitude Modulation (QAM), Nonlinearity Compensation.

I. INTRODUCTION

RECENT efforts in overcoming the limit to optical communications imposed by fiber nonlinearity can be broadly grouped into two areas: optical and digital techniques. Optical techniques include, for example, optical phase conjugation (OPC) using twin waves [1] or OPC devices placed mid-span [2]. Digital techniques include transmitter-based [3], [4] and receiver-side [5] digital nonlinearity compensation (NLC), simple nonlinear phase shifts [6], [7], perturbation-based precompensation [8], adaptive filtering [9] and optimum detection [10]. With the exception of optimum detection (a special case of receiver-side NLC for single span transmission) the digital signal processing (DSP) techniques are algorithms which invert the propagation equations for the optical fiber, either exactly or with simplifying approximations.

Consider the model in Fig. 1, which shows a transmission link with digital NLC at both the transmitter and the receiver. To date, the best performing experimentally demonstrated digital technique for receiver-side digital NLC is the digital backpropagation (DBP) algorithm. This algorithm numerically solves the inverse of the optical fiber propagation equations to compensate the linear and nonlinear impairments introduced by the optical fiber transmission; albeit not taking account of amplifier noise. The demonstrations of multi-channel NLC via receiver-side DBP [5] which takes account of the inter-channel nonlinear distortions, have recently been repeated using similar digital techniques to predistort for nonlinearity at the transmitter – digital precompensation (DPC) [3]. We note that, as might be expected due to the symmetry of the transmission link, the experimentally demonstrated performance of the pre- and post-compensation algorithms is similar; achieving a 100% increase in transmission reach [3], [5].

Whether applying DBP or DPC, additive noise from in-line optical amplifiers is enhanced, which limits the performance of the NLC. One can, therefore, make an argument for dividing the NLC equally between transmitter and receiver, in that it limits the noise enhancement in the compensated waveform to the signal-noise interaction present at the center (rather than the end) of the transmission link.

Although split NLC (dividing digital NLC between transmitter and receiver) has previously been considered, experimental implementation was confined to the special case of simplified DSP (single nonlinear phase shift [6]) and theoretical analysis considered only residual NLC after OPC [2]. In this Letter, we assess the performance of split NLC via numerical simulations, and characterize performance in terms of achievable signal-to-noise ratio (SNR). Further, we confirm these results theoretically.

II. MODEL OF TRANSMISSION PERFORMANCE USING DIGITAL NONLINEARITY COMPENSATION

To model the effect of digital NLC we used a coherent Gaussian noise (GN) model of nonlinear interference.

1DBP is a zero-forcing equalization, however it should be noted that algorithms such as stochastic DBP incorporate the noise distribution to improve the NLC performance [11].

2As noted in [7], the first span is an exception to link symmetry in that, under the simplifying assumptions of a noiseless transmitter, no polarization mode dispersion and no photon-phonon interactions, the nonlinear interference in this span can be compensated exactly with DPC.
including the effect of signal-ASE (amplified spontaneous emission) noise interactions. The model treats the field propagating in the fiber as a summation of signal and noise fields, incorporating the signal-ASE noise interaction as a form of cross channel interference. Similar to [13] the SNR at the receiver is approximated as 

\[
\text{SNR} \approx \frac{P}{N_S P_{S} + N_S^{1+\varepsilon_{sn}} \eta_{ss} P^3 + 3 \xi \eta_{sn} P^2 P_{ASE}},
\]

where \( P \) is the signal power, \( N_S \) is the number of spans, \( P_{ASE} \) is the ASE noise power in the signal bandwidth from a single span amplifier, \( \eta_{ss} \) is a single span nonlinear interference factor for the self channel interference (i.e., signal-signal interactions), \( \eta_{sn} \) is a single span nonlinear interference factor for signal-squared ASE noise interference, \( \varepsilon_{ss} \) is the coherence factor for self channel interference and \( \xi \) is a factor depending on the number of spans and the method used for digital NLC. The nonlinear interference terms with ASE noise squared and cubed have been neglected as insignificant.

In order to analytically calculate the SNR when applying different nonlinear equalization methods, the \( \xi \) parameter must be computed for DPC, DBP and split NLC (\( \xi_{DPC}, \xi_{DBP} \) and \( \xi_{SC} \), respectively).

Following the method in the Appendix, it is found that the difference in SNR at optimum signal launch power when applying split NLC versus DBP is given by

\[
\Delta \text{SNR} = \sqrt{\frac{\xi_{DBP}}{\xi_{SC}}},
\]

where \( \xi_{DBP} \) and \( \xi_{SC} \) are given in the appendix by Eqs. (6) and (7). Choosing a 50% transmitter:receiver split ratio for NLC, and for a large number of spans, (2) becomes

\[
\lim_{N_S \to \infty} \Delta \text{SNR} = \sqrt{2^{1+\varepsilon_{sn}}}. \tag{3}
\]

For this work, \( \varepsilon_{sn} = 0.134 \), obtained via numerical integration (see appendix). For \( \varepsilon_{sn} \) varying from 0 to 0.3 (a conservatively high value) \( \Delta \text{SNR} \) varies between 1.5 dB and 1.95 dB. In the large bandwidth limit, \( \varepsilon_{sn} \) tends to zero.

III. Numerical Simulations

Consider the point-to-point transmission link shown in Fig. 1, consisting of an idealized optical transmitter and coherent receiver separated by \( N_S \) spans of standard single mode fiber (SSMF), followed by erbium doped fiber amplifiers (EDFA). The simulation parameters are shown in Table I.

The transmitted signal was single channel 50 Gbd polarization division multiplexed (PDM) 4- and 256-ary quadrature amplitude modulation (QAM). These formats were chosen to investigate the validity of the model when using NLC for both low and high cardinality modulation. The signal was sampled at 4 samples/symbol (to take account of the signal broadening due to fiber nonlinearity) and shaped using a root-raised cosine (RRC) filter. Where DPC was considered, it was applied at this point using the split step Fourier method (SSFM) to solve the Manakov equation [14, Eq. (12)].

The optical fiber span was again modeled by solving the Manakov equation using the SSFM. Each fiber span was followed by an EDFA which applied gain which exactly compensated the previous span loss.

Where required, the receiver DSP applied either frequency domain chromatic dispersion compensation (linear case), or DBP. Subsequently, a matched RRC filter was applied to the signal, and the signal was downsampled from 4 to 1 sample/symbol. To mitigate any residual phase rotation due to uncompensated nonlinear interference, carrier phase recovery was performed as described in [15]. Finally, the SNR was estimated over 2^17 symbols by comparing the transmitted and received symbols, using the SNR definition in [15].

IV. Results and Discussion

The analytical expression for SNR, (1), was evaluated using the methods outlined in the Appendix for calculating \( \xi \) for both linear signal equalization (CDC) and for each NLC technique: DPC, DBP and split NLC. In simulation, transmission distances were considered between 200 and 10000 km (2-100 spans), with the signal launch power varied in 1 dB steps. For each transmission distance, the SNR was determined at the optimum launch power. Fig. 2(a) shows how the maximum achievable SNR for a PDM-4QAM signal varies with transmission distance when applying different digital NLC techniques. A 50% split ratio is used for split NLC. It should be noted that there is excellent agreement between the analytical expressions and the SSFM simulations, with an SNR estimation agreement better than 0.4 dB for all distances when NLC is applied. For linear CDC, the model accuracy increases for distances over approximately 1000 km where the GN model is known to have greater accuracy due to the high accumulated chromatic dispersion. An SNR improvement for split NLC over both DBP and DPC at all distances is also observed, as predicted by (3).

Fig. 2(b) shows the PDM-256QAM transmission performance. The increased cardinality modulation improves the accuracy of linear CDC model at short distances, as expected. Note that this has no impact on the high accuracy of the NLC performance model, which can be attributed to the compensation of signal-dependent self-interference terms.

The results in Fig. 2(c) show the SNR gain that can be achieved by dividing the NLC between transmitter and receiver with different ratios. Note that the gain of DPC over DBP rapidly diminishes with transmission distance. Further, it can be seen that a 50% NLC split ratio is optimum for all transmission distances.

TABLE I

<table>
<thead>
<tr>
<th>Parameter</th>
<th>Value</th>
<th>Units</th>
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<tbody>
<tr>
<td>Fiber attenuation</td>
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<td>dB/km</td>
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<tr>
<td>Dispersion parameter</td>
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<td>ps/(nm-km)</td>
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<tr>
<td>Fiber nonlinear coefficient</td>
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<td>Span length</td>
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<td>km</td>
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<td>Simulation step size</td>
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</tr>
<tr>
<td>NLC step size</td>
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<td>m</td>
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<td>EDFA noise figure</td>
<td>5</td>
<td>dB</td>
</tr>
<tr>
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<td>rollof</td>
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analyse the potential SNR gain when dividing NLC between the signal-ASE interaction over multiple spans in order to translate this work demonstrates that the current arrangements of digital NLC can be substantially improved. Nevertheless, these results should be interpreted as an optimistic estimation of performance using digital NLC. Therefore, this work demonstrates that the current arrangements of digital NLC (DPC or DBP) can be substantially improved.

V. CONCLUSIONS

We used a closed form approximation for the accumulation of the nonlinear interference factors, ηss and ηsn, were calculated using numerical integration of the GN model reference equation [12, Eq. (1)]. Note ηsn ≈ ηss but is more accurately given by numerical integration of [16, Eq. (7)] where the spectral shape, \( g(f_1 + f_2 + f) \), is replaced by unity to represent the uniformity of the ASE spectrum. Coherence factors \( \varepsilon_{ss} \) and \( \varepsilon_{sn} \) were calculated by obtaining the nonlinear interference factors for 100 spans by numerical integration and using

\[
\varepsilon = \log \left( \frac{\eta_{ss}}{\eta} \right) - 1
\]

where \( \eta_{ss} \) is the single span nonlinear interference factor and \( \eta_{100} \) is the nonlinear interference factor for 100 spans. In each case, \( \eta \) is substituted by \( \eta_{ss} \) or \( \eta_{sn} \), as appropriate. Note that the purpose of \( \varepsilon \) is to change the coherence of the interference terms, altering the accumulation of the nonlinear interference with number of spans, and that \( 0 \leq \varepsilon \leq 1 \).

The effect of NLC on the effective received SNR is modeled by assuming that NLC effectively subtracts in power the nonlinear interference generated by the forward propagating field. This simplification is customary in the literature and can be seen as the result of two assumptions: i) a perturbative first-order approximation, and ii) uncorrelation of all the optical fields involved in the SNR calculation. Note that this implicitly assumes that NLC is applied to the full received optical field. As shown in [17], DBP generates a first-order field, identical, but with opposite sign, to the forward-propagated field, provided that the linearly-propagated field (zeroth-order solution) along the fiber link is the same, hence the cancellation. However, due to the noise accumulation over the link, there is a mismatch between the linearly forward-propagated field and the backward-propagated field (or the precompensated field). As a result, residual signal-ASE interaction terms are still present after the application of either DBP or DPC, representing one of the main performance limitations [18].

Further assuming a weak nonlinear interaction between ASE noise contributions along the link, the calculation of the signal-ASE interaction terms can be performed by considering each ASE noise contribution as separately interacting with the signal in each span.

\[ \text{Indeed, the perturbative approximation does not allow the additivity of nonlinear terms arising from two or more optical fields adding together, even to the first order.} \]
The nonlinear interference scaling coefficient, \( \xi \), accounts for the noise generated due to this signal-ASE interaction. In the case of linear CDC, each contribution of ASE noise interacts with the signal from the span following its addition, up until the end of the link. In the configuration analysed herein (Fig. 1), the first ASE noise contribution interacts with the signal in the second span. Likewise, in the case of DPC, signal-ASE noise interference accumulates from the second span onwards, since the first noise source follows the first span. Thus, for the CDC and DPC scenarios,

\[
\xi_{\text{DPC}} = \xi_{\text{CDC}} = \sum_{k=1}^{N_S-1} k^{1+\varepsilon_{\text{sn}}}. \tag{5}
\]

For DBP, noise from the last amplifier will be backpropagated as if it were signal for \( N_S \) spans. The noise from the penultimate amplifier will have interacted with the signal for one span but will be backpropagated as if it were signal over all \( N_S \) spans. Thus the signal noise interaction over the final span will be correctly compensated, leading to \( N_S-1 \) spans of excess nonlinear interference. Thus the total signal-ASE noise interference is given by the following sum over all spans

\[
\xi_{\text{DBP}} = \sum_{k=1}^{N_S} k^{1+\varepsilon_{\text{sn}}}. \tag{6}
\]

If the NLC is split between \( N_{S1} \) spans of DPC and \( N_{S2} \) spans of DBP such that the total number of spans is \( N_S = N_{S1} + N_{S2} \), then \( \xi_{\text{SC}} \) is given by a combination of (5) and (6) as

\[
\xi_{\text{SC}} = \sum_{k=1}^{N_{S1}-1} k^{1+\varepsilon_{\text{sn}}} + \sum_{k=1}^{N_{S2}} k^{1+\varepsilon_{\text{sn}}}. \tag{7}
\]

The advantage of splitting the compensation arises since \( \xi_{\text{DBP}} \) and \( \xi_{\text{DPC}} \) increase superlinearly with the number of spans. \( \xi_{\text{SC}} \) is minimized for \( N_{S1} = \left\lfloor \frac{N_S}{2} \right\rfloor \) and \( N_{S2} = \left\lfloor \frac{N_S}{2} \right\rfloor \).

The SNR gain due to the split NLC can be quantified using an approximated closed-form expression for the summation, in each of (5) and (6). Using Faulhaber’s formula [19, Eq. 0.121], such a summation can be expressed as

\[
\sum_{k=1}^{N_S} k^{1+\varepsilon_{\text{sn}}} = \frac{N_S^{2+\varepsilon_{\text{sn}}}}{2 + \varepsilon_{\text{sn}}} + \frac{N_S^{1+\varepsilon_{\text{sn}}}}{2} + \frac{1}{2} \left( \frac{1}{1} \right) B_2 N_S^{\varepsilon_{\text{sn}}} + \frac{1}{4} \left( \frac{1}{3} \right) B_4 N_S^{2\varepsilon_{\text{sn}}-2} + \ldots \tag{8}
\]

where the coefficients \( B_n \) are known as the Bernoulli numbers. A sufficiently accurate closed-form for \( N_S > 1 \) can be derived by truncating (8) to the first 2 terms. These terms rapidly dominate the higher order terms as \( N_S \) increases, particularly considering that \( B_2 = 1/6 \) and \( B_4 = -1/30 \). The SNR gain, \( \Delta \text{SNR} \), for split compensation over DBP can be defined as the ratio between the SNRs achieved by each compensation technique at optimum launch power. All NLC techniques remove the cubic terms in (1). Thus, considering that maximizing the SNR leads to the optimum launch power given by

\[
P_{\text{opt}} = \frac{1}{2P_{\text{ASE}} \sqrt{N_S \eta_{\text{sn}} \xi}}. \tag{9}
\]

and that \( \text{SNR} \propto P \) at the optimum power since the overall ASE noise power is equal to the signal-ASE interaction power, the change in SNR is given by (2). Substituting the first two terms from the approximation (8) into (2), and choosing \( N_{S1} = \left\lfloor \frac{N_S}{2} \right\rfloor \) when calculating \( \xi_{\text{SC}} \), for an asymptotically large number of spans, we obtain (3).

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**REFERENCES**


